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APS BEAMLINE STANDARD COMPONENTS HANDBOOK

Version 1.3

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INTRODUCTION

It is expected that the members of the APS Collaborative Access Team (CAT) would like to concentrate their effort on designing specialized equipment related to their scientific programs rather than on routine or standard beamline components. Thus, an effort is made at the APS to identify standard and modular components of APS beamlines. Identifying standard components is a non-trivial task because these components should support diverse beamline objectives. To assist with this effort, the APS has obtained advice and help from a Beamline Standardization and Modularization Committee consisting of the following experts in beamline design, construction, and operation:

Richard Boyce	SSRL
Richard Hewitt	EXXON and CMCCAT
Tunch M. Kuzay (Chair)	APS
Richard Levesque	LLNL
Ed Melczer	LBL/APS
Dennis M. Mills	APS and SRI CAT
Tom Oversluizen	NSLS
Wilfried Schildkamp	University of Chicago and CARS CAT

A group of CAT representatives have also joined in this effort to lend their views on the subject.

Based on the charge given to this committee by Gopal Shenoy, Director of the Experimental Facilities of the Advanced Photon Source on January 22, 1990 (see Appendix A), the committee identified the following tasks:

- 1) to identify standard and modular components of an APS insertion device beamline,
- 2) to insure safety and quality in the beamline design concepts,
- 3) to develop conceptual and engineering designs for the components,
- 4) to review the designs,
- 5) to develop prototypes,
- 6) to disseminate the information to the user community and vendors.

(Tasks 2, 5 and 6 are carried out exclusively by the staff of the APS.)

In addition, the guidelines to this committee called for the following considerations:

- modular design of as many components as possible,
- vendor production design to reduce cost to users,
- safety of personnel and equipment,

- ALARA* design objective,
- Experiment Hall should be a Class IV restricted area (500 mR per year)
- engineered safety included in all the components to avoid inadvertent actions leading to hazards
- interlocks with adequate redundancies as well as visual and audible alarms to prevent human errors,
- spares for standard components will be available in the APS stockroom.

With these guidelines in mind, the staff of the Experimental Facilities Division identified various components thought to be standard items for beamlines, regardless of the specific scientific objective of a particular beamline. A generic beamline layout (see next page) formed the basis for this identification. This layout is based on a double-crystal (or multi-layer) monochromator as the first optical element, with the possibility of other elements to follow. Preliminary engineering designs were then made of the identified standard components. The Beamline Standardization and Modularization Committee has reviewed these designs and provided very useful input regarding the specifications of these components during many meetings.

This *Handbook* in its current version (1.3) contains descriptions, specifications, and preliminary engineering design drawings for many of the standard components. The design status and schedules have been provided wherever possible. In the near future, the APS plans to update engineering drawings of identified standard beamline components and complete the *Handbook*. The completed version of this *Handbook* will become available to both the CATs and potential vendors. Use of standard components should result in major cost reductions for CATs in the areas of beamline design and construction.

Because of the involved nature of the job at hand, we encourage CAT Directors to inform us of their specific needs as they progress in completing their beamline preliminary designs. The engineering drawings, in their current state of design, for the identified standard components are now available on the APS Design Exchange.

* ALARA ("as low as reasonable achievable") refers to DOE's policy of establishing a program for minimizing radiation exposure to personnel and equipment.

1. Vacuum specifications

1.1 APS beam transport - windowless

1.1.1 APS beam transport - mirrors

1.2 APS beam transport - Be window

1. Vacuum Specifications

The Storage Ring defines the vacuum conditions in the front end, which is the link to the beamlines. A pressure of 1×10^{-9} torr or better will be maintained in the Storage Ring during operation.

The pressure in the beamlines will strongly depend on the components that will be used to transport the beam to the experiment. The interface between beamline and front end is the front end valve (FEV) in the first optics enclosure (FOE). The pressure in the beamline immediately upstream of this valve must be $< 1 \times 10^{-8}$ torr in order to obtain permission to open the valve. The pressure at the safety shutters (SS2) in the front end must be $< 6 \times 10^{-9}$ torr. Figure 1 illustrates the situation. The trigger gauge downstream from the front end valve will have two set points. When the pressure exceeds 1×10^{-8} torr, the slow valve (SV) will close. If there is an accidental venting and if the pressure rises in less than 1 ms to more than 1×10^{-5} torr, the fast acting valve (FV) will be activated followed by the slow valve. Figure 1 also shows the setup for windowless operation with two differential pumps (DP), which allow a higher pressure limit for the beamline operation to be $< 1 \times 10^{-6}$ torr (instead of being $< 1 \times 10^{-8}$ torr in the absence of the differential pumps).

1.1 APS Beam Transport - Windowless

Beamlines under vacuum have to maintain a pressure $< 1 \times 10^{-6}$ torr. To have a windowless connection between the beamline and the front end, a differential pump will be needed. This achieves the needed pressure at the front end valve ($< 1 \times 10^{-8}$ torr) and an additional delay in shock wave propagation (in case of accidental venting) to protect the front end. For pumping, ion pumps are recommended. The vacuum of the beamline must be free of hydrocarbons. This will be verified (by the APS) upstream from the front end valve through residual gas analysis. The result of this analysis must be that the masses above 38 have a total pressure of less than 5×10^{-11} torr.

1.1.1 APS Beam Transport - Mirrors

All beam transports that are connected without windows to mirror chambers must be particularly free from hydrocarbons to avoid carbon contamination of the mirrors. It should be verified by the CAT that hydrocarbons contribute less than 1×10^{-3} to the total pressure of these beam transport components. This can be verified by the mass spectrum of a single component. The sum of the masses > 38 has to be less than 1×10^{-3} of the total pressure.

1.2 APS Beam Transport - Be Window

Beam transport that is separated from the front end by a Be window has to be evacuated to a pressure $< 1 \times 10^{-6}$ torr. To avoid carbon contamination of the window, oil free pumping of beamline components is required.

If the window terminates the vacuum part of the beamline, special measures must be taken to prevent contamination from the atmospheric side. Exposing the windows to air with the beam on will not be allowed. If the beamline design does not permit vacuum on one side of the window, we suggest one of the following measure be included: a short clean hydrocarbon-free He buffer (terminated by an Al foil) or a protective coating on the window. The mechanical and thermal design of the windows is discussed in section 4.

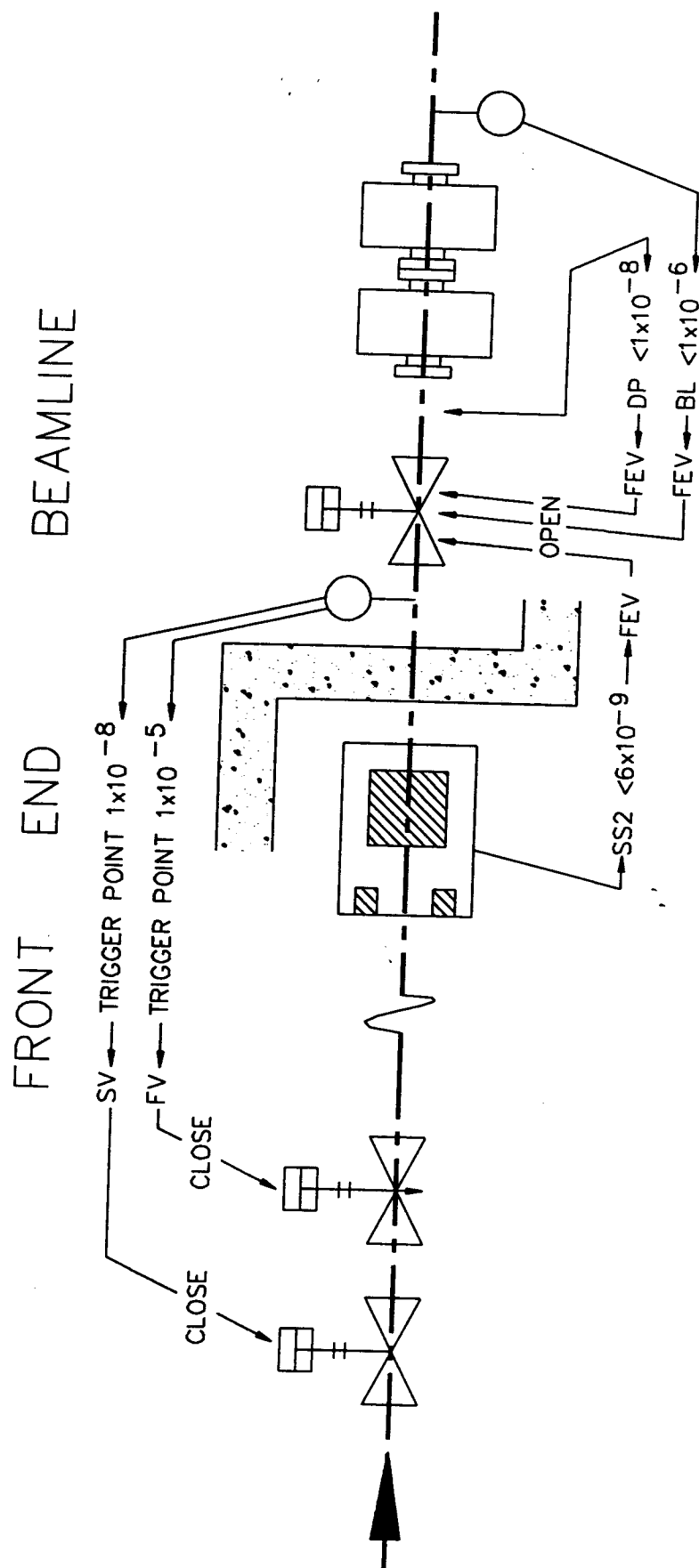


Figure 1

2.0. Beamline Shielding

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- 2.8. APS Shielded Monochromatic Transport and Pump Station (section to be added later)

Technical Analysis

APS has performed technical analysis of the shielding required under a variety of unusual operation conditions. These are summarized in sections 2.1 - 2.6

Design Stage and Schedule

The recommended shielding for various configurations of operation are now being evaluated from an engineering standpoint, and will be added to section 2.7 and 2.8. The results will lead to final shielding specifications for the hutches and the transports. This work is planned to be completed by May 1993.

2. Beamline Shielding

The shielding for the first optics enclosure (FOE), white beam, pink beam (reflected white beam), and monochromatic beam stations and transport lines shall be designed to keep the annual integrated dose equivalent at the shielding surface in occupied areas to less than 500 mrem. This design criteria is based on D.O.E. requirements (Radiation Control Manual, June 1992). For a 2000 hour operating year, this translates to a design criterion of 0.25 mrem/h. However, because it is highly unlikely that any user will be on the experimental floor at the shield surface for 2000 hours per year, and coupled with the fact that calculations were performed with conservative assumptions, annual dose equivalents received by individuals on the experimental floor should be well below 500 mrem.

2.01 Sources of Radiation for Beamline Shielding

Three sources of radiation should be considered for beamline shielding. They are:

- 1) gas bremsstrahlung
- 2) neutrons produced by gas bremsstrahlung
- 3) synchrotron radiation

Gas bremsstrahlung is produced by the interaction of the primary electron/positron beam with the residual gas in the Storage Ring vacuum chamber and is a major source of beam losses in storage rings. The interaction of the electron/positron with the gas molecules or ions takes place all around the Storage Ring, however, the photon intensity in the straight sections is very high. This is because in each interaction, the bremsstrahlung is produced in a narrow cone (characteristic emission angle = $1/g = 73 \mu\text{radians}$ for the APS) around the same direction and each contribution adds up resulting in a narrow monodirectional photon beam of high intensity. This narrow beam of bremsstrahlung travels down the synchrotron beamline and may be of major concern in the shielding design of the beamlines. The problem is aggravated with poor vacuum conditions in the Storage Ring.

The photons may be energetic enough to propagate an electromagnetic shower in any thick targets that they strike, or they can scatter off thin targets. In either case, this results in contributions to dose outside the transverse shielding of the beam transport, the optical enclosures/experimental stations, and the back walls of these stations. Because these photons are much more energetic than synchrotron radiation, they require far greater thicknesses of shielding material. For example, about 2 inches of lead will reduce the gas bremsstrahlung by a factor of 10, whereas it takes only about 3 mm of lead to reduce the 90° scattered synchrotron radiation (section 2.1) by the same factor. Monte-Carlo calculations are currently underway to determine the impact of gas bremsstrahlung on the shielding design of the beamlines. If it is determined that gas bremsstrahlung is a major concern in the shielding design of beamlines, additional local shielding around the target/scatterer will be specified.

In addition, if the target with which the gas bremsstrahlung interacts is sufficiently thick and the photons have energies above the photo-neutron production cross section, neutrons can also be produced. Analysis of neutron production is also being carried out. A foot of concrete will reduce the neutron and bremsstrahlung dose equivalent rate by a factor of 10 and 5, respectively.

Synchrotron radiation traveling down the beamline can scatter off any limiting aperture or any device that it strikes (e.g., monochromators, mirrors, masks, shutters, etc.) Thus the synchrotron beamline needs to be shielded against the scattered radiation.

The next section describes the shielding methodology. It must be pointed out that beam stops will be required in the forward direction inside the enclosures/experimental stations, however, they will not be addressed in this document. Other aspects of beamline shielding such as

collimators for bremsstrahlung, treatment of joints, doors, feedthroughs for cables and pipes are also not addressed.

2.02

The "Photon" program^{1,2} developed at the National Synchrotron Light Source was used to determine the shielding for the beamlines. This is a computer program that calculates dose in the following sequence:

- 1) calculation of photon flux as a function of energy and vertical opening angle of the synchrotron beam,
- 2) attenuation by filters,
- 3) a scattering process,
- 4) conversion from photon flux to dose.

Compton scattering is the primary mechanism for scattering at the large angles necessary to strike a shielding wall at or near normal incidence (where the effective elastically shielding thickness is a minimum). Low energy photons, which are more efficiently scattered through large angles, will not penetrate the shielding walls and therefore will not contribute to the dose outside the shielding.

In "Photon," the scatterer is assumed to be an isotropic point source and the total angularly integrated Compton cross section is used to calculate the scatter of the incident synchrotron spectrum from a target. In reality, there will be no point source of scatter in the beamlines, hence, "Photon" will overestimate the scattered intensities compared to that from an extended source.

"Photon" does not take into account the polarization dependence of the scattering. This will overestimate the scattered intensities in the horizontal plane while underestimating the scattered intensities in the vertical plane.

No consideration is given in the "Photon" program for electron-photon beam interactions, finite source size, or horizontal beam distribution. It must be pointed out that "Photon" uses the narrow beam attenuation coefficient for determining the dose outside the shielding. This can

¹D. Chapman, N. Gmur, N. Lazarz, and W. Thomlinson, "Photon: A Program for Synchrotron Radiation Dose Calculations," Nucl. Instr. and Meth. A266 191-194 (1988).

²E. Brauer and W. Thomlinson, "Experimental Verification of "Photon." A Computer Program for use in X-Ray Shielding," BNL 39541, Brookhaven National Laboratory, New York.

underestimate the dose because there will be build up from scattered photons. No build-up factor is used in the program. However, experimental data indicate that "Photon" overestimates the dose in the polarization plane.³

Sections 2.1 to 2.6 outline the shielding parameters and specifications for the beamlines. A maximum positron energy of 7 GeV, maximum current of 300 mA, and a maximum vertical divergence of 4/g were used for all calculations. Because the beamlines have to be shielded against scattered synchrotron radiation, "Photon" was run several times with different target materials (air, silicon, copper, and lead) and different target thicknesses to determine the material and thickness of the target that resulted in the highest scattered dose. Based on these runs, 30 cm of copper was chosen as the optimum target. Because enclosures/experimental stations will have optical elements such as mirrors, monochromators, safety shutters, and beam stops, all calculations for transverse shielding were based on using 30 cm of copper as the target (sections 2.1 - 2.3).

For beam transport pipes, a different approach is used. If ray traces indicate that the synchrotron beam could strike a high target (e.g., mask) or the beam pipe itself, during normal operating conditions or cases in of missteering, copper should be chosen as the optimum target (sections 2.4 - 2.6). If ray traces indicate that the synchrotron radiation could never strike a high-Z target in the transport pipe (this could be achieved with upstream collimation), 30 cm of air should be chosen as the optimum target. This would mean that no scattered radiation should be measured during normal operating conditions when the beam transport pipe is under good vacuum. However, if the vacuum in the pipe should be lost, then the synchrotron radiation could scatter off the air molecules. For the ID beamlines, calculations are done only for wigglers, which would result in more stringent specifications than for undulators. For wigglers, a critical energy of 32.6 keV, 32 poles, and a horizontal divergence of 2 mrad was used. For bending magnets, a critical energy of 19.5 keV and a horizontal divergence of 6 mrad was used. In addition, a safety factor of 2 for dose was incorporated into all the calculations.

The shielding specifications are based on model calculations and do not represent the final specifications for construction. After assessing the engineering needs, the APS will provide the final specifications.

The shielding specification in sections 2.1 to 2.6 can be used as long as the parameters used lie within the envelope of the specified parameters. The dose equivalent rates scale linearly with current, number of poles, and horizontal divergence. The dose equivalent rates follow an inverse square law with distance.

³ E. Brauer, "Health Physics Measurements Around the New F2 Wiggler Station at CHESS (Cornell University) ESRF Report.

The specifications of steel thicknesses for shielding are based on recommendations (for structural support) by a commercial supplier. The shielding effect of steel has also been taken into account.

2.03 First Optics Enclosure/White Beam Hutches

The shielding parameters are specified in section 2.1. The copper scatterer is assumed to be at a distance of 29.45 m from the source. The calculations do not depend on this distance as long as all the radiation is taken into account by integrating over the full vertical extent of the beam. The energy range of the incident spectrum is 1-800 keV. The first and second tables specify the shielding requirements for the ID and bending magnet, respectively. The first column in each table specifies the wall under consideration. The second column shows the distance between the scatterer and the wall. The third, fourth, and fifth columns show the thickness of steel, lead, and steel required for each wall. The sixth column shows the dose equivalent rate (DER) at the shield surface for which the hutch wall has been shielded. The last column shows the effective tenth value layer (TVL) for lead, i.e., the thickness required to reduce the DER by a factor of 10. The lateral wall has been shielded for 0.25 mrem/h because a high occupancy can be expected outside this wall.

The roof has been shielded for 2.5 mrem/h since it is not expected to be occupied. Conservative calculations for skyshine (i.e., x-rays reflected back from the atmosphere to the experimental floor) indicate that the dose equivalent rates will be at least two orders of magnitude lower. So, the contribution from skyshine to the experimental floor will be less than 0.025 mrem/h.

The back walls of the hutch are thicker than the lateral walls by a tenth-value layer, because "Photon" underestimates the scattered intensities in the vertical plane and to account for the forward scattered photons, which are more energetic than the laterally scattered ones. Inherent in this approach is the assumption that beam stops will be designed to stop both the forward directed gas bremsstrahlung and forward directed synchrotron radiation. Provisions should be made for additional shielding of the back walls, if beam stops do not intercept all the forward scattered radiation.

2.04 Pink Beam Hutches

It is difficult to generalize shielding for pink beam hutches, because the type of mirror used and the grazing angle of incidence can vary. Hence, the shielding specifications for pink beam hutches (section 2.2) has been given only as an example and is not to be used as a general case. In this example, a platinum mirror with a grazing angle of incidence of 0.15° and a cut-off energy of 32 keV, (reflectivity = 0.4) was used. However, for shielding calculations reflectivities of 1.0, 0.0164, and 0.0017 were used for photon energies in the range 1-50 keV, 50-80 keV, and 80 -100 keV, respectively. Hence, the results are conservative.

2.05 Monochromatic Beam Hutches

The determination of shielding for monochromatic beam hutches is not straight forward because any energy and bandwidth can be chosen. In addition, one must shield for harmonics as well. The shielding specifications in section 2.3 assume a monochromatic beam with a 0.1% bandwidth in the energy range of 1-300 keV. The photons in the energy range of 200 - 300 keV contribute the highest dose, hence a photon energy in this range was chosen with a 0.1% bandwidth, and the shielding was determined. A half-value layer (HVL) of lead, that is, the thickness required to reduce the dose by a factor of 2, was added to the thickness determined earlier to account for the harmonics. These new values are reported in column 4.

2.06 White Beam Transport

As mentioned in section 2.06, the calculations were done for two scatterers, 30 cm of copper and 30 cm of air. The beam pipe diameter is four inches (section 2-4). If ray traces indicate that the beam may strike a high-Z target in the beam pipe, the shielding in the second row of the tables should be used, because this will limit the dose equivalent rate to 0.25 mrem/h. If ray traces indicate that only during missteering could the synchrotron beam could strike a high-Z target in the beam pipe, then the shielding in the third row should be used. A dose equivalent rate of 2.5 mrem/h at the shield surface can be tolerated because it will last only during missteering and not persist for 2000 hours.

If ray traces indicate that the synchrotron beam will not strike any high-Z material in the beam pipe, then technically no shielding is required for the beam pipe. However, it is possible to lose the vacuum in the beam pipe, and, if this happens, the synchrotron radiation could scatter off air molecules. In this case, the shielding in row 5 should be used.

2.07 Pink Beam Transport

A similar calculation was carried out for pink beam transport (section 2.5) was done for white beam transport. The pink beam transport shielding specifications are given only as an example and should not be used as a general case.

2.08 Monochromatic Beam Transport

A similar calculation was carried out for monochromatic beam transport (section 2.6) as for white beam transport.

2.1. Typical First Optical Enclosure (FOE) - White Beam Hutch

Shielding Parameters

The following parameters were used to determine the shielding for the walls and the roof of the FOE and the white beam stations at the ID beamlines.

Positron energy	7.0 GeV	
Positron current	300 mA	
Photon energy range	1 - 800 keV	
Vertical divergence	$\Psi = \pm 4/\gamma$	
Scatterer	300 mm Cu at a distance of 29.45 m from the source	
	<i>Insertion Device (ID)</i>	<i>Bending Magnet (BM)</i>
Critical energy	32.6 keV	19.5 keV
Number of poles	32	1
Horizontal divergence	2 mrad	6 mrad

Specifications

Insertion Device (ID)

Wall	Distance ¹ (m)	Shielding Material			DER ² (mrem/h)	TVL ³ (mm)
		steel (mm)	+lead (mm)	+steel (mm)		
Lateral	1.0	6.35	12.8	6.35	0.25	3.1
Roof	1.5	3.2	9.9	3.2	2.5	2.7
Back	1.0	6.35	15.9	6.35		

Bending Magnet (BM)

Wall	Distance (m)	Shielding Material			DER (mrem/h)	TVL (mm)
		steel (mm)	+lead (mm)	+steel (mm)		
Lateral	1.0	3.2	5.3	3.2	0.25	1.3
Roof	1.5	3.2	3.7	3.2	2.5	1.1
Back	1.0	3.2	6.6	3.2		

¹ Distance from scatterer to wall

² DER = Dose Equivalent Rate at the shielding surface

³ TVL = Tenth Value Layer (thickness of Pb required to reduce the dose equivalent rate by a factor of ten)

2.2. Typical Pink Beam Hutch

Shielding Parameters

The following parameters were used to determine the shielding for the walls and the roof of the pink beam stations at beamlines with reflected beams.

Positron energy	7.0 GeV
Positron current	300 mA
Photon energy range	1 - 50 keV (R=1), 50 - 80 keV (R=0.0164), 80 -100 keV (R=0.0017) R = reflectivity of the mirror
Vertical divergence	$\Psi = \pm 4/\gamma$
Scatterer	300 mm Cu
Insertion Device (ID)	
Critical energy	32.6 keV
Number of poles	32
Horizontal divergence	2 mrad

Specification

Insertion Device (ID)

Wall	Distance ¹ (m)	Shielding Material			DER ² (mrem/h)	TVL ³ (mm)
		steel (mm)	+lead (mm)	+steel (mm)		
Lateral	1.0	3.2	4.1	3.2	0.25	1.0
Roof	1.5	3.2	2.9	3.2	2.5	0.9
Back	1.0	3.2	5.1	3.2		

¹ Distance from scatterer to wall

² DER = Dose Equivalent Rate at the shielding surface

³ TVL = Tenth Value Layer (thickness of Pb required to reduce the dose equivalent rate by a factor of ten)

2.3. Typical Monochromatic Beam Hutch

Shielding Parameters

The following parameters were used to determine the shielding for the walls and the roof of the monochromatic beam stations at beamlines with monochromatic beams.

Positron energy	7.0 GeV	
Positron current	300 mA	
Photon energy range	1 - 300 keV (0.1%bandwidth)	
Vertical divergence	$\Psi = \pm 4/\gamma$	
Scatterer	300 mm Cu	
	<i>Insertion Device (ID)</i>	<i>Bending Magnet (BM)</i>
Critical energy	32.6 keV	19.5 keV
Number of poles	32	1
Horizontal divergence	2 mrad	6 mrad

Specifications

Insertion Device (ID)

	Distance ¹	Shielding Material			DER ²	TVL ³
Wall	(m)	steel (mm)	+lead (mm)	+steel (mm)	(mrem/h)	(mm)
Front + Lateral	1.0	3.2	8.9	3.2	0.25	2.7
Roof	1.5	3.2	4.9	3.2	2.5	2.9
Back	1.0	3.2	11.6	3.2		

Bending Magnet (BM)

	Distance	Shielding Material			DER	TVL
Wall	(m)	steel (mm)	+lead (mm)	+steel (mm)	(mrem/h)	(mm)
Front + Lateral	1.0	3.2	3.5	3.2	0.25	1.1
Roof	1.5	3.2	2.0	3.2	2.5	1.0
Back	1.0	3.2	4.6	3.2		

¹ Distance from scatterer to wall

² DER = Dose Equivalent Rate at the shielding surface

³ TVL = Tenth Value Layer (thickness of Pb required to reduce the dose equivalent rate by a factor of ten)

2.4. Typical White Beam Transport

Shielding Parameters

The following parameters were used to determine the shielding for the white beam transport lines.

Positron energy	7.0 GeV	
Positron current	300 mA	
Photon energy range	1 - 800 keV	
Vertical divergence	$\Psi = \pm 4/\gamma$	
Ø of the beam pipe	4"	
	<i>Insertion Device (ID)</i>	<i>Bending Magnet (BM)</i>
Critical energy	32.6 keV	19.5 keV
Number of poles	32	1
Horizontal divergence	2 mrad	6 mrad

Specifications

Insertion Device (ID)

Scatterer	Shielding Material			DER (mrem/h)
	steel (mm)	+lead (mm)	+steel (mm)	
300 mm Cu	6.35	21.2	6.35	0.25
300 mm Cu	6.35	18.0	6.35	2.5
300 mm air	6.35	13.2	6.35	0.25
300 mm air	6.35	10.6	6.35	2.5

Bending Magnet (BM)

Scatterer	Shielding Material			DER (mrem/h)
	steel (mm)	+lead (mm)	+steel (mm)	
300 mm Cu	3.2	9.3	3.2	0.25
300 mm Cu	3.2	7.6	3.2	2.5
300 mm air	3.2	6.0	3.2	0.25
300 mm air	3.2	4.9	3.2	2.5

2.5. Typical Pink Beam Transport

Shielding Parameters

The following parameters were used to determine the shielding for the walls of the pink beam transport lines (beamlines with reflected beams).

Positron energy	7.0 GeV
Positron current	300 mA
Photon energy range	1 - 50 keV (R=1), 50 - 80 keV (R=0.0164), 80 -100 keV (R=0.0017) R = reflectivity of the mirror
Vertical divergence	$\Psi = \pm 4/\gamma$
Ø of the beam pipe	4"

Insertion Device (ID)

Critical energy	32.6 keV
Number of poles	32
Horizontal divergence	2 mrad

Specifications

Insertion Device (ID)

Scatterer	Shielding Material			DER (mrem/h)
	steel (mm)	+lead (mm)	+steel (mm)	
300 mm Cu	3.2	6.7	3.2	0.25
300 mm Cu	3.2	5.6	3.2	2.5
300 mm air	3.2	5.0	3.2	0.25
300 mm air	3.2	4.0	3.2	2.5

2.6. Typical Monochromatic Beam Transport

Shielding Parameters

The following parameters were used to determine the shielding for the walls of the monochromatic beam transport lines.

Positron energy	7.0 GeV	
Positron current	300 mA	
Photon energy range	1 - 300 keV (0.1% bandwidth)	
Vertical divergence	$\Psi = \pm 4/\gamma$	
Ø of the beam pipe	4"	
	<i>Insertion Device (ID)</i>	<i>Bending Magnet (BM)</i>
Critical energy	32.6 keV	19.5 keV
Number of poles	32	1
Horizontal divergence	2 mrad	6 mrad

Specifications

Insertion Device (ID)

Scatterer	Shielding Material			DER (mrem/h)
	steel (mm)	+lead (mm)	+steel (mm)	
300 mm Cu	6.35	15.5	6.35	0.25
300 mm Cu	6.35	12.8	6.35	2.5
300 mm air	3.2	9.1	3.2	0.25
300 mm air	3.2	6.2	3.2	2.5

Bending Magnet (BM)

Scatterer	Shielding Material			DER (mrem/h)
	steel (mm)	+lead (mm)	+steel (mm)	
300 mm Cu	3.2	6.3	3.2	0.25
300 mm Cu	3.2	5.2	3.2	2.5
300 mm air	3.2	4.4	3.2	0.25
300 mm air	3.2	3.3	3.2	2.5

3. Filters

- 3.1. Filter assembly
- 3.2. Filter material

Technical Analysis

The details of a filter (material and dimensions) are closely linked to the nature of the experiment being planned by the CATs. We suggest that the CATs design the filter material to meet their needs. It should be recognized that filter failure during operation can lead to damage of equipment in the beamline.

In section 3.1 we present a generic design for the filter assembly that the CATs could use in this preliminary design of the beamline. Section 3.2 provides filter properties essential for the selection of the material.

Design Schedule

The APS is pursuing detailed analysis of filter material including both thermal and mechanical considerations. This will be available in May 1993.

3. Filters

Filters in beamlines are primarily used to reduce the bandpass of the beam and thus the power load on the elements that interact with the beam (windows, monochromator crystals, etc.). For x-ray beamlines, a combination of high pass (filter foils) and low pass filters, such as a beam-deflecting mirror is very effective. These combinations are also able to suppress higher order reflections in the monochromatic beam.

3.1. Filter Assembly

General description

The filter assembly is designed to provide a modular beamline filtering system. The assembly consists of a housing with a selection of linear filter mounts. The assembly or the linear filter mounts can be placed in every vacuum segment of the user's beamline. For ease of replacement, the filter foils are mounted on standardized filter frames. The filter frames can carry up to 5 different filter foils. The filters are linearly moved into the beam by a light load actuator. The positions of the filters must be interlocked with the beam. This protects the filter frames from being hit by the beam. The filter frames are directly cooled. In the case of radiation cooling, the surrounding vacuum chamber is protected by water cooled-radiation shielding or is directly cooled by attached water cooling.

Specifications

Filter assembly tank

Two ultra high vacuum (UHV) compatible vacuum tanks with two 8" O.D. flanges for filter inserts from the top are under design. The length of one tank is 325 mm. The I.D. of the entrance and exit flange is 4". Ports for pumping (170 l/sec) and viewing the filter foils are supplied. Figure 2 shows the two tanks for a maximum of four assemblies.

Filter assembly

Two types of filter assemblies are in the design phase: a single insert type and a double insert type based on the APS light load actuator with a stepping motor drive. In five different places, up to two filter foils can be mounted on a water-cooled frame. The frame can be moved linearly to different filter slots. The sizes of the filters are 15 x 80 mm. The drive is supplied with interlock switches to prevent accidental irradiation of the frame. The filters can be positioned to within 0.1 mm. Figure 3 shows the water-cooled frame with a linear drive and with radiation shielding.

3.2. Filter Material

The choice of filter material is primarily determined by the transmission energy range, which is defined by the photo absorption coefficient of the material and the thickness of the filter. Figures 4 to 9 show transmission curves for different materials that can be used as x-ray high-pass filters. The filter materials for high power insertion device beamlines have to be carefully analyzed and chosen for the ability to be cooled. Both cooling schemes (conduction cooling and radiation cooling) have to be taken into account because filters often operate at high temperatures. At the APS, failure criteria and an analysis method for filter and window assemblies are under development.

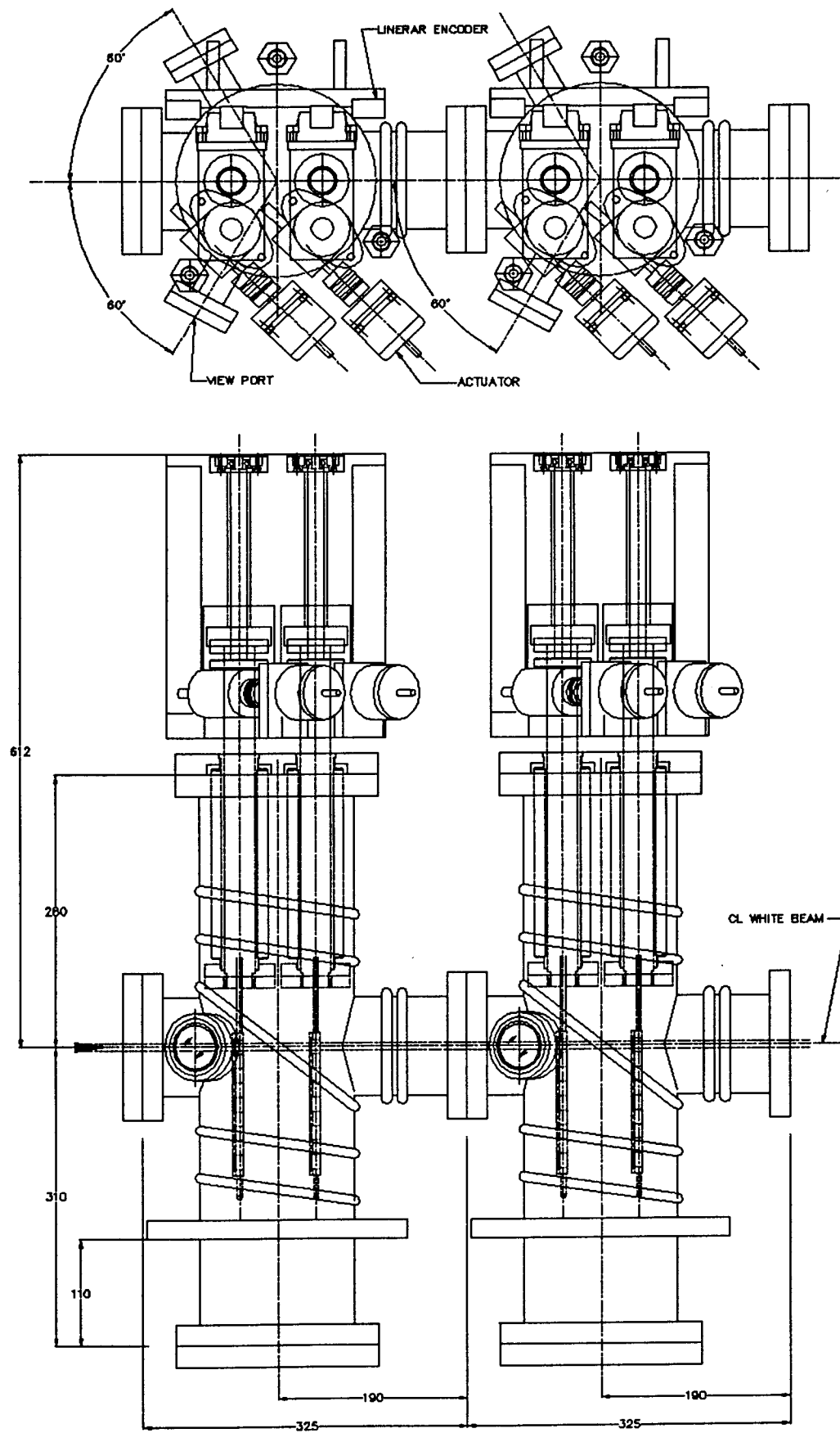


Figure 2

APS BEAM LINE FILTER ASSY
2/20/93

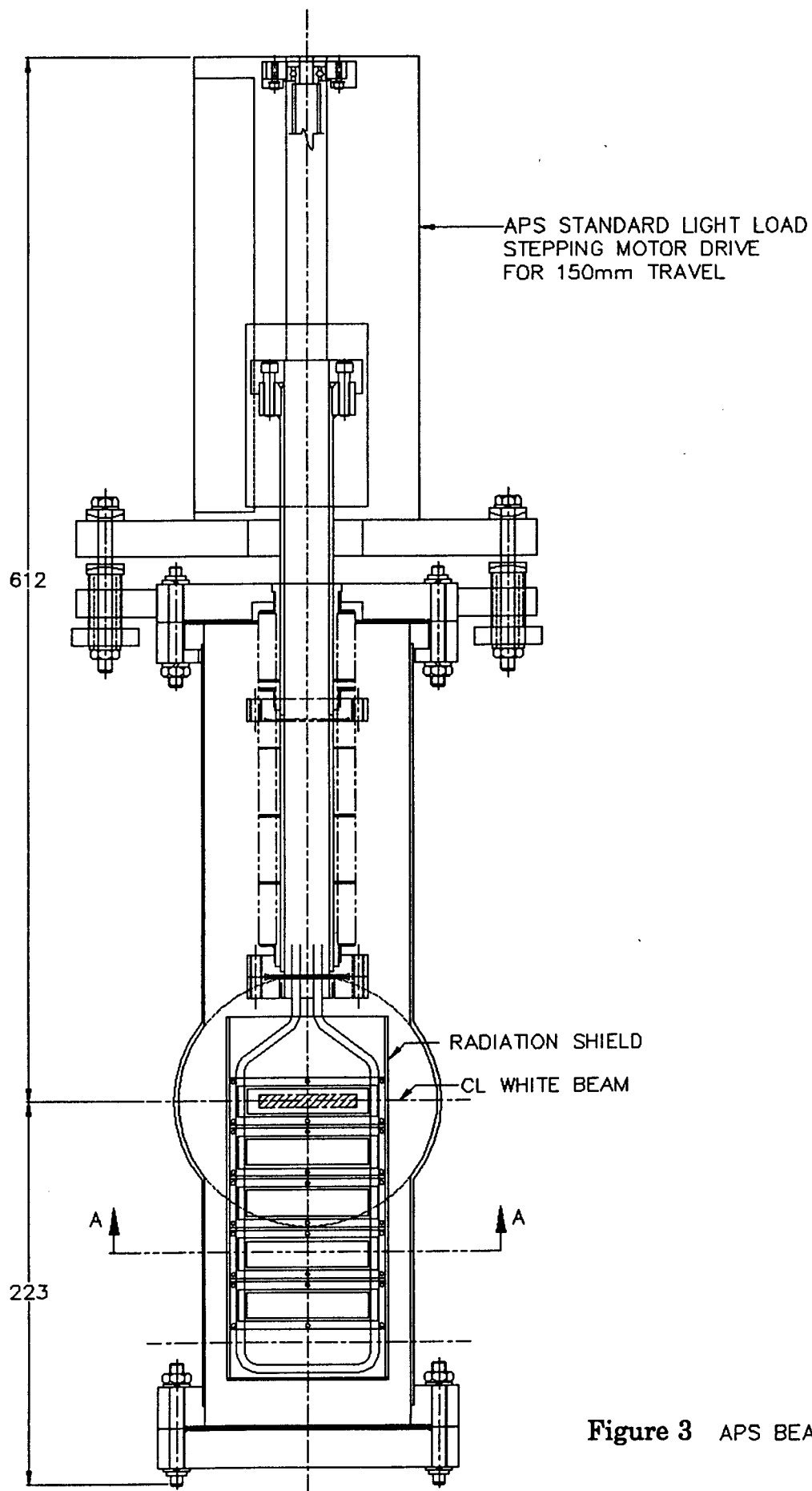


Figure 3 APS BEAM LINE FILTER

Fraction of Transmitted Photons vs.

Thickness of Be Filter ($\rho=1.85\text{g/cm}^3$)

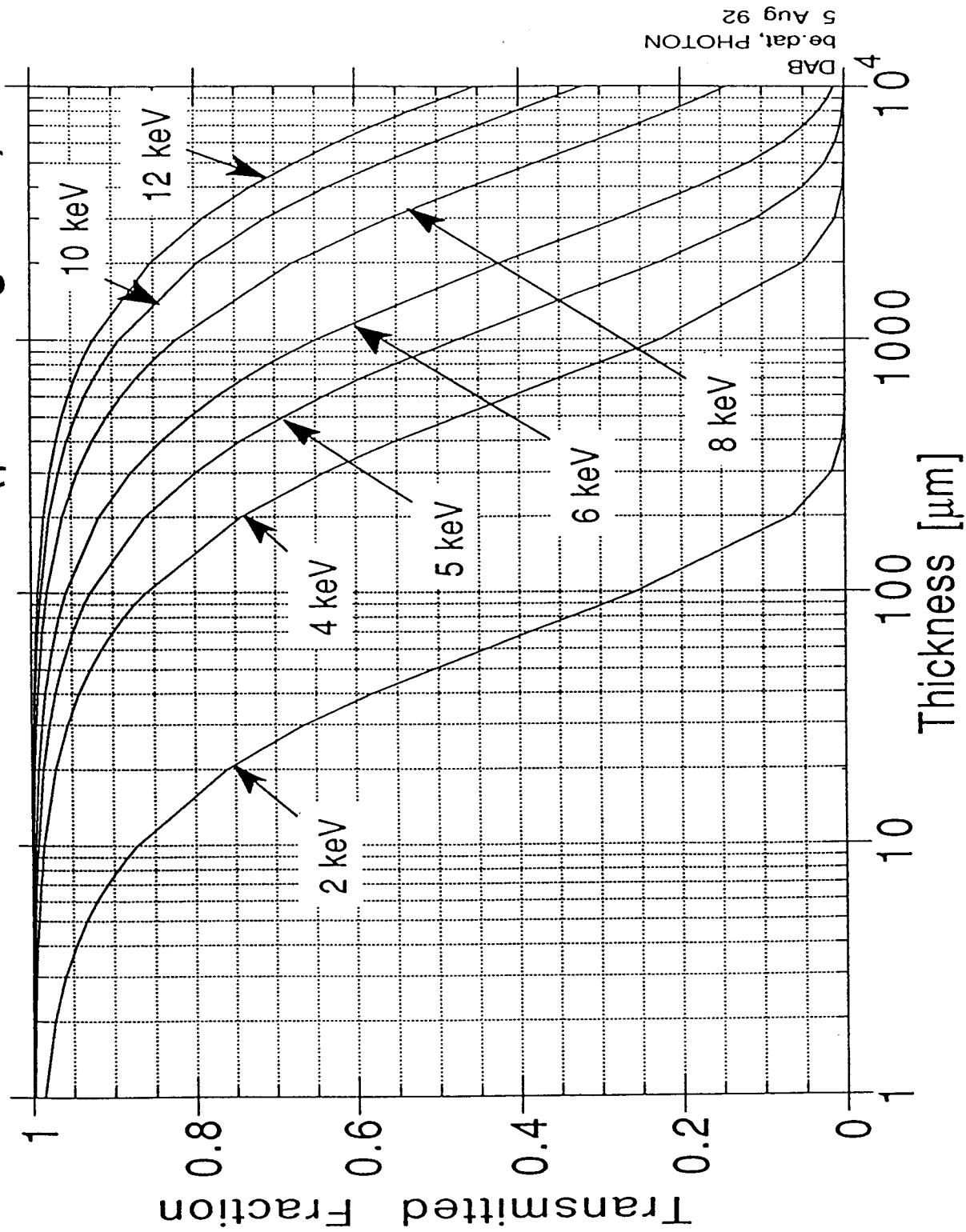


Figure 4

Fraction of Transmitted Photons vs.

Thickness of Diamond Filter ($\rho=3.51\text{g/cm}^3$)

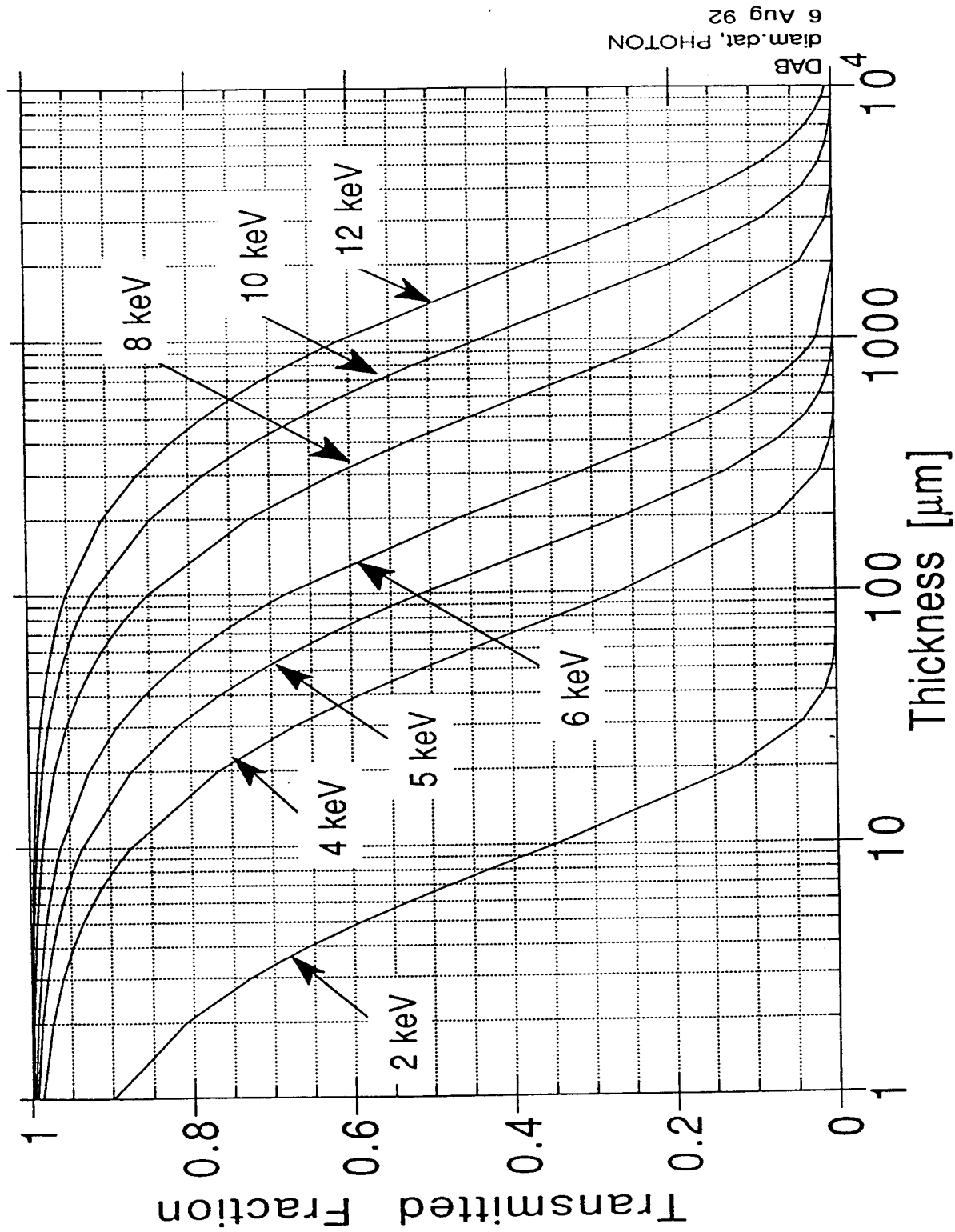


Figure 5

Fraction of Transmitted Photons vs.

Thickness of Al Filter ($\rho=2.6989\text{g/cm}^3$)

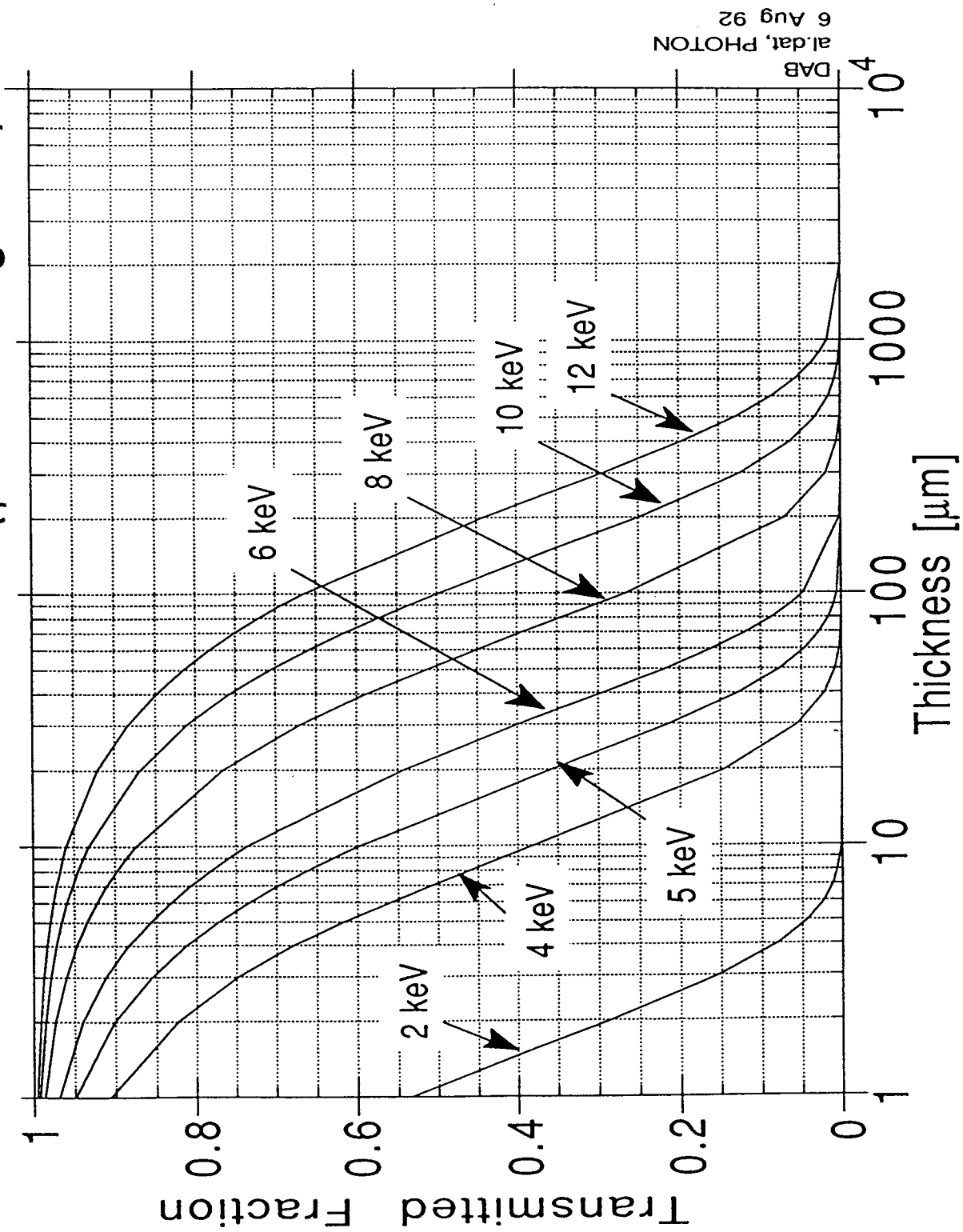


Figure 6

Fraction of Transmitted Photons vs.

Thickness of Si Filter ($\rho=2.33\text{g/cm}^3$)

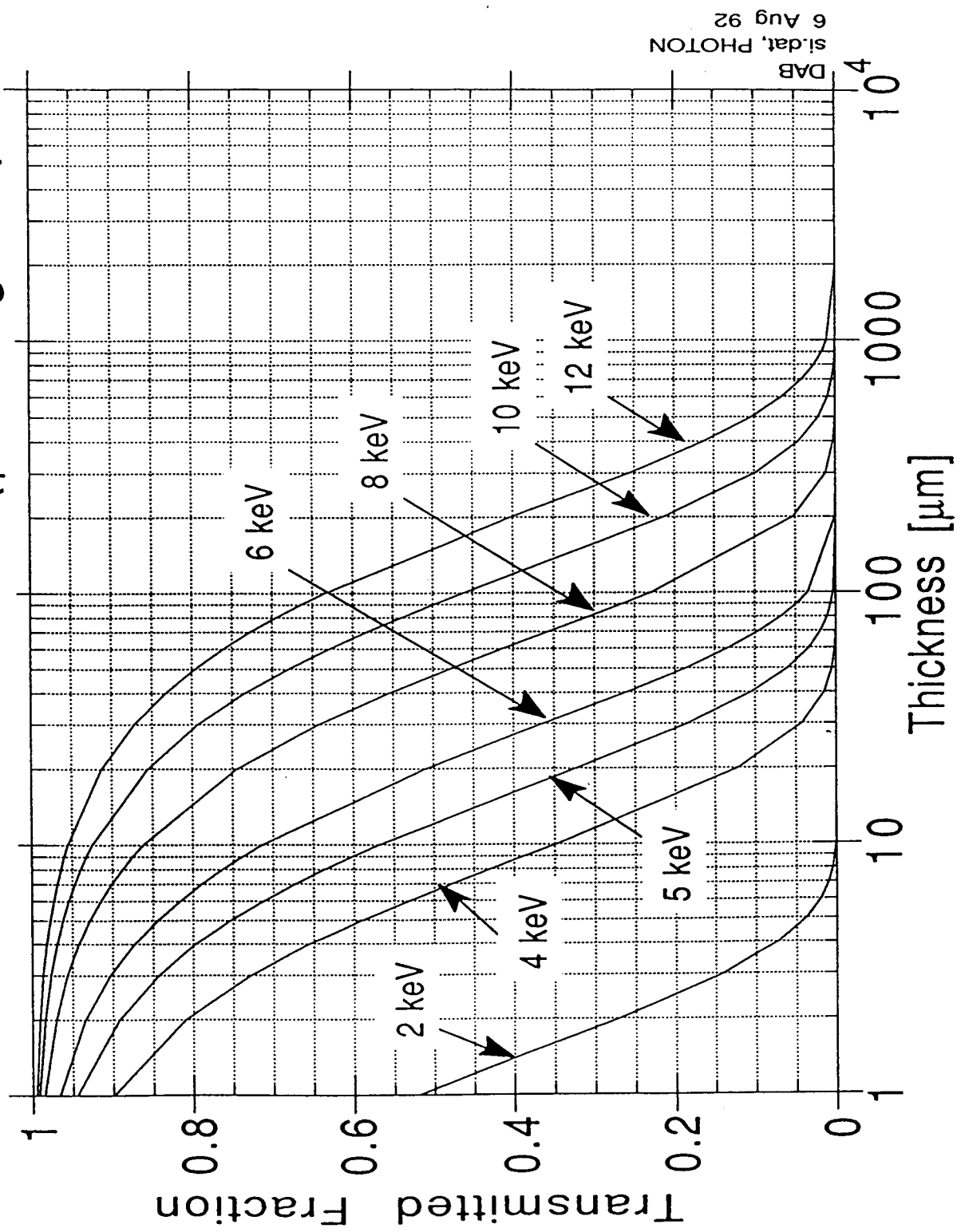


Figure 7

Fraction of Transmitted Photons vs.

Thickness of SiC Filter ($\rho=3.22\text{g/cm}^3$)

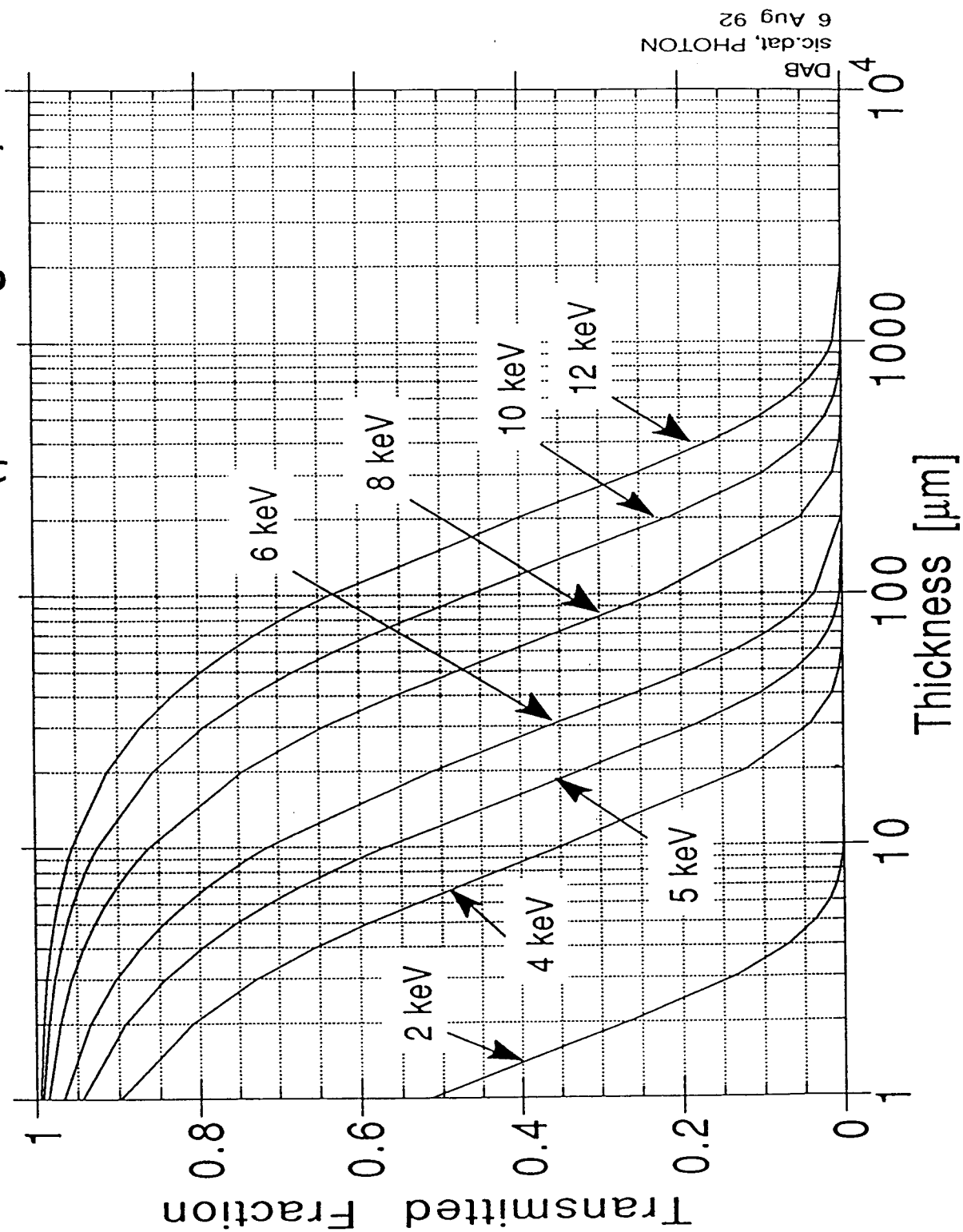


Figure 8

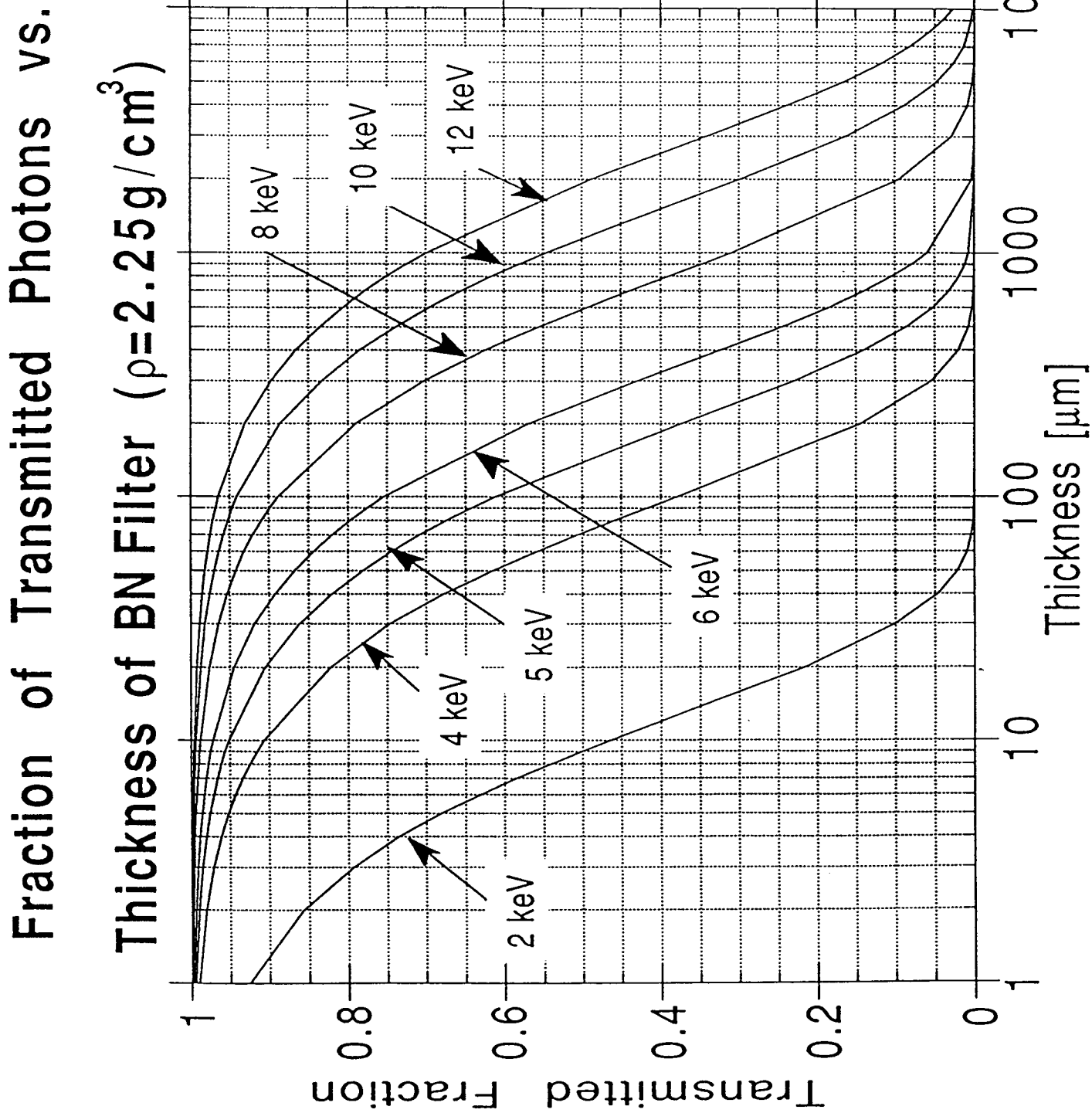


Figure 9

4. Windows

- 4.1. Be - windows
- 4.2. C - windows
- 4.3. Differential pump

Technical Analysis

At APS, failure criteria and an analysis method for filter and window assemblies and their cooling schemes are under development. Reports on the analysis will be made available to all CATs by May 1993.

4. Windows

Windows are used to separate beamline sections with different vacuum or pressure conditions (UHV - HV - atmospheric pressure). For the transmission of the windows, the same design criteria are used as for the filters. The vacuum tightness of the windows ($<1 \times 10^{-10}$ torr/l/sec) together with the pressure difference at a transition from vacuum to atmosphere are additional complications of the window design. The main difficulty is introduced by the high heat load of the ID beams, which can introduce power loads in the kW range. In these cases, windows have to be protected by filters, which have to take a large amount of the power load. Such filter - window combinations severely limit the availability of radiation below 5 - 6 keV. For many CATs, we strongly recommend the use of windowless configurations on ID beamlines to retain the flexibility of using the entire energy spectrum.

It should also be pointed out that if the CAT's interest is primarily in the hard x-ray range (>10 keV), the use of Al windows may be appropriate and should alleviate many design problems of filters and windows.

At APS, failure criteria and an analysis method for filter and window assemblies and their cooling schemes are under development.

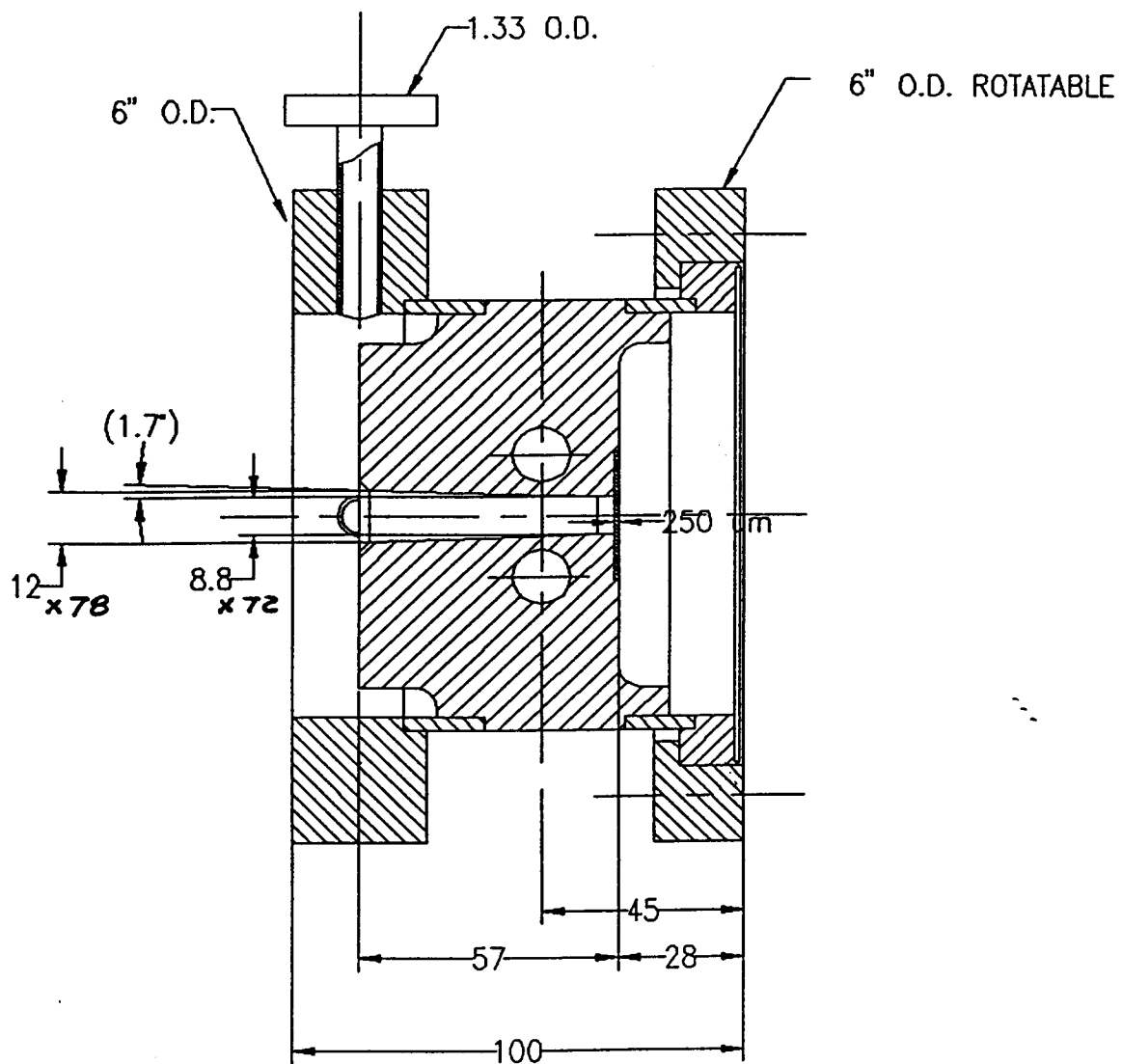
4.1. Be - windows

For windows low-Z materials are preferred. Beryllium is a very common window material. In conventional synchrotron applications better than 99.8% pure special grade Be of 250 μm (10 mil) thickness foil is utilized as the window material and is metallurgically bonded to a water-cooled copper Conflat flange. Several reputable US and European manufacturers of Be windows now exist from which one can purchase ready-made window assemblies with 125 to 250 μm thickness that are warranted to be vacuum tight. Windows are assumed to fail under several scenarios. These include severe vacuum incursions, an atmospheric shock wave being the worst possible case; oxidization of Be itself from the vacuum gas impurities; and, deterioration of the window bond itself. The most recognized and studied case of window failures in open literature (Asaoka et al., Rev. Sci. Instrum. Vol. 63, No. 1, pp 473-476, Jan 1992) is however the thermally induced failures under x-ray heating of the Be foil. Structural failure of the thin Be foil under heating and the resulting thermal stresses have been poorly understood and postulated. The conventional criterion that when the thermally induced shear stress becomes half of the foil's yield has underpredicted window failures. Depending on the usage and power source etcetera, the window failures may occur as sudden cracking under heat, gradual evaporative erosion, and elastic/plastic buckling. The latter scenario has been experimentally observed and we can verify it analytically.

Our current analyses and understanding of the thermal behaviour of the cooled, whitebeam APS front end Be window lead us to believe that the window should be protected by at least a 300 μm thick carbon (graphite) filter, should not be allowed to absorb more than 60 W total power, and the window temperature should not exceed 250°C.

Here we present a set of window designs for various uses.

1. A window suitable for white radiation from an APS wiggler (with $K=14$, 7 GeV and 100 mA). This can also be used for monochromatic radiation from APS IDs.
2. A double window to deliver both white and/or monochromatic radiation from either an APS ID or bending magnet source.
3. A window suitable for transmitting bending magnet white radiation with a horizontal width of approximately 110 mm.



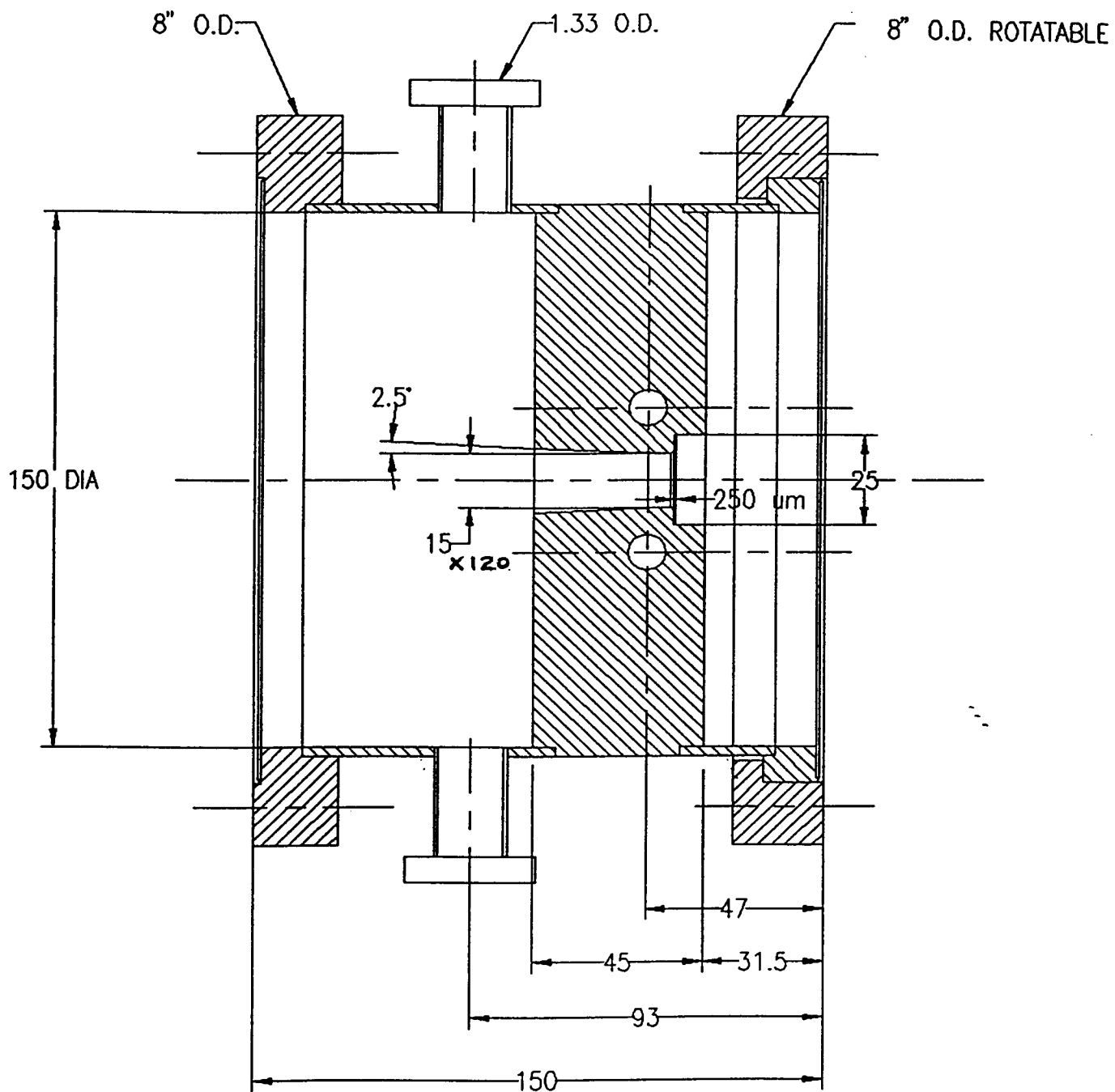
WIG. WHITE & WIG/UND MONO. WINDOW

Figure 10

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Figure 11



BM WHITE BEAM WINDOW

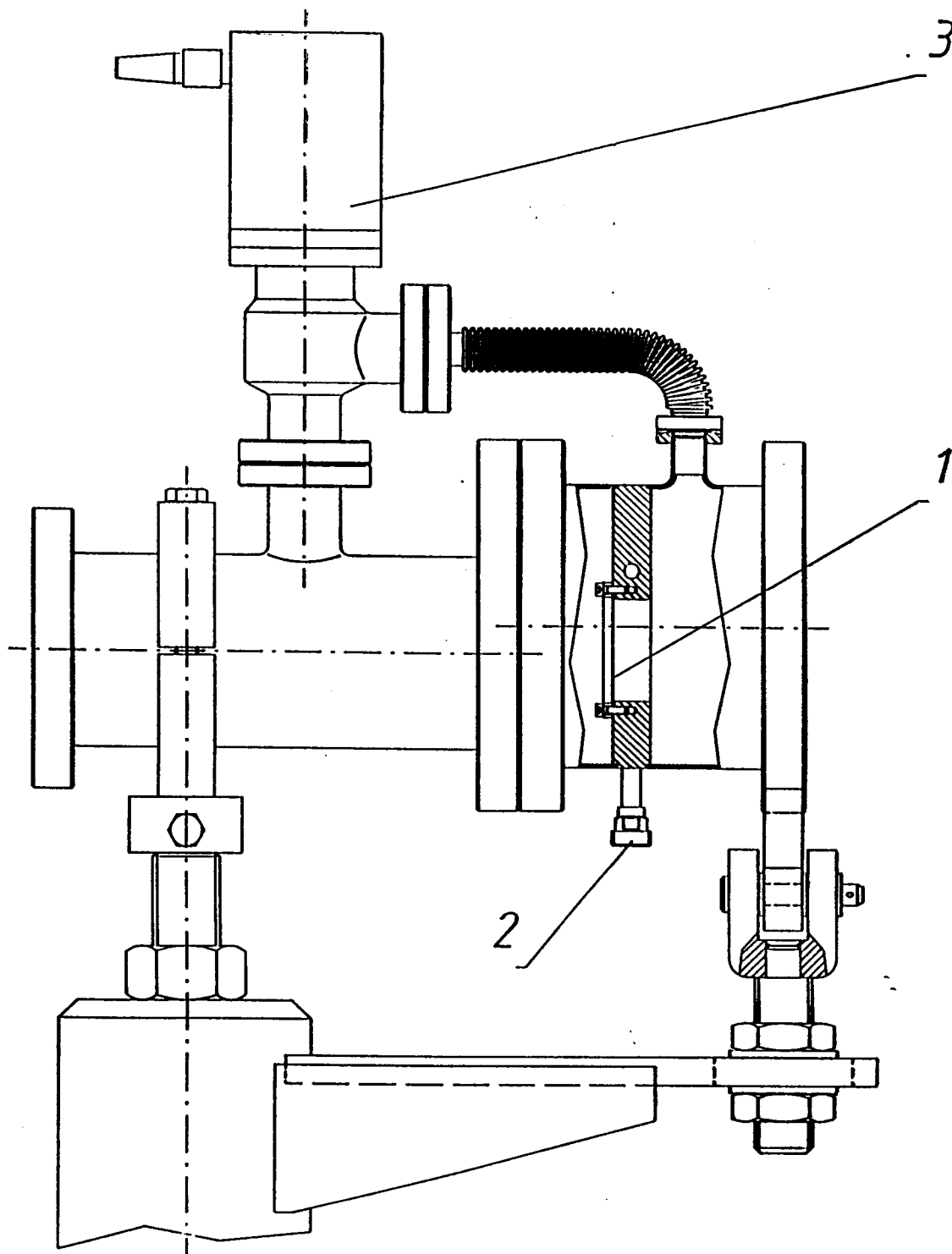
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Figure 12

4.2. C - windows

4.2.1. Carbon foil windows

Carbon foil windows consists mostly of a thin pyrolytic graphite foil that is mounted on a water-cooled copper block. These windows cannot handle pressure differences in the range of one atmosphere. Also, accidental venting will destroy these windows. They are mainly used as contamination barriers to separate UHV beamline sections from sections with relative bad vacuum conditions ($\sim 10^{-5}$ torr). A detailed analysis of the vacuum separation properties of thin carbon foils was carried out by Lagomarsino et al. [Nucl. Inst. Meth. A307 (1991) 309-311]. Figure 13 shows the design of such window for a high power wiggler beamline at HASYLAB; (1) is the carbon foil (50 mm x 80 mm and 130 μm thick). The foil is clamped on a water-cooled copper block(2). The bypass valve (3) is used for pump down and venting.



Carbon foil window

Contamination barrier window for high power x-ray beamlines

- 1 Carbon foil (50 x 80 mm, 130 μ m thick)**
- 2 Water-cooled Cu - Block**
- 3 Vacuum bypass with valve**

Figure 13

4. 3. Differential Pump

Differential pumps make use of the good vertical collimation of the synchrotron radiation beam. It is possible to get several orders of magnitude pressure difference in the high vacuum range.

Figure 14 shows the standard APS design for windowless operation. With a minimal aperture of 10 x 78 mm, two 170 l/s ion pumps, and a total length of ~ 1 m, a pressure difference of two orders of magnitude is achieved. With its narrow aperture this device gives good performance in delay of shock waves in case of accidental venting.

A prototype differential pump similar to the one shown in figure 14 has been built and successfully tested by the APS. A pressure differential of more than two orders of magnitude has been reached with the aperture of 10 x 78 mm.

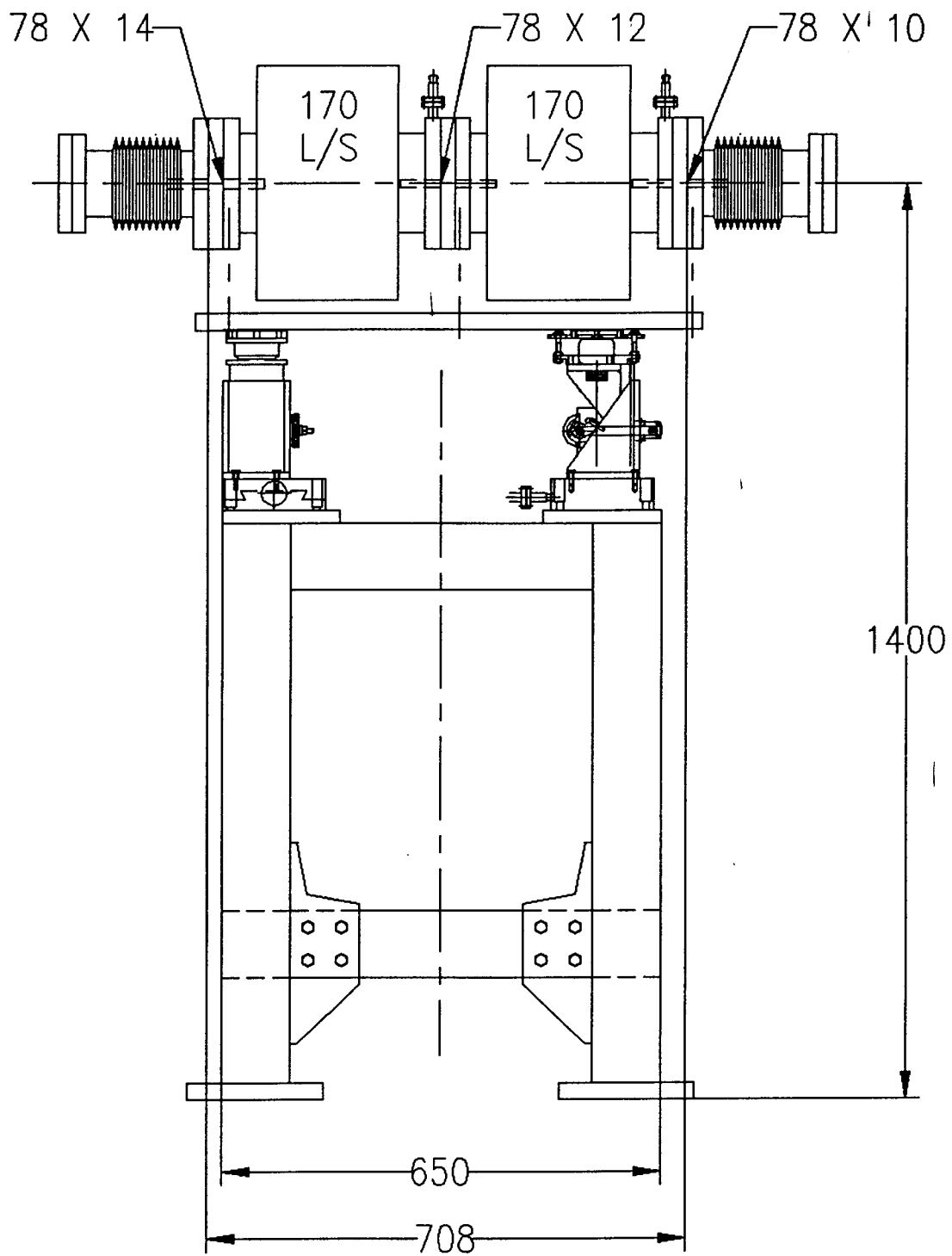


Figure 14

5. Slits

- 5.1.1. White beam slits - insertion device
- 5.1.2. White beam slits - bending magnet
- 5.2. Monochromatic beam slits

Design Status and Schedule

The design of slits and the choice of the material for their construction is closely related to their application. The CATs will have to participate closely in slit designs. For the present, the APS has put much emphasis on the power handling issue related to slit designs. These designs are not likely to meet all user needs. More work will be scheduled in this area as users provide more input to the APS during the beamline preliminary design phase.

In sections 5.1.1 and 5.1.2, the currently designed APS white beam slits for the insertion device and the bending magnet source are included along with specifications. The APS is currently working on its fabrication procedures to develop a prototype to be completed by the end of 1993.

In section 5.2 a monochromatic slit has been specified.

5.1.1. APS ID White Beam Slits

- Horizontal and vertical slits
- White beam compatible
- Four independent precision high load actuators
- Cooling for structural, vibrational, and thermal stability
- UHV compatible
- Provide for closed aperture

The APS white beam slits provide for precise aperture for the white synchrotron radiation. APS standard high load stepping linear actuator modules are used with horizontal and vertical slits. Each of the four masks in the slit assembly is independently movable. The beam intercepts the slits with a grazing incidence. Water-cooled copper foam removes the heat from the slit masks. The masks have been designed so that a pair of slits can be removed through a single vacuum port.

Specifications:

- Slit positional resolution:	2 μm
- Slit positional reproducibility:	5 μm
- Vertical aperture:	0 - 30 mm
- Horizontal aperture:	0 - 100 mm
- Grazing incidence angle:	3° (typical)
- Vacuum tank flanges:	6 inch
- Vacuum tank length:	< 1500 mm
- Actuator:	Standard APS heavy load stepping linear actuator
- Actuator drive:	Stepping motor with linear encoder
- Actuator maximum speed:	20 mm/min
- Encoder	Linear encoder

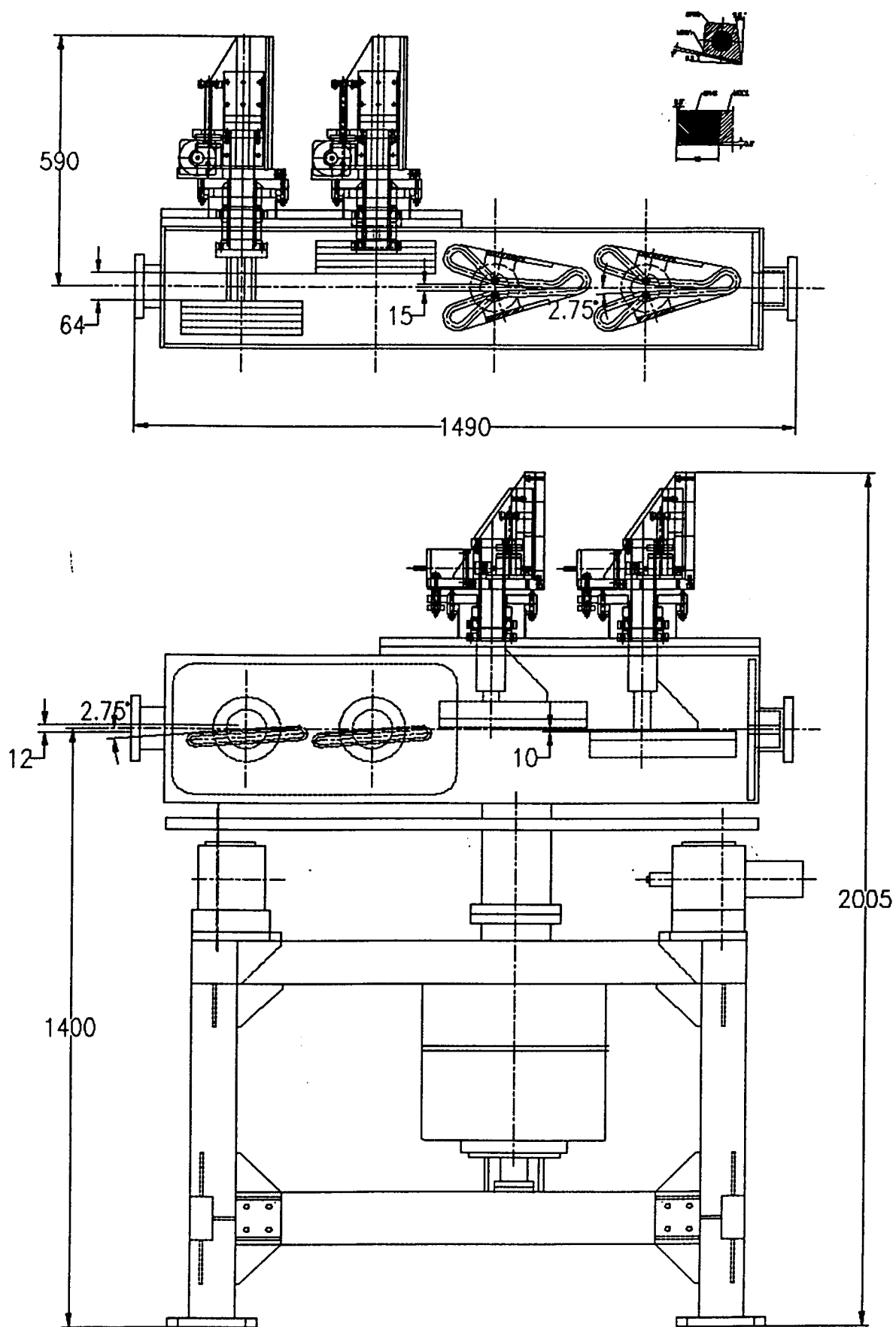


Figure 15

5.1.2. APS BM White Beam Slits

- Horizontal and vertical slits
- White beam compatible
- Four independent precision light load actuators
- Cooling for structural, vibrational, and thermal stability
- UHV compatible
- Provide for closed aperture

The APS white beam slits provide for precise aperture for the white synchrotron radiation. APS standard light load stepping linear actuator modules are used with horizontal and vertical slits. Each of the four masks in the slit assembly is independently movable. The beam intercepts the slits with a normal incidence. Water cooling removes the heat from the slit masks. The masks have been designed so that each one can be removed through a single vacuum port.

Specifications:

- | | |
|------------------------------------|--|
| - Slit positional resolution: | 10 μ m |
| - Slit positional reproducibility: | 25 μ m |
| - Vertical aperture: | 0 - 30 mm |
| - Horizontal aperture: | 0 - 150 mm |
| - Vacuum tank flanges: | 8 inch |
| - Vacuum tank length: | < 900 mm |
| - Actuator: | Standard APS light load stepping linear actuator |
| - Actuator drive: | Stepping motor with linear encoder |
| - Actuator maximum speed: | 50 mm/min |

ADVANCED PHOTON SOURCE

DRAFT

BM WHITE BEAM HORIZONTAL AND VERTICAL SLITS

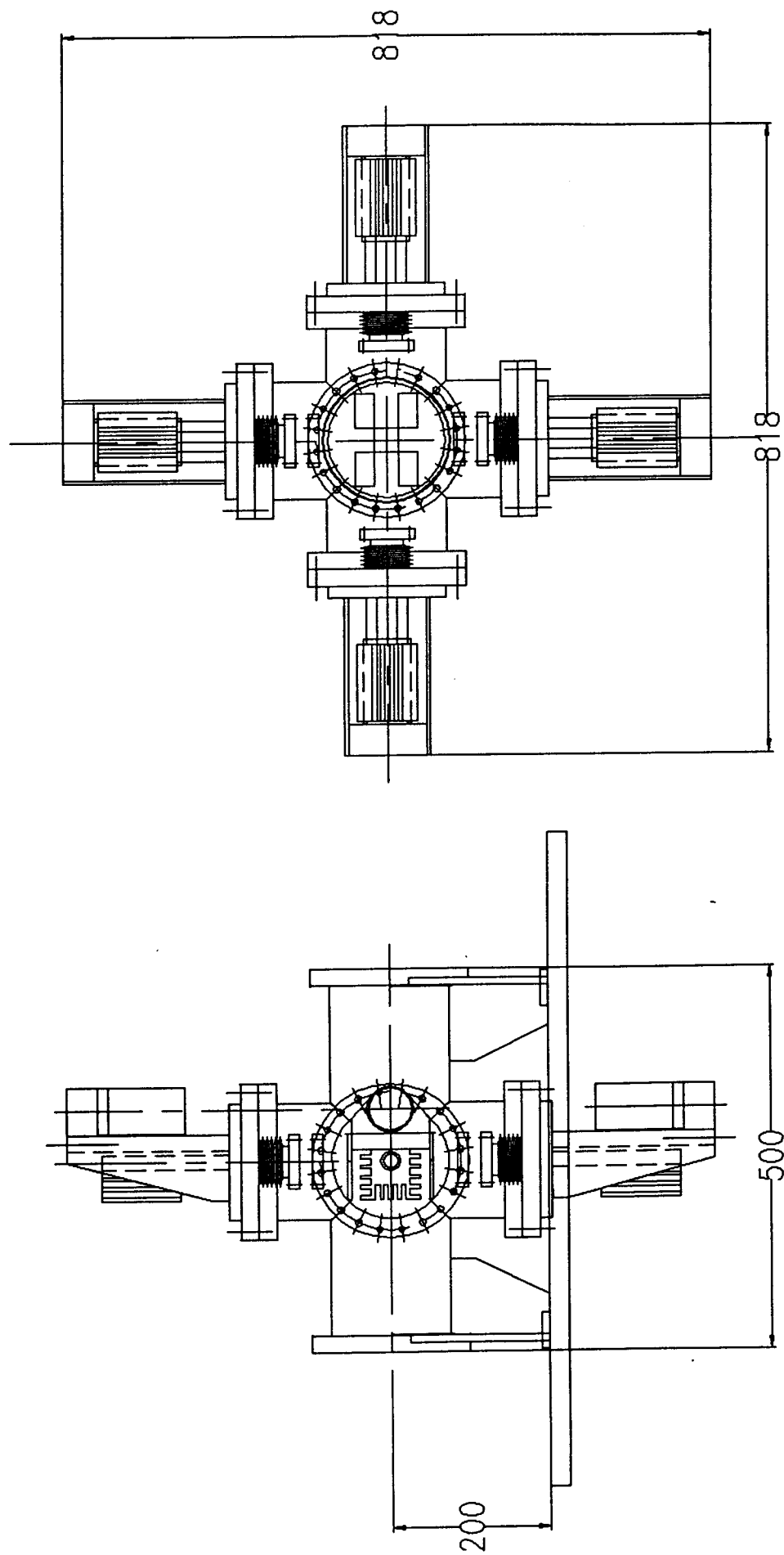


Figure 16

IDMONOS.DWG 01-20-92

ADVANCED PHOTON SOURCE

DRAFT

ID MONOCHROMATIC BEAM HORIZONTAL AND VERTICAL SLITS

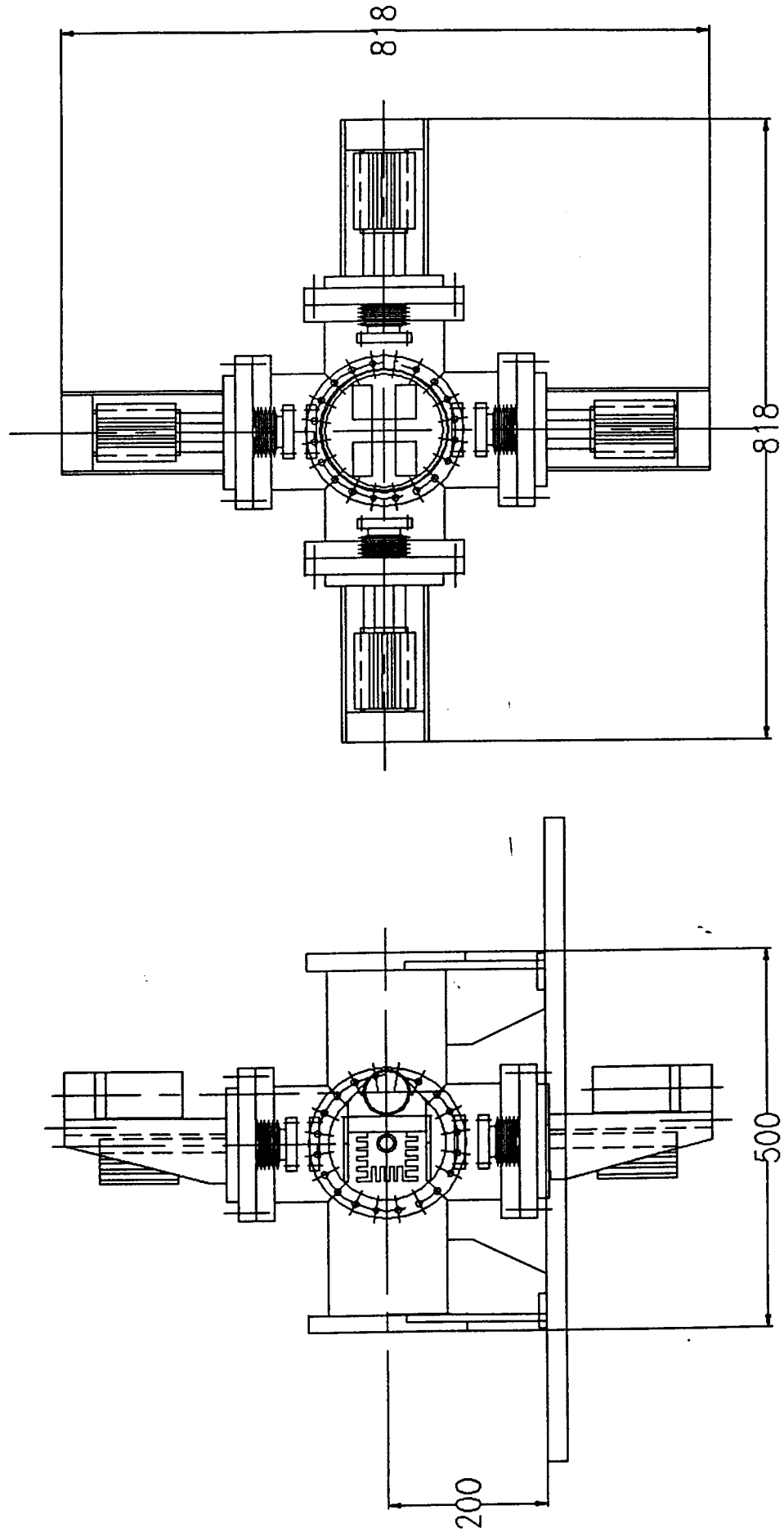


Figure 17

IDMONOS.DWG 01-20-92

6. Beam Shutters and Beam Stops

- 6.1. Monochromatic beam shutter - insertion device
- 6.2. White beam stop with integral shutter - insertion device
- 6.3. White beam stop with integral shutter - bending magnet (added later)

Design Considerations

All white beam stops discussed in sections 6.2 and 6.3 are combinations of water-cooled photon absorbers and heavy metal beam stops. Together photon absorber and beam stop completely stop all the radiation from any of the insertion device or bending magnet sources. In order to have a safe operationing scheme, the absorber and the stop will be locked with a "Kirk" key system parallel in its appropriate position.

Design Schedule

The design of the prototype is in an advanced stage and will be completed by May 1993.

6.1 Monochromatic Beam Shutter - Insertion Device

The monochromatic beam shutter is designed to handle monochromatic beam loads from APS insertion devices. In this design, the heat is conducted by a copper rod to a conventional aircooled radiator.

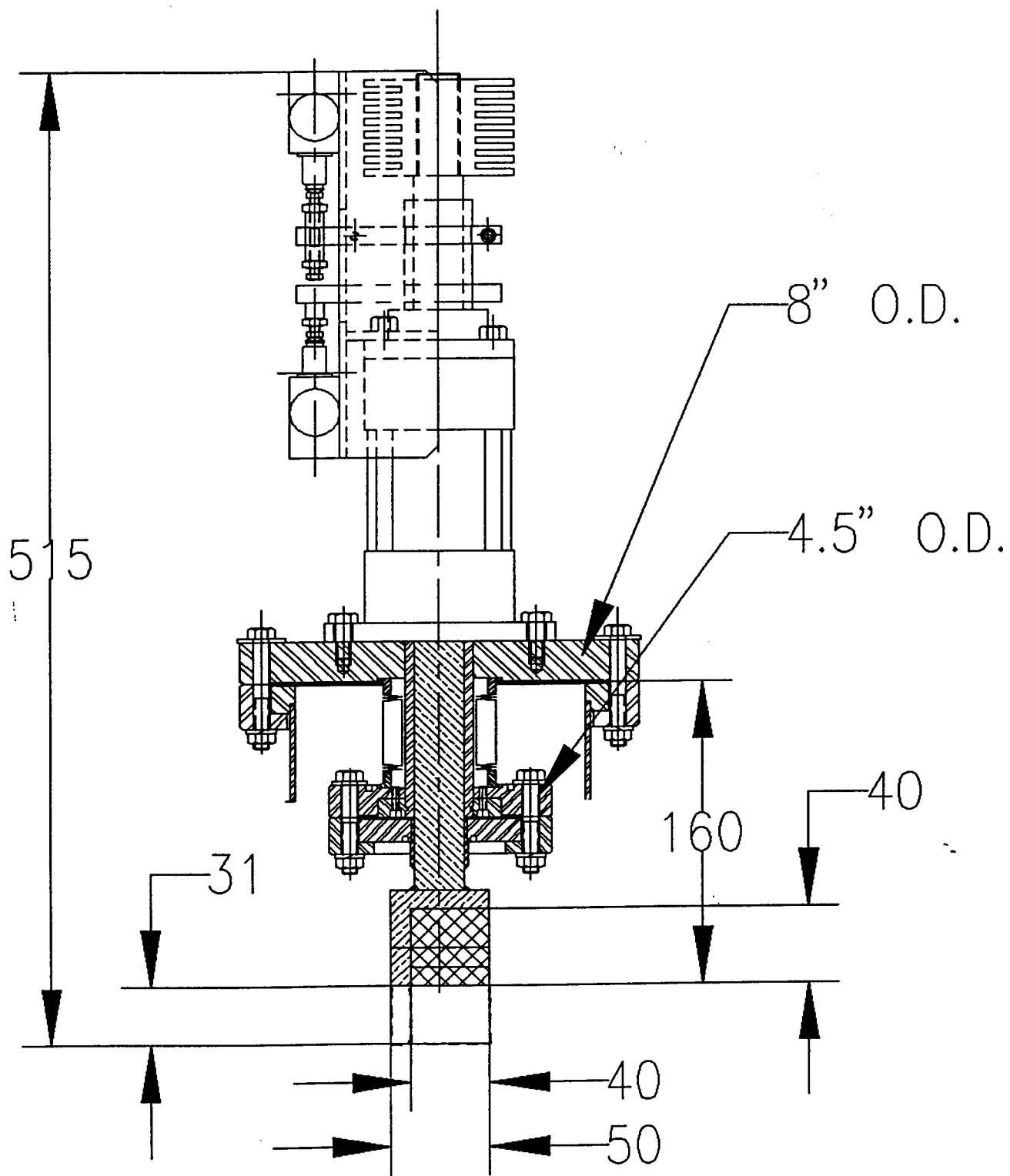
Assumptions

All APS beamlines are required to have two independent beam shutters, each capable of stopping the beam, so that there is less exposure than permitted according DOE guidelines (0.25 mrem/h). The following assumptions are made in this design specification:

- | | |
|---|-------------|
| 1. Maximum energy transmitted | 500 keV |
| 2. Maximum critical energy of the ID | 32.6 keV |
| 3. Maximum total power | 10 W |
| 4. Maximum bandpass at 500 keV | 0.1% |
| 5. Expected radiation dose behind one shutter | 0.25 mrem/h |
- These are extremely conservative assumptions for the design because the monochromators are unlikely to propagate full spectrum power in the higher harmonics.

Specifications

- | | |
|----------------------------|---|
| 1. Material of the shutter | 1/2" Cu + 1 5/8" (40 mm) heavy metal |
| 2. Optical aperture | 80 x 40 mm ² |
| 3. Actuator | APS light load actuator with pneumatic drive (12.4) |
| 4. Closing time | 1 sec |
| 5. Mounting flange | 8" O.D. |
| 6. Vacuum | UHV compatible |



P4 ID MONO. PHOTON SHUTTER 1

P4S1.DWG 02-22-1993

Figure 18

ADVANCED PHOTON SOURCE

Design Specifications for P4 ID White Beam Photon Absorber

- 1, Location : 31.10 m from APS ID Straight Section Center
 - 2, Optical Aperture Area : 75 mm (H) x 13 mm (V)
 - 3, Horizontal Maximum Acceptance : 2.57 mrad
 - 4, Vertical Maximum Acceptance : 0.42 mrad
 - 5, Closing Time : 1 sec
 - 6, Input Fringe O.D. : 8 inch
 - 7, Output Fringe O.D. : 14 inch
 - 8, Mask Grazing Incidence Angle : 3 degree
 - 9, Mask Material : OFHC with Glid-Cop Face Plate
 - 10, Water Cooling : Mesh-filled Tube
 - 11, Mask Motion Structure : Two-Point Suspension Hockey Stick
 - 12, Actuator : Pneumatic
End Point Reproducibility : 10 um
 - 13, Damper : Pneumatic
 - 14, Mask Length : 250 mm
 - 15, Device Fringe to Fringe Length : 1030 mm (with heavy metal stop)
 - 16, Vacuum : UHV Compatible
 - 17, Maximum Total Power : 5000 W
-

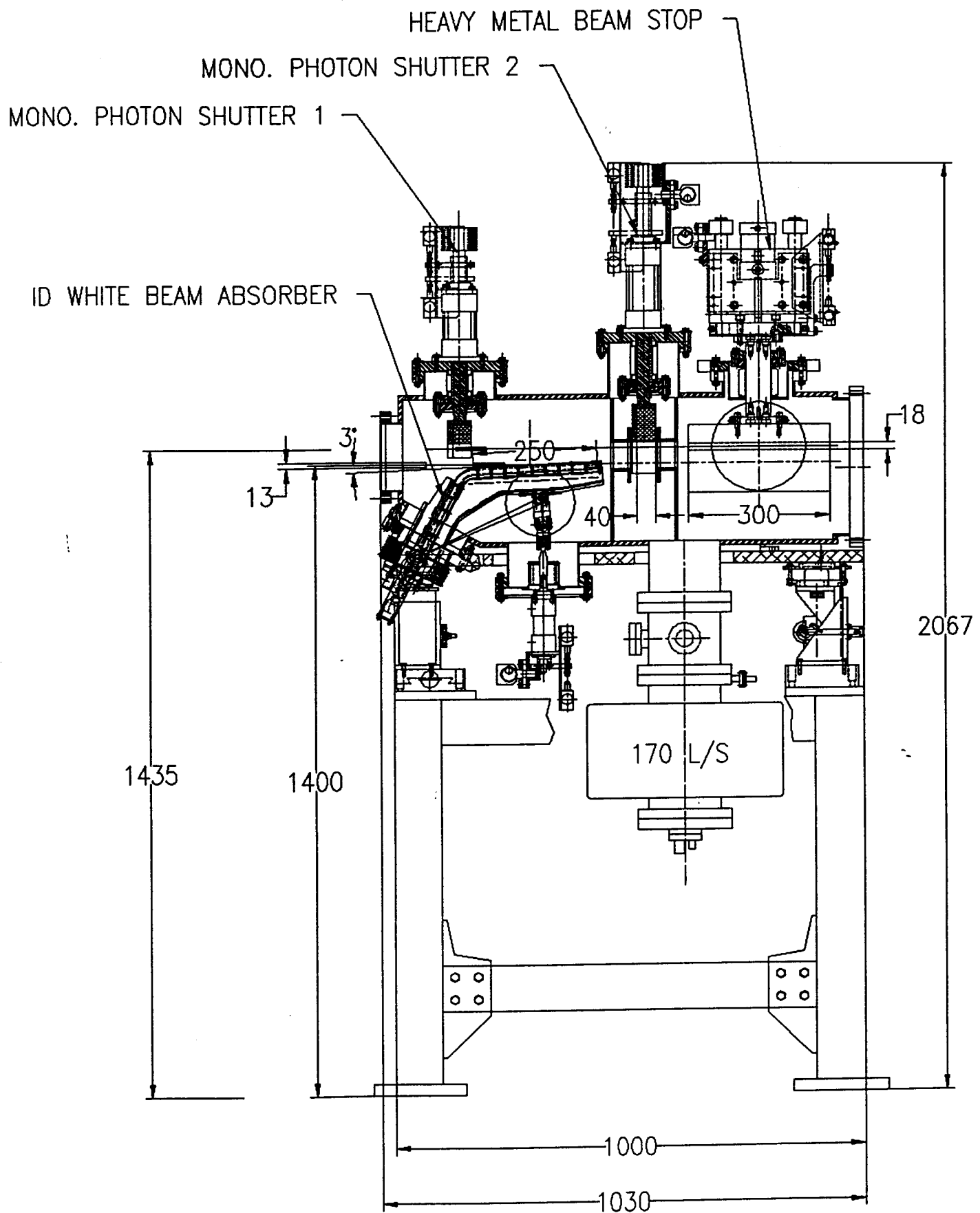


Figure 19

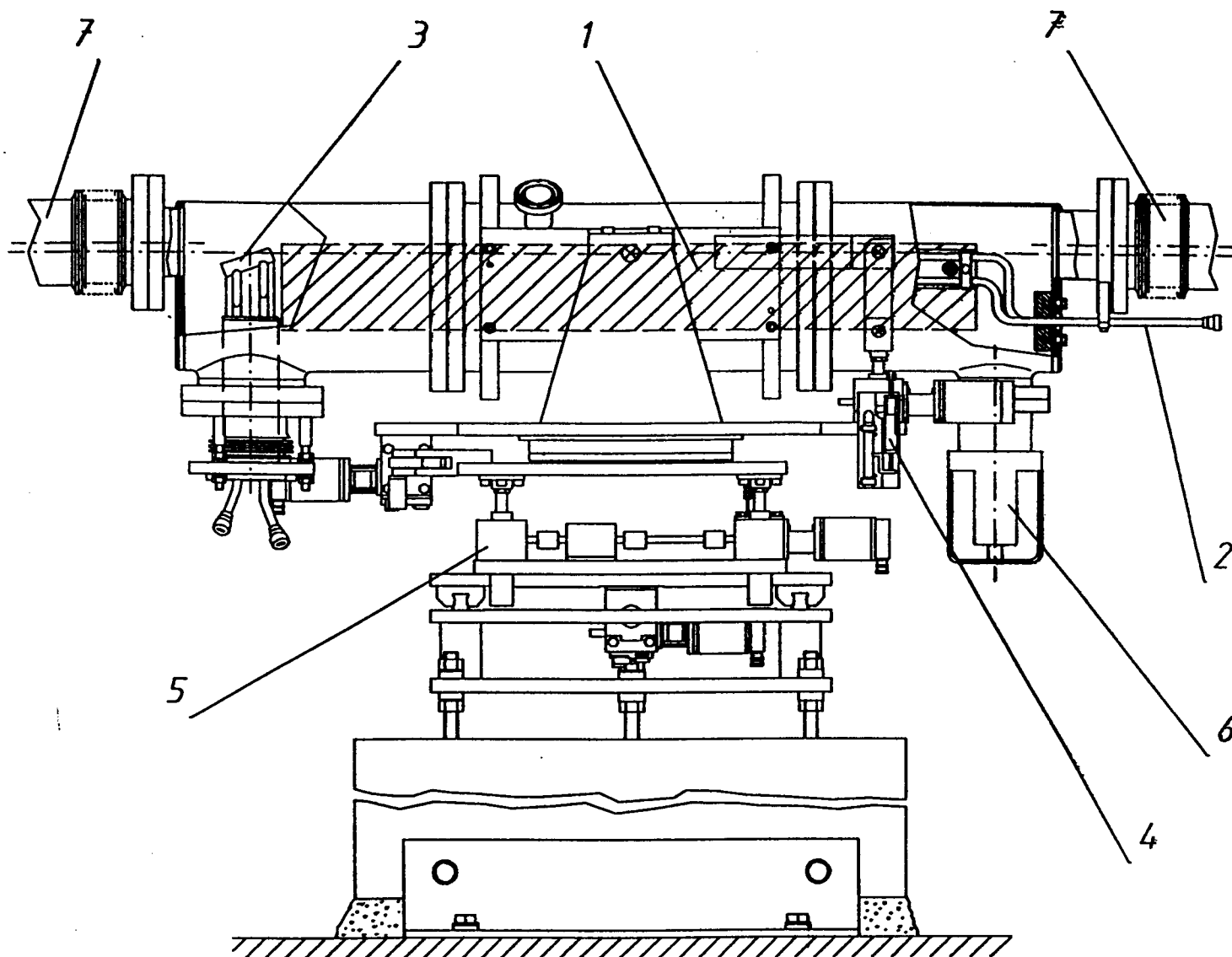
7. Mirror Chambers

Mirror chambers are used to provide a stable, vibration- and force-free support of beam deflecting mirrors. The chamber must allow the very precise alignment of the mirror. Angle resolutions of the deflection angle of less than 1 μ rad have to be achieved. The vacuum condition in the chamber ($<1 \times 10^{-9}$ torr) shall avoid carbon contamination of the reflecting surface. In combination with high power beamlines effective cooling has to be supplied. The chamber has to allow bending of the mirror for variable focusing.

To shift the photon energy cut off of the mirrors to high energies, very small reflection angles (e.g. 3 - 4 mrad) are needed. To get a sufficient beam acceptance of the mirror, long mirrors (> 1 m) are used. This strongly influences the chamber design. HASYLAB has had good experience with a chamber design, that makes use of a stiff central chamber frame. The mirror is supported by this frame. The stiffness of the frame withstands easy deformations introduced to the chamber by air pressure or thermal expansion without affecting the alignment of the mirror. The deformations are mainly carried by the cylindrical part of the chamber.

The mirror is aligned by aligning the whole chamber. The chamber movements are decoupled from the beamline by bellows, which allow transversal movements in the vertical and horizontal directions of ± 25 mm. Angular rotations around the beam axis have to be excluded to protect the bellows. This rotation can be easily excluded because of the very small deflection angle.

Figure 21 shows the cooled x - ray mirror chamber design for a 1-m-long cooled toroidal mirror at HASYLAB. Because these are well-tested designs, the APS plans to adopt these designs for the use of the CATs. An improved design drawing for such a mirror chamber will be available before September 1993. The support system for the mirror chamber is also a standard design and is discussed in section 9.1.3.



X - ray mirror chamber for high power beamlines at HASYLAB

Design criteria:

- mirror alignment by moving the whole mirror chamber
- linear and rotational movings mechanically decoupled
- rigid central chamber frame as mirror support
- friction-free rotation of the deflection angle (resolution < 1 μ rad)
- chamber movement decoupled from the beamline by formed bellows
- range of linear movement ± 25 mm

- | | |
|---|---|
| 1 | toroidal mirror (1000 x 130 x 130) |
| 2 | water cooling |
| 3 | water-cooled absorber (protection of the mirror face) |
| 4 | linear encoder |
| 5 | mirror support and aligning system |
| 6 | ion pump |
| 7 | bellows |

Figure 20

8. Beam position monitors

8.1. White beam position monitor

8.2. Monochromatic beam position monitor

Design Schedule

A prototype of the white beam position monitor for the ID beams has been built and tested. The drawings are in section 8.1, along with specifications.

The monochromatic beam position monitors are of a lower priority for design, because many designs are already in use at various synchrotron facilities.

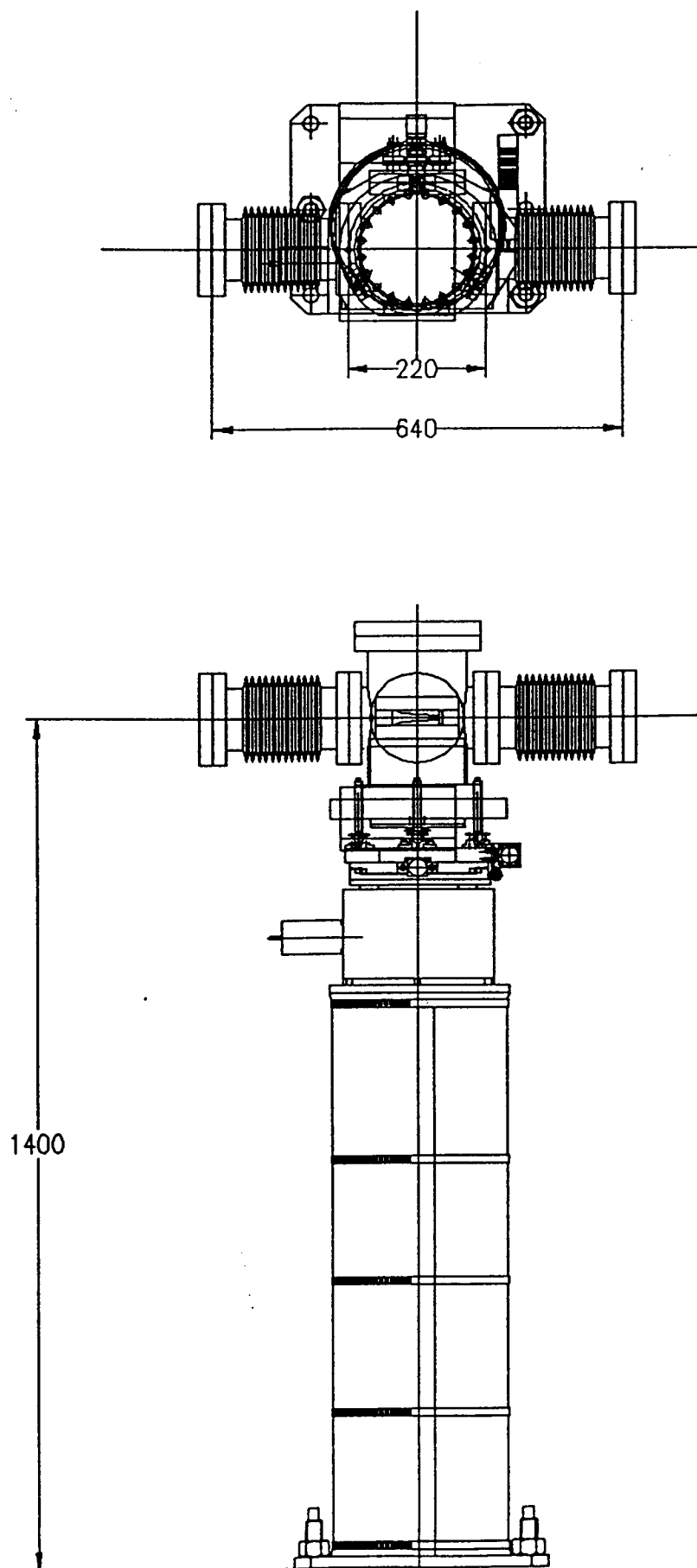
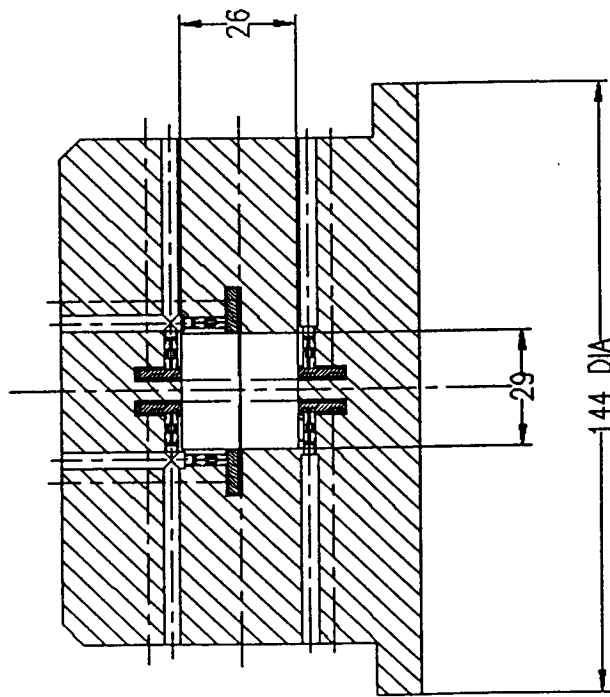
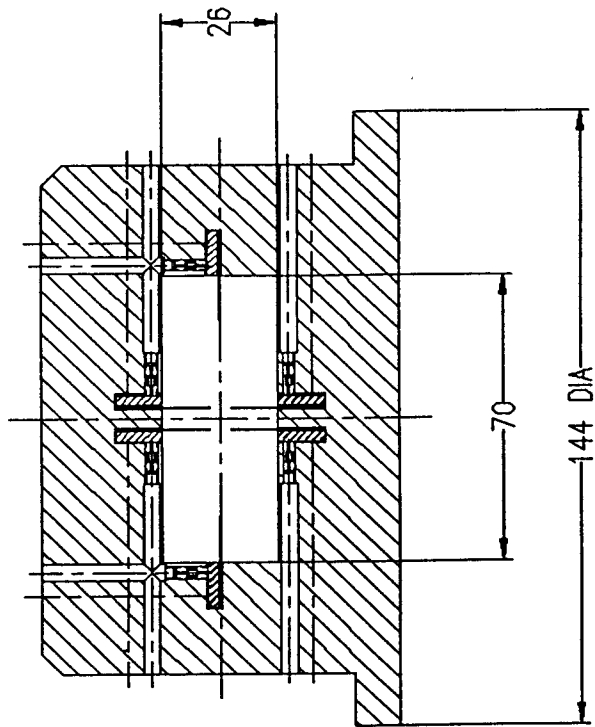


Figure 21

ID FE PBPM
(FIXED VERSION)



ID FE PBPM
(FOR UNDULATOR A)



ID FE PBPM
(FOR WIGGLER A)

Figure 22

9. Supports

- 9.1. Kinematic mount support tables
 - 9.1.1. Economic style support table
 - 9.1.1.1. Vertical motion cone
 - 9.1.1.2. Vertical motion V
 - 9.1.1.3. Vertical motion Flat
 - 9.1.1.4. Horizontal motion
 - 9.1.2. Standard style support table
 - 9.1.2.1. Standard vertical stage
 - 9.1.2.2. Standard horizontal stages
 - 9.1.2.3. Standard spherical coupling
 - 9.1.2.4. Standard V coupling
 - 9.1.2.5. Standard Flat coupling
 - 9.1.3. Precision style support table
 - 9.1.3.1. Precision vertical stage - "A"
 - 9.1.3.2. Precision vertical stage - "B"
 - 9.1.3.3. Precision vertical stage - "C"
 - 9.1.3.4. Precision horizontal stage - "A"
 - 9.1.3.5. Precision horizontal stage - "B"
 - 9.1.3.6. Precision horizontal stage - "C"
- 9.2. Beam position monitor support
 - 9.2.1. Beam position monitor vertical stage
 - 9.2.2. Beam position monitor horizontal stage
 - 9.2.3. Beam position monitor rotation stage
 - 9.2.4. Beam position monitor support column
 - 9.2.5. Beam position monitor kinematic mount cone
 - 9.2.6. Beam position monitor kinematic mount flat
 - 9.2.7. Beam position monitor kinematic mount V
- 9.3. Ion pump supports
 - 9.3.1. Inline 60 l/s ion pump support
- 9.4. Beam pipe supports
 - 9.4.1. 6" beam pipe support

Design Status

All supports have been fully designed. The prototypes of each of the supports are either already built or under construction. The tests will be completed by June 1993.

APS/XFD FE Support System

	FE Economic Support Table	FE Standard Support Table	FE Precision Support Table	FE PBPM Support
Max. Load (Kg)	1000	1000	1000	90
Slide Type (V)	N/A	Linear Rolling	Linear Rolling	Linear Rolling
Slide Type (H)	Regular Friction	Regular Friction	Linear Rolling	Linear Rolling
Travel Range (V) (H) (mm)	50	50	12.7	12.7
Motion (V) Resolution (um)	250	50	10	0.1
Motion (H) Resolution (um)	250	50	10	0.1
Motion (V) Repeatability (um)	400	100	50	2
Motion (H) Repeatability (um)	400	250	50	2
(V) Straightness of Trajectory (rad/5mm)	N/A	5 E -4	2 E -4	1 E -5
(H) Straightness of Trajectory (rad/5mm)	N/A	2 E -3	1 E -4	1 E -5
Basic Operating Mode	Manual	Manual	Stepping Motor	Stepping Motor
Optional Operating Mode	N/A	Stepping Motor	Manual	Manual

ADVANCED PHOTON SOURCE

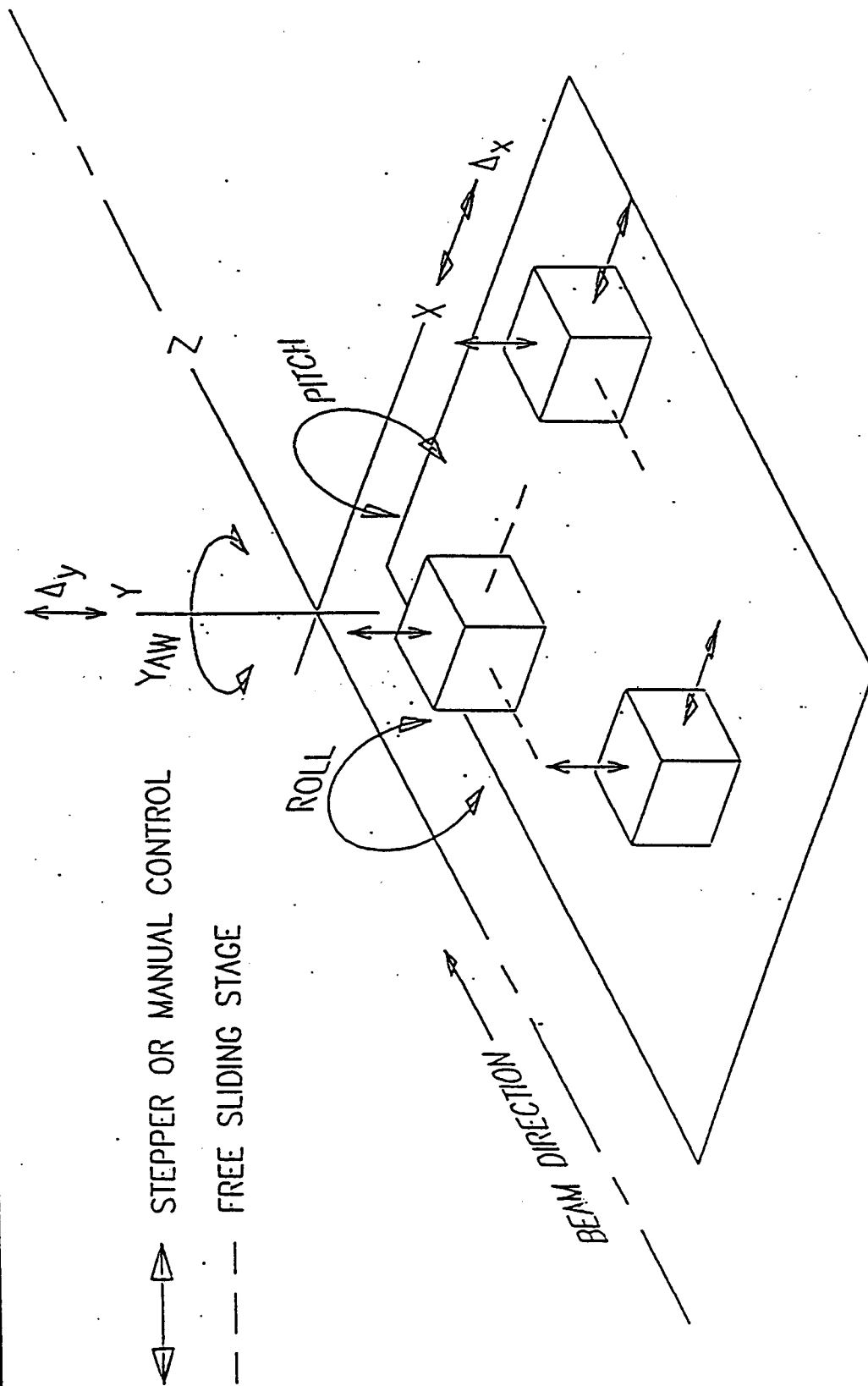


Figure 23

3-POINT KINEMATIC MOUNTING

ECONOMICAL SUPPORT TABLE SPECIFICATIONS

Max. Load (Kg)	1000
Slide Type (V)	N/A
Slide Type (H)	Regular Friction
Travel Range (V) (H) (mm)	50
Motion (V) Resolution (um)	250
Motion (H) Resolution (um)	250
Motion (V) Repeatability (um)	400
Motion (H) Repeatability (um)	400
(V) Straightness of Trajectory (rad/5mm)	N/A
(H) Straightness of Trajectory (rad/5mm)	N/A
Basic Operating Mode	Manual
Optional Operating Mode	N/A

ADVANCED PHOTON SOURCE

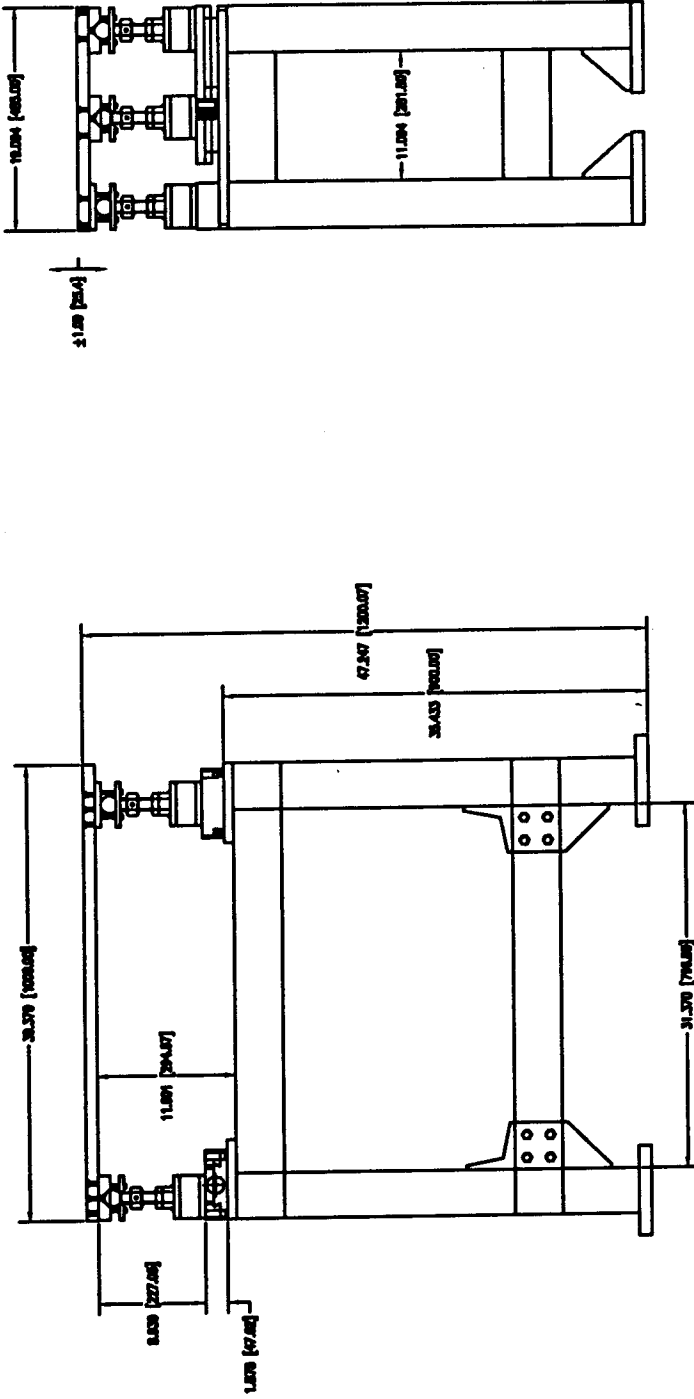
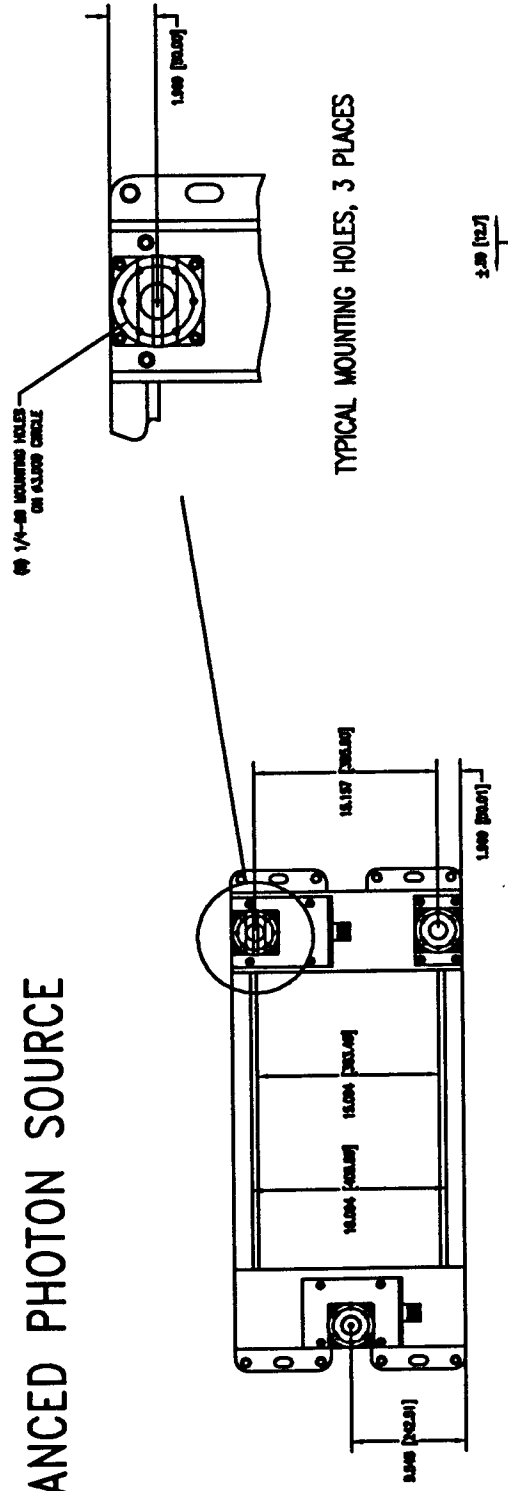


Figure 24

ECONOMICAL SUPPORT BASE WITH ECONOMICAL STYLE KINEMATIC MOUNT STAGES

ADVANCED PHOTON SOURCE

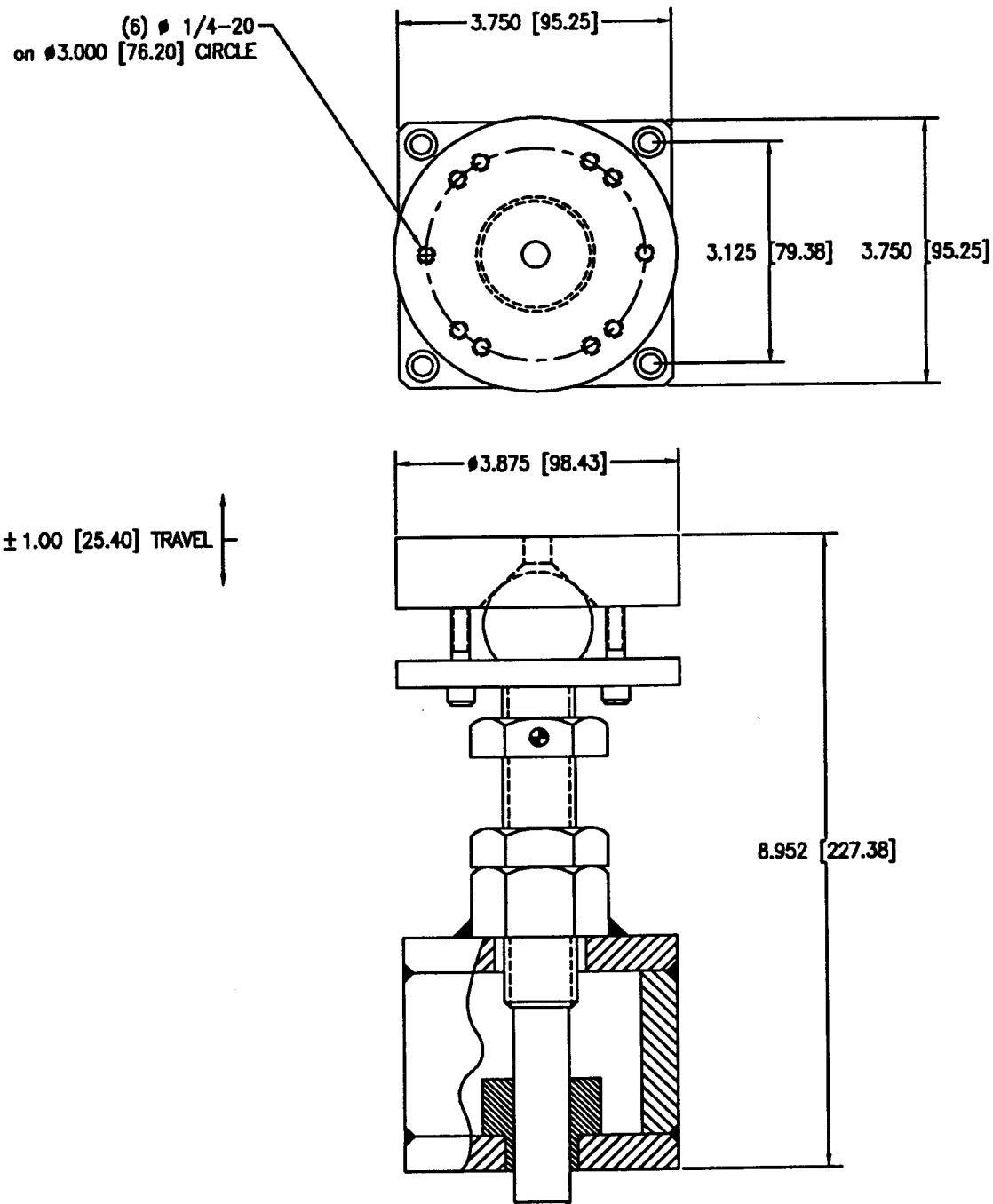


Figure 25

ECONOMICAL VERTICAL KINEMATIC MOUNT – CONE

ADVANCED PHOTON SOURCE

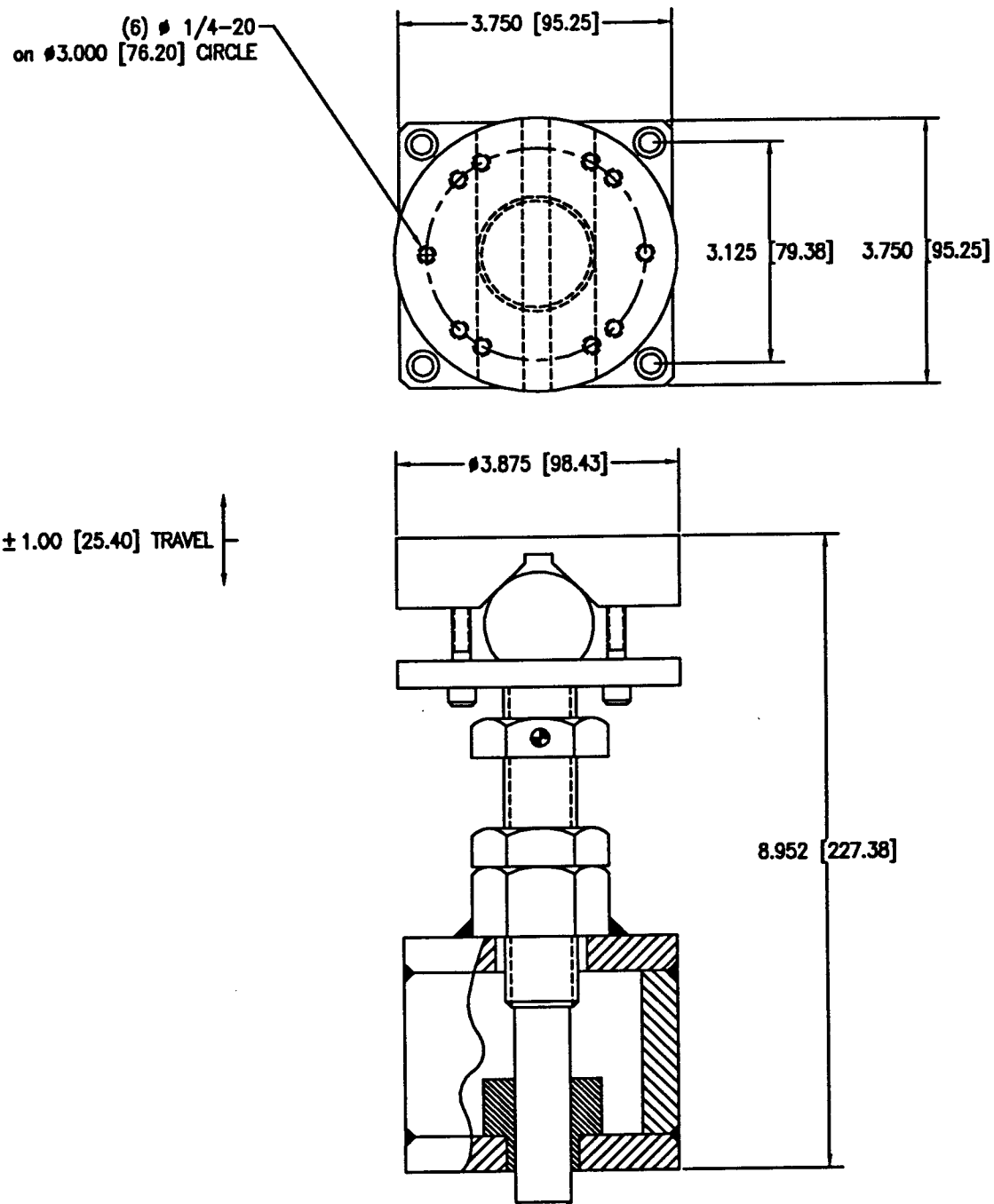


Figure 26

ECONOMICAL VERTICAL KINEMATIC MOUNT - V

ADVANCED PHOTON SOURCE

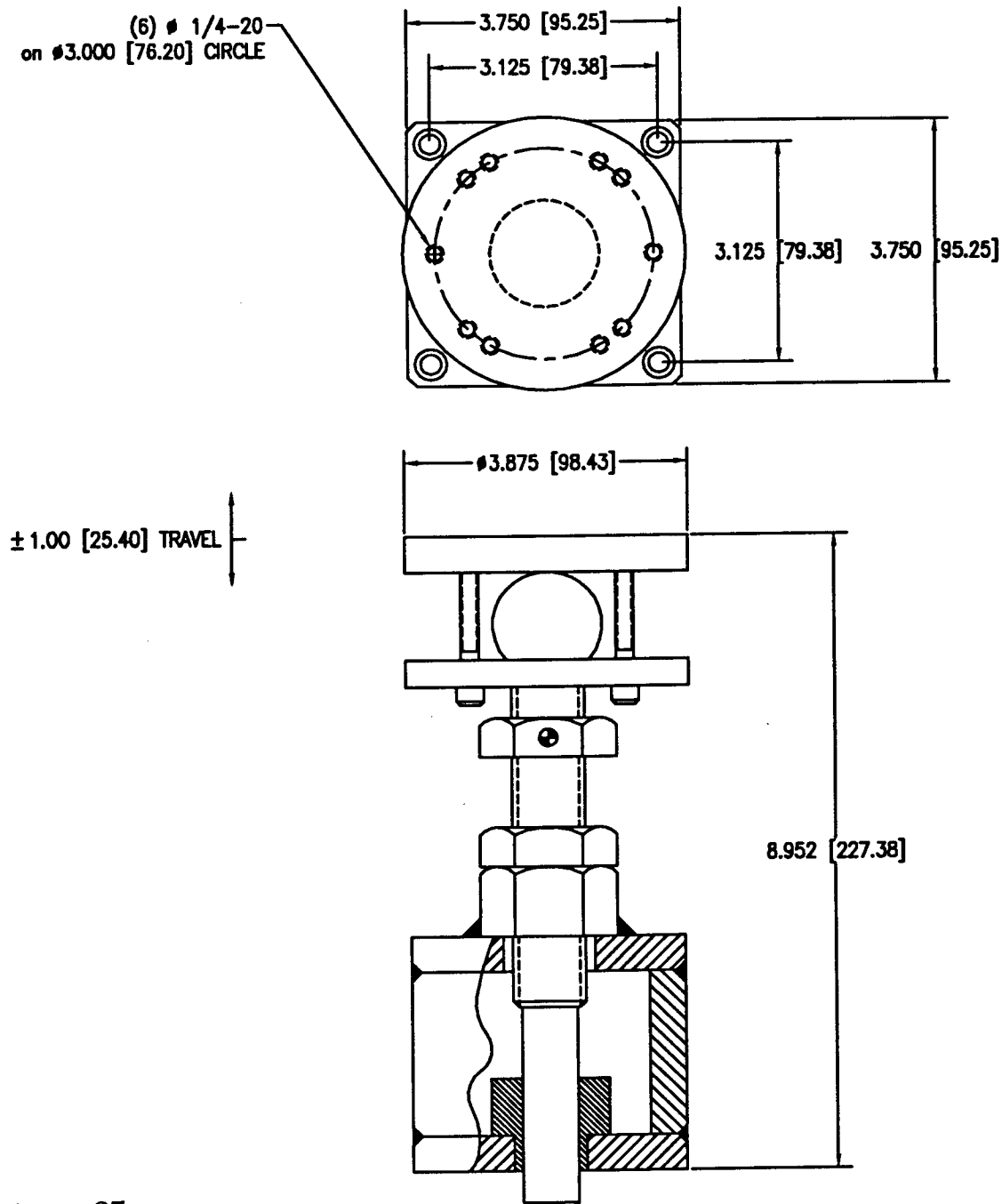
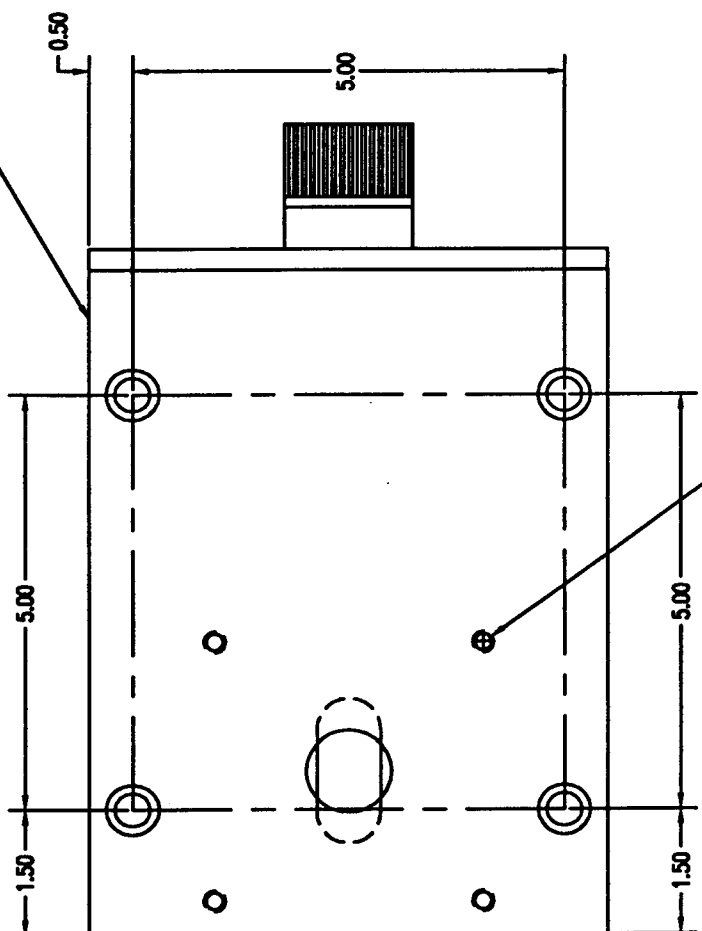


Figure 27

ECONOMICAL VERTICAL KINEMATIC MOUNT - FLAT

MILWAUKEE SLIDE AND SPINDLE SLIDE, PART NO. R-668L
WITH GB LOCK AND KNURLED HAND KNOB



KNURLED KNOB

(4) 1/4-20 UNC X .50 DEEP
ON 3.125 SQUARE

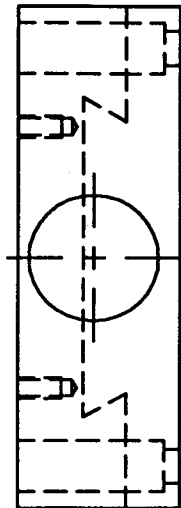
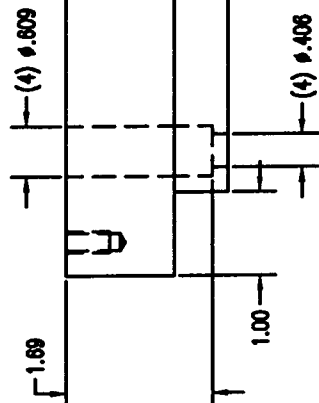
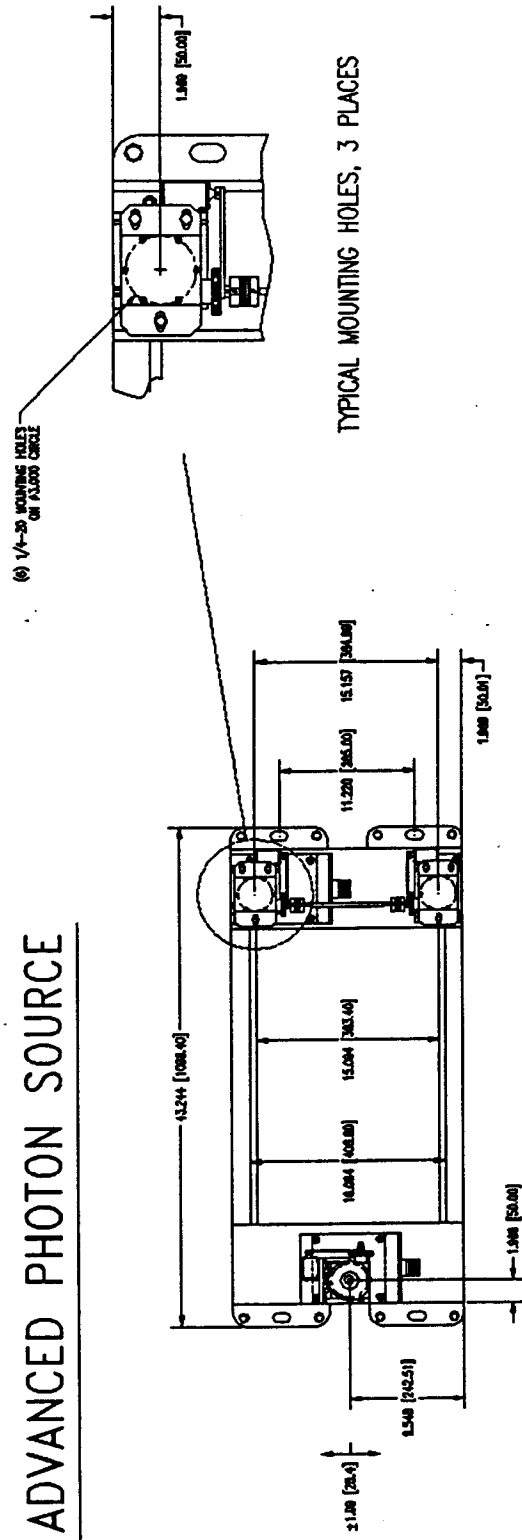


Figure 28 ECONOMICAL KINEMATIC MOUNT HORIZONTAL SLIDE

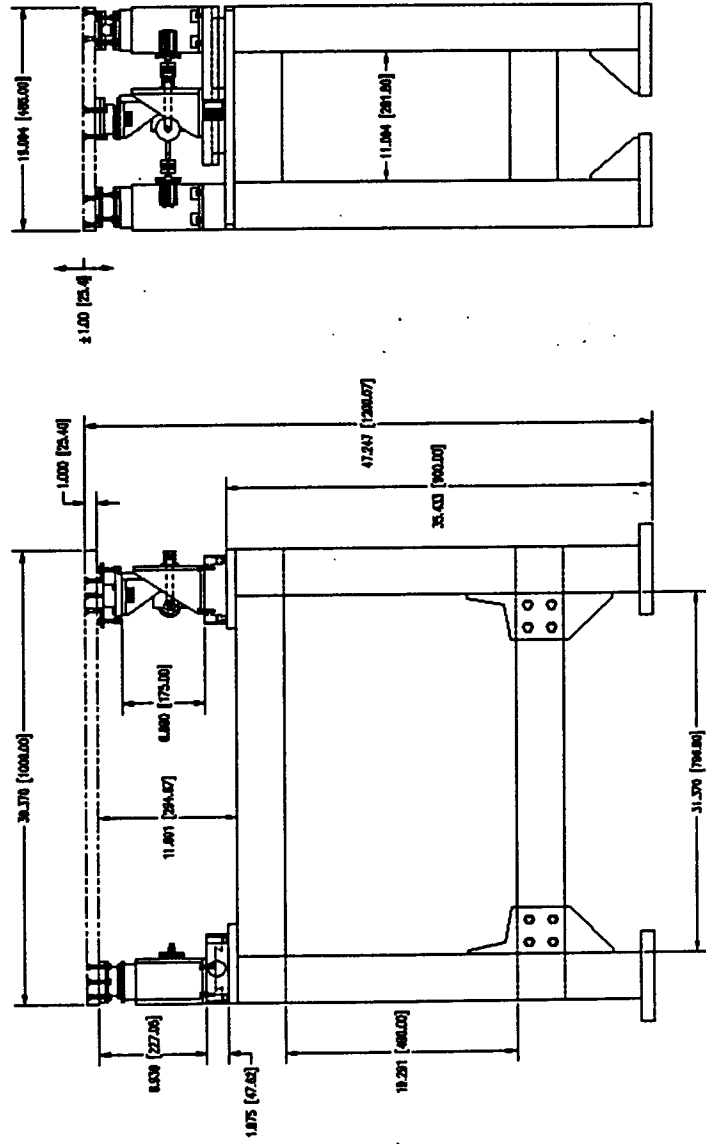
STANDARD SUPPORT TABLE SPECIFICATIONS

Max. Load (Kg)	1000
Slide Type (V)	Linear Rolling
Slide Type (H)	Regular Friction
Travel Range (V) (H) (mm)	50
Motion (V) Resolution (um)	50
Motion (H) Resolution (um)	50
Motion (V) Repeatability (um)	100
Motion (H) Repeatability (um)	250
(V) Straightness of Trajectory (rad/5mm)	5 E -4
(H) Straightness of Trajectory (rad/5mm)	2 E -3
Basic Operating Mode	Manual
Optional Operating Mode	Stepping Motor

ADVANCED PHOTON SOURCE



TYPICAL MOUNTING HOLES, 3 PLACES

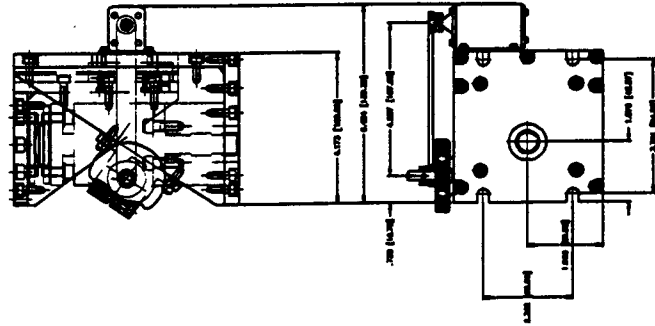
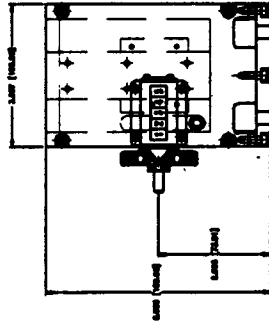
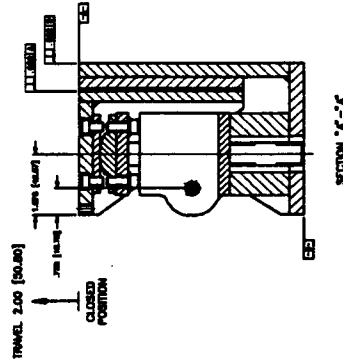
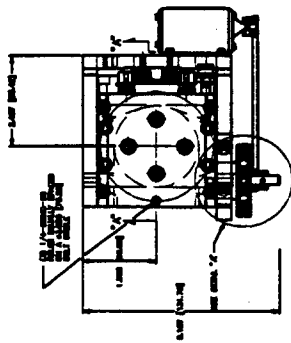


SPECIFICATIONS:

1. LOAD CAPACITY: 2200 LBS [1000 kg]
2. DEGREES OF FREEDOM: 5
3. TRAVEL RANGE: $\pm 1"$ [25.4 mm]
4. MECHANICAL COUNTER RESOLUTION: .005"/COUNT
5. VERTICAL AND HORIZONTAL ADJUSTMENT: HAND KNOB
6. OPTIONAL MOTOR MOUNTS AVAILABLE

Figure 29 STANDARD SUPPORT BASE WITH STANDARD KINEMATIC MOUNT STAGES

- TECHNICAL SPECIFICATIONS:**
1. TRAVEL 2 inch [50.80]
 2. LOAD CAPACITY 1000 lb. [450 kg.]
 3. MANUAL VERTICAL ADJUSTMENT :
 4. MECHANICAL COUNTER RESOLUTION : .001" per count
 5. TURNS PER INCH OF TRAVEL : 20
 6. MAX. OFFSET LOAD DISTANCE : 1 inch.



SECTION "A-A"

Figure 30 STANDARD KINEMATIC MOUNT VERTICAL STAGE

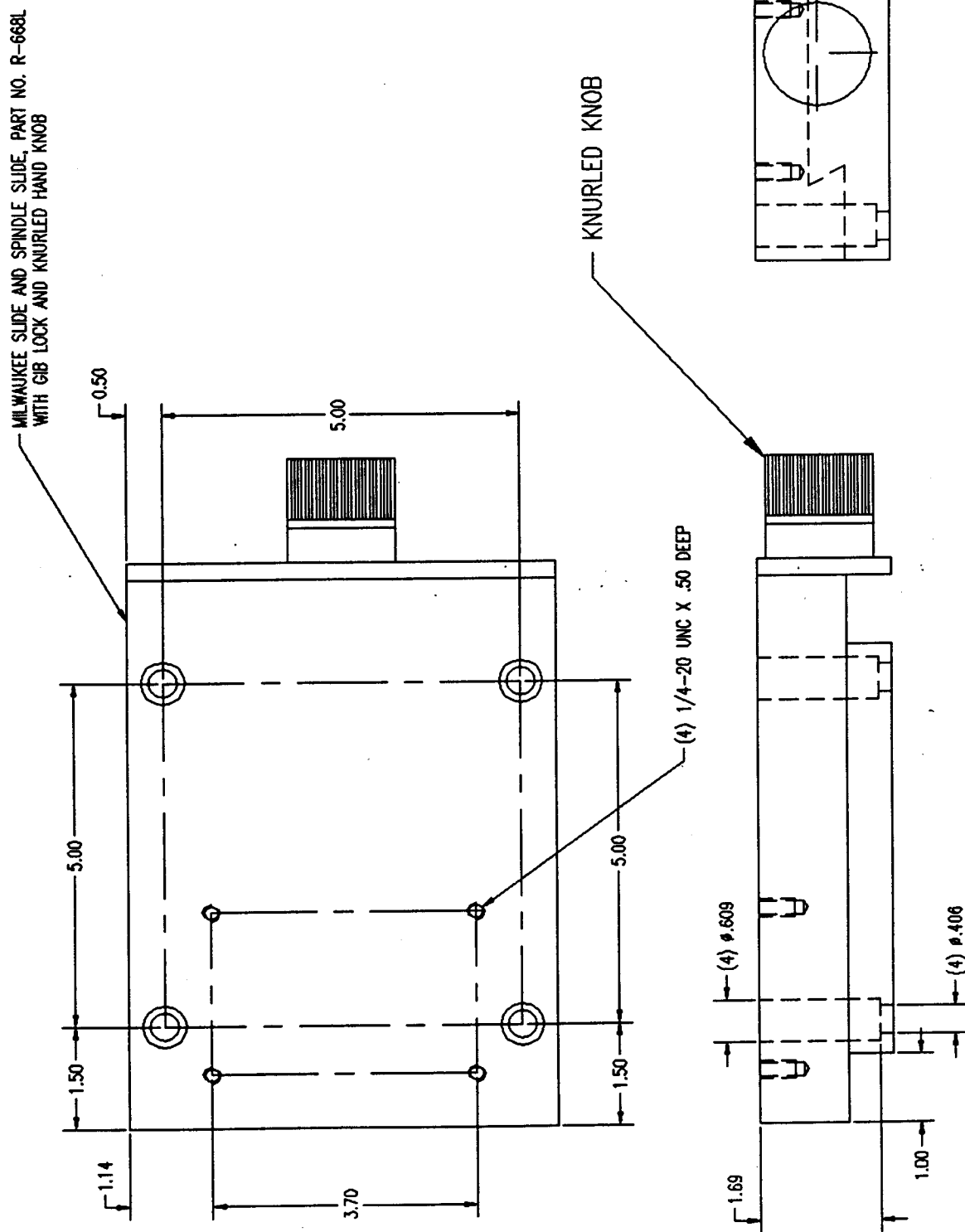
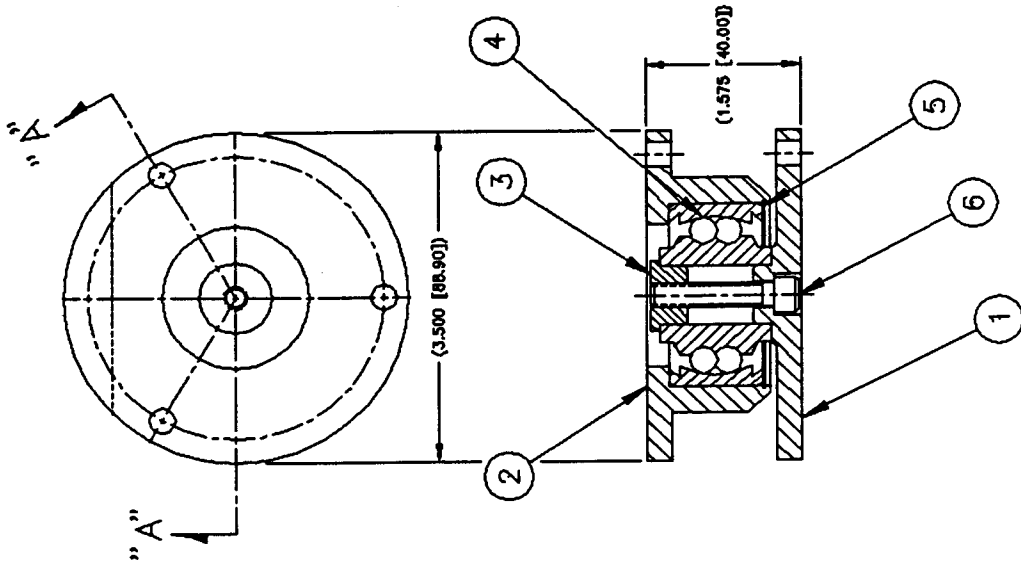


Figure 31



SECTION "A" - "A"

STANDARD KINEMATIC MOUNT SPHERICAL COUPLING

Figure 32

NOTE:

1. ALL DIMENSIONS SHOWN IN [] ARE MILLIMETERS.

ITEM	DWG/PART NUMBER	DESCRIPTION	MATERIAL / SPEC	QTY
6	1/4-20UNC-2A X 1.25 LG. CAP. SCR.	STN. STL.	1	
5	RETAINING RING, (ASSOC. SPRING)	CI 193	1	
4	BEARING, SELF ALIGNING (AST)	DSP-10	1	
3	P4105090501-820803 FASTENER	304 STN. STL. ROUND	1	
2	P4105090501-820802 BEARING HOUSING	304 STN. STL. ROUND	1	
1	P4105090501-820801 BASE	304 STN. STL. ROUND	1	

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<p>LOG NUMBER A07504</p>	<p>DATE 9/2/82</p>
<p>DRAWN BY HP Czerwinski</p>	<p>DATE 9/2/82</p>
<p>CHECKED BY D. SHU</p>	<p>DATE 9/2/82</p>
<p>DESIGNED BY T. KUZAY</p>	<p>DATE 9/2/82</p>
<p>APPROVED BY J. BARRAZA</p>	<p>DATE 9/2/82</p>
<p>ADVANCED PHOTON SOURCE T1 FRONT END SPHERICAL COUPLING ASSEMBLY</p>	
<p>SCALE 1:1</p>	
<p>SHEET 1 of 1</p>	
<p>DRAWING NUMBER P4105090501-820800-00</p>	

SYN	CHANGE DESCRIPTION	BY	CHKD	DATE

REVISIONS

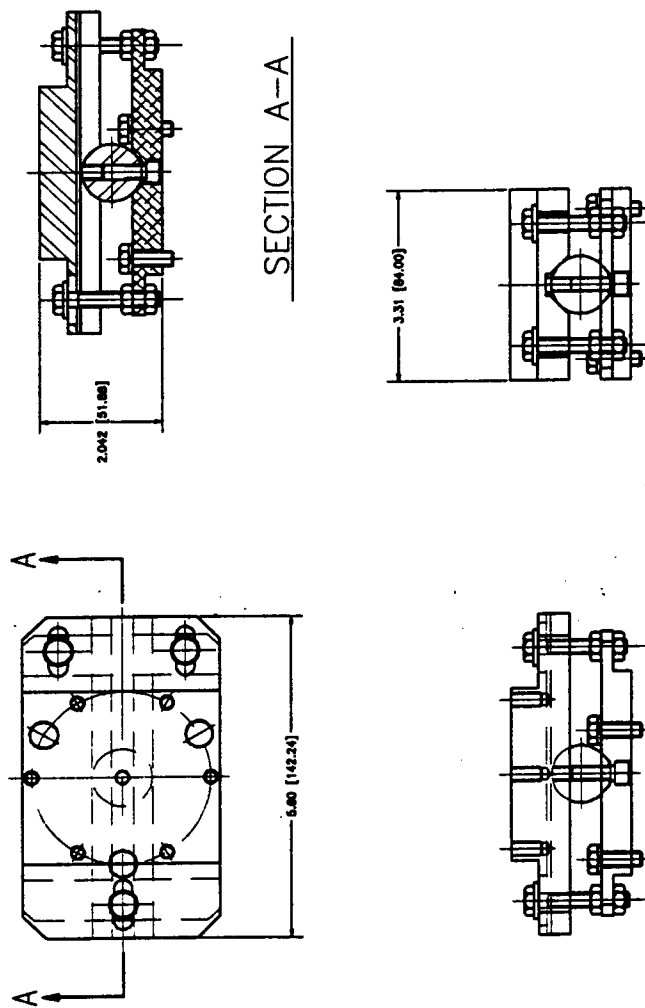


Figure 33 STANDARD KINEMATIC MOUNT V COUPLING

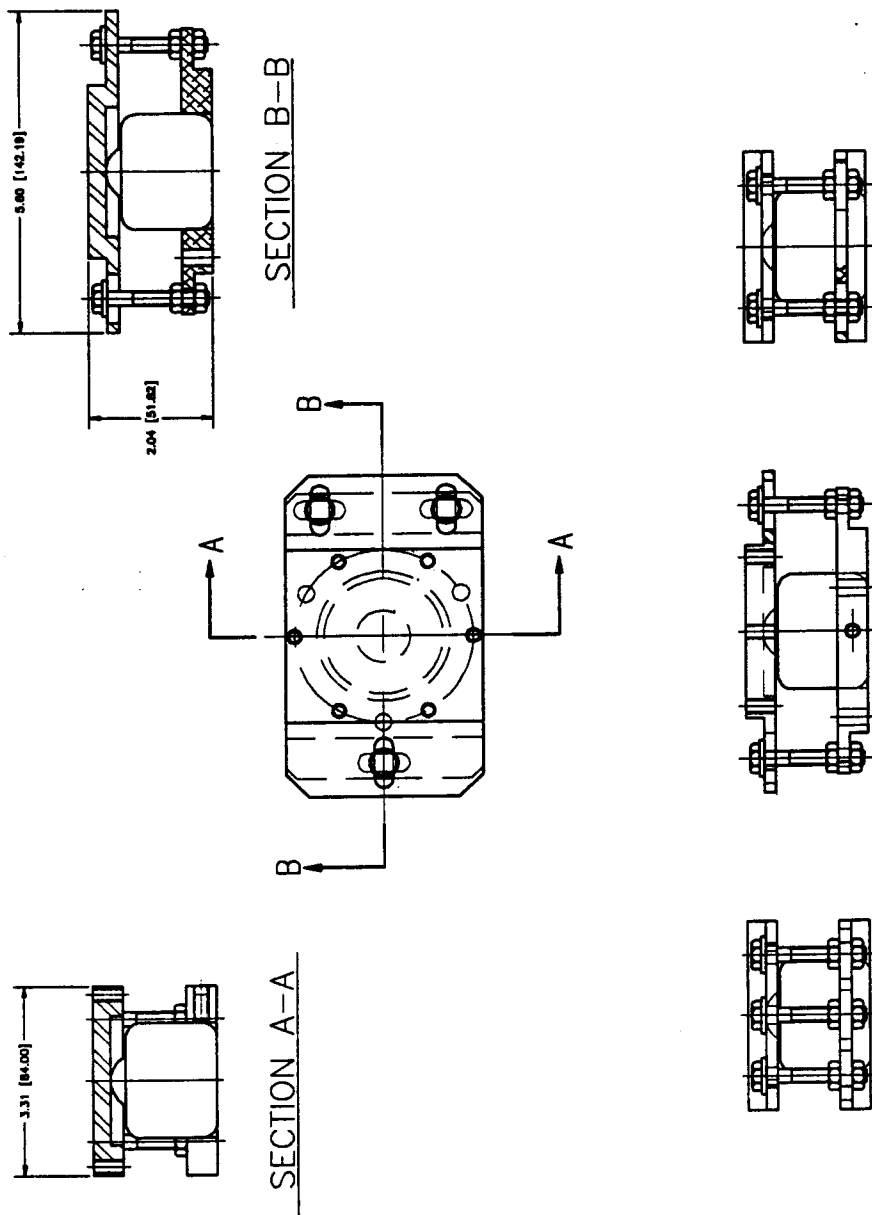


Figure 34 STANDARD KINEMATIC MOUNT FLAT COUPLING

PRECISION SUPPORT TABLE SPECIFICATIONS

Max. Load (Kg)	1000
Slide Type (V)	Linear Rolling
Slide Type (H)	Linear Rolling
Travel Range (V) (H) (mm)	12.7
Motion (V) Resolution (um)	10
Motion (H) Resolution (um)	10
Motion (V) Repeatability (um)	50
Motion (H) Repeatability (um)	50
(V) Straightness of Trajectory (rad/5mm)	2 E -4
(H) Straightness of Trajectory (rad/5mm)	1 E -4
Basic Operating Mode	Stepping Motor
Optional Operating Mode	Manual

- SPECIFICATIONS:
1. LOAD CAPACITY: 2200 LBS [1000 kg]
 2. TRAVEL RANGE: ± 0.25 [6.35]
 3. DEGREES OF FREEDOM: 5
 4. REPEATABILITY: $50 \mu\text{m}$
 5. RESOLUTION: $10 \mu\text{m}$
 6. HORIZONTAL AND VERTICAL ADJUSTMENT: STEPPER MOTOR

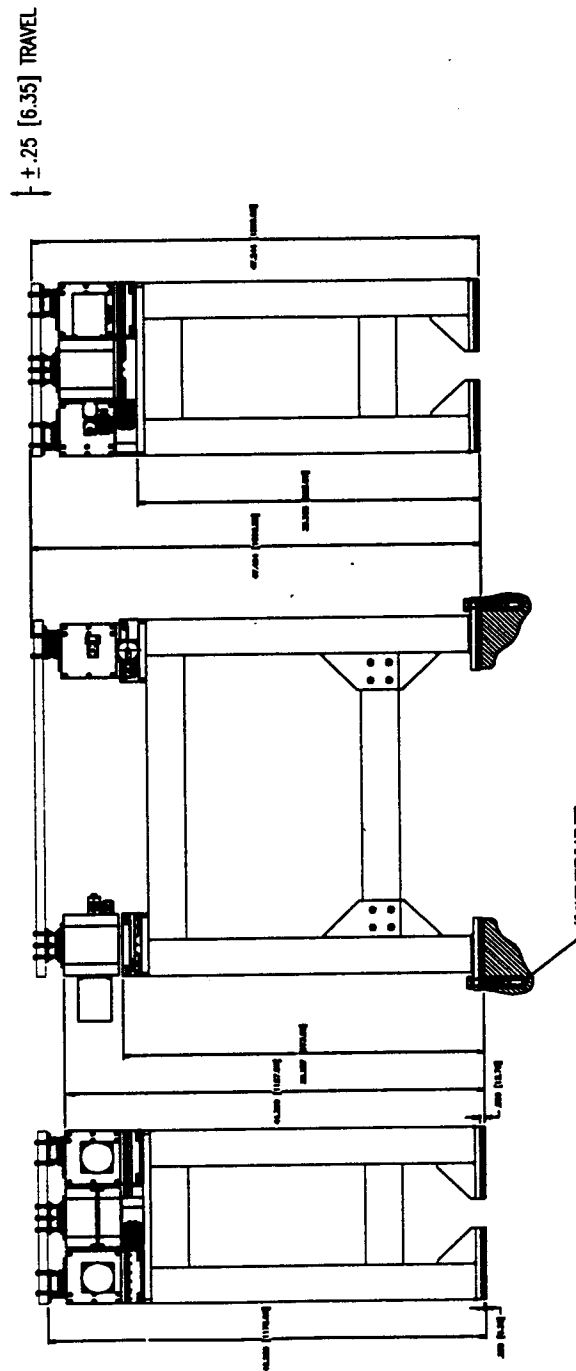
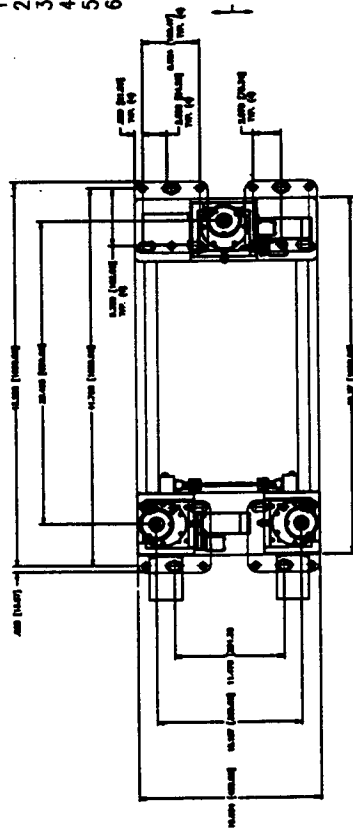
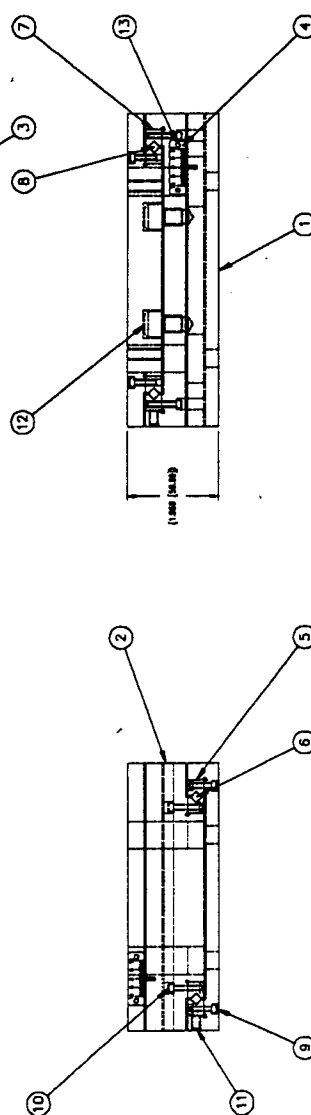
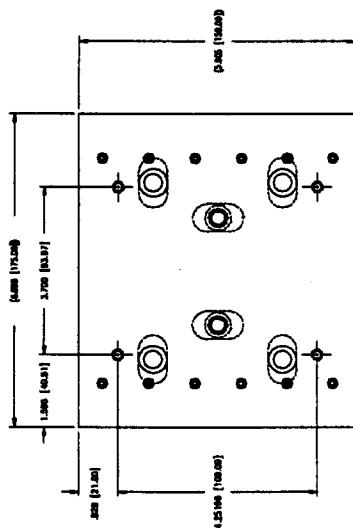


Figure 35 SUPPORT BASE WITH PRECISION KINEMATIC MOUNT STAGES

1. ITEM NO.'S ④ & ⑬ ARE TO BE MOUNTED IN AREAS SHOWN. DRILL (4) Ø .042 HOLES X .25 DEEP.
2. ALL DIMENSIONS SHOWN IN [] ARE MILLIMETERS
3. SOME HIDDEN LINES OMITTED FOR CLARITY.



TECHNICAL SPECIFICATIONS:

1. PRIOR TO ASSEMBLY, ALL MACHINED PARTS MUST BE FREE OF GREASE, OIL, DUST, LINT AND ALL FOREIGN MATTER. SPECIAL ATTENTION SHOULD BE PAID TO THE BEARING SURFACES.
2. PRIOR TO FITTING, ALL LINEAR BEARINGS MUST BE WASHED WITH A CLEANSING AGENT THEN OILED LIGHTLY.

1. FIT BEARING NAILS INTO THEIR BASE AND SECURE LIGHTLY WITH SCREWS.
2. INSERT ROLLER CAGES AND CENTER ALONG BEARING NAILS.
3. ADJUST PRELOAD BAR USING SET SCREWS UNTIL PLAY FREE, THEN PRELOAD EACH SET SCREW TO APPROX. 10-20 LB. TIGHTEN TO APPROX. 110-115.
4. SECURE SCREWS ON BEARING NAILS THOROUGHLY USING A

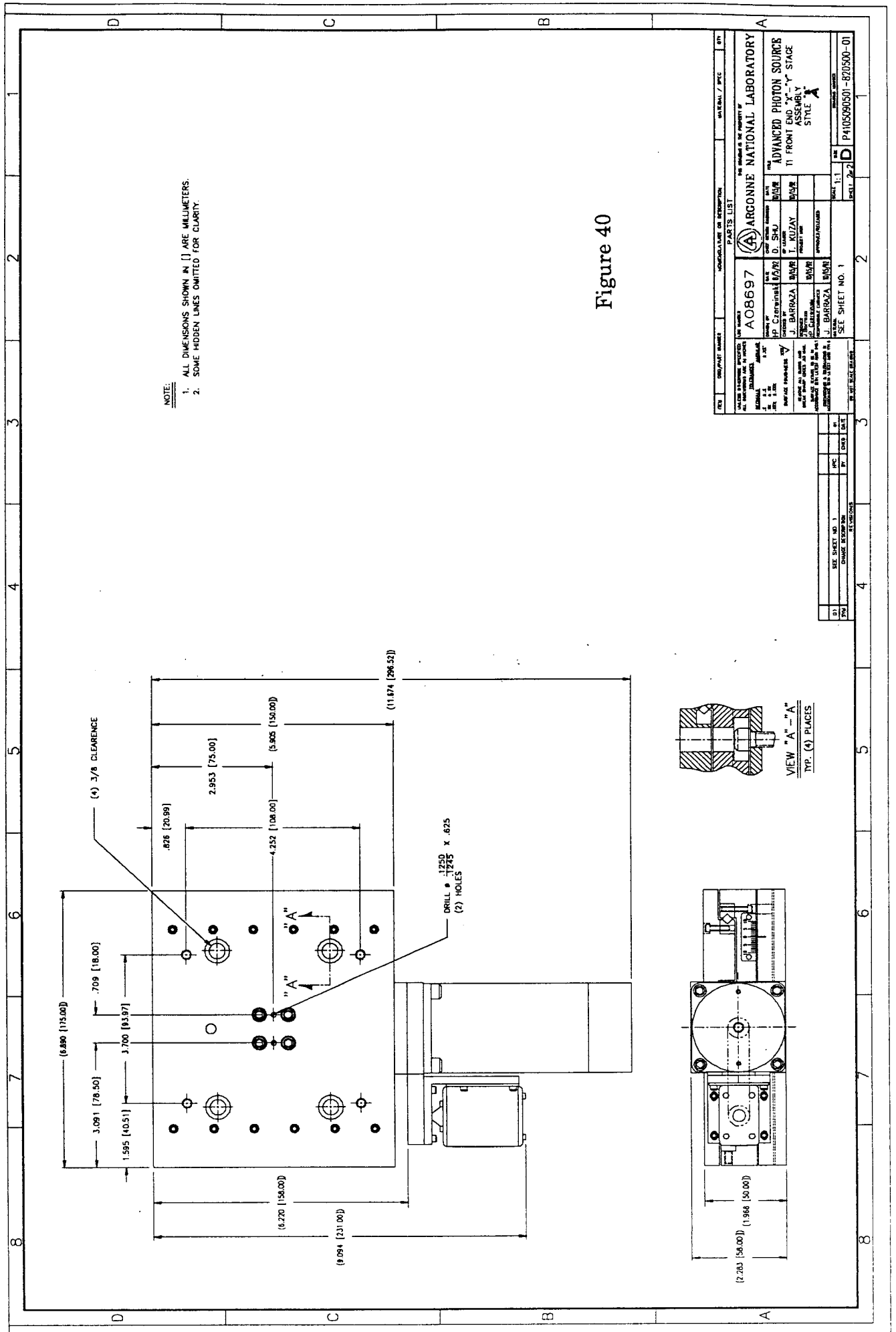
A SPECIFICATIONS:

- 1. LOAD CAPACITY:** 1000 LBS. (454 kg).

13	Ø 3 x 25 LL TYPE "U" DRIVE SCREW	304 STL.	4
12	7/8"-26UNC-2A x 48 LL CAP SCREW	304 STL.	4
11	7/8"-26UNC-2A x 36 LL CAP SCREW	304 STL.	4
10	7/8"-26UNC-2A x 36 LL SET SCREW	304 STL.	12
9	3/4" x 10mm LL CAP SCREW	304 STL.	20
8	3/4" x 10mm LL CAP SCREW	304 STL.	20
7	3/4" x 10mm LL CAP SCREW	"NO-MEETING" NO	2
6	3/4" x 10mm LL CAP SCREW	"NO-MEETING" NO	2
5	3/4" x 10mm LL CAP SCREW	"NO-MEETING" NO	2
4	3/4" x 10mm LL CAP SCREW	"NO-MEETING" NO	2
3	3/4" x 10mm LL CAP SCREW	"NO-MEETING" NO	2
2	3/4" x 10mm LL CAP SCREW	"NO-MEETING" NO	2
1	3/4" x 10mm LL CAP SCREW	"NO-MEETING" NO	2

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
1. NAME OF THE COMPANY 2. ADDRESS 3. CITY 4. STATE 5. ZIP CODE 6. PHONE NO. 7. FAX NO. 8. E-MAIL ADDRESS 9. WEBSITE ADDRESS 10. OTHER INFORMATION										11. NAME OF THE PRODUCT 12. DESCRIPTION 13. SPECIFICATIONS 14. MATERIALS 15. MANUFACTURING PROCESS 16. TESTING METHODS 17. QUALITY CONTROL 18. PACKAGING 19. STORAGE 20. DISTRIBUTION										21. NAME OF THE CUSTOMER 22. ADDRESS 23. CITY 24. STATE 25. ZIP CODE 26. PHONE NO. 27. FAX NO. 28. E-MAIL ADDRESS 29. WEBSITE ADDRESS 30. OTHER INFORMATION										31. NAME OF THE SUPPLIER 32. ADDRESS 33. CITY 34. STATE 35. ZIP CODE 36. PHONE NO. 37. FAX NO. 38. E-MAIL ADDRESS 39. WEBSITE ADDRESS 40. OTHER INFORMATION										41. NAME OF THE DISTRIBUTOR 42. ADDRESS 43. CITY 44. STATE 45. ZIP CODE 46. PHONE NO. 47. FAX NO. 48. E-MAIL ADDRESS 49. WEBSITE ADDRESS 50. OTHER INFORMATION										51. NAME OF THE END USER 52. ADDRESS 53. CITY 54. STATE 55. ZIP CODE 56. PHONE NO. 57. FAX NO. 58. E-MAIL ADDRESS 59. WEBSITE ADDRESS 60. OTHER INFORMATION										61. NAME OF THE PROJECT 62. DESCRIPTION 63. SPECIFICATIONS 64. MATERIALS 65. MANUFACTURING PROCESS 66. TESTING METHODS 67. QUALITY CONTROL 68. PACKAGING 69. STORAGE 70. DISTRIBUTION										71. NAME OF THE CONTRACTOR 72. ADDRESS 73. CITY 74. STATE 75. ZIP CODE 76. PHONE NO. 77. FAX NO. 78. E-MAIL ADDRESS 79. WEBSITE ADDRESS 80. OTHER INFORMATION										81. NAME OF THE ARCHITECT 82. ADDRESS 83. CITY 84. STATE 85. ZIP CODE 86. PHONE NO. 87. FAX NO. 88. E-MAIL ADDRESS 89. WEBSITE ADDRESS 90. OTHER INFORMATION										91. NAME OF THE ENGINEER 92. ADDRESS 93. CITY 94. STATE 95. ZIP CODE 96. PHONE NO. 97. FAX NO. 98. E-MAIL ADDRESS 99. WEBSITE ADDRESS 100. OTHER INFORMATION									

Figure 39



FE PBPM SUPPORT TABLE SPECIFICATIONS

Max. Load (Kg)	90
Slide Type (V)	Linear Rolling
Slide Type (H)	Linear Rolling
Travel Range (V) (H) (mm)	12.7
Motion (V) Resolution (um)	0.1
Motion (H) Resolution (um)	0.1
Motion (V) Repeatability (um)	2
Motion (H) Repeatability (um)	2
(V) Straightness of Trajectory (rad/5mm)	1 E -5
(H) Straightness of Trajectory (rad/5mm)	1 E -5
Basic Operating Mode	Stepping Motor
Optional Operating Mode	Manual

PATENT HOLD

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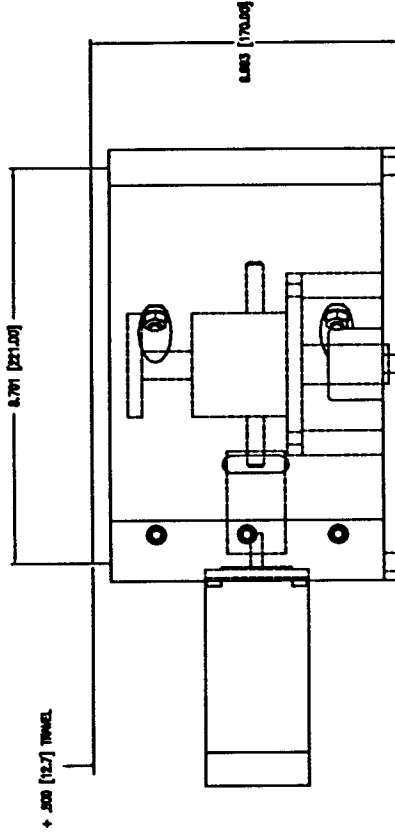
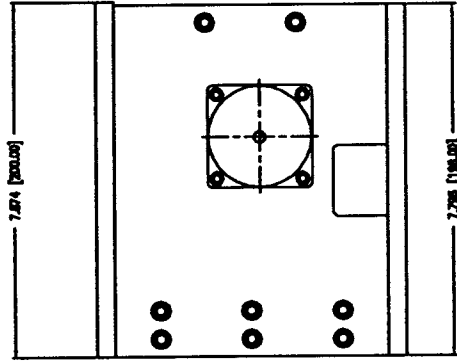
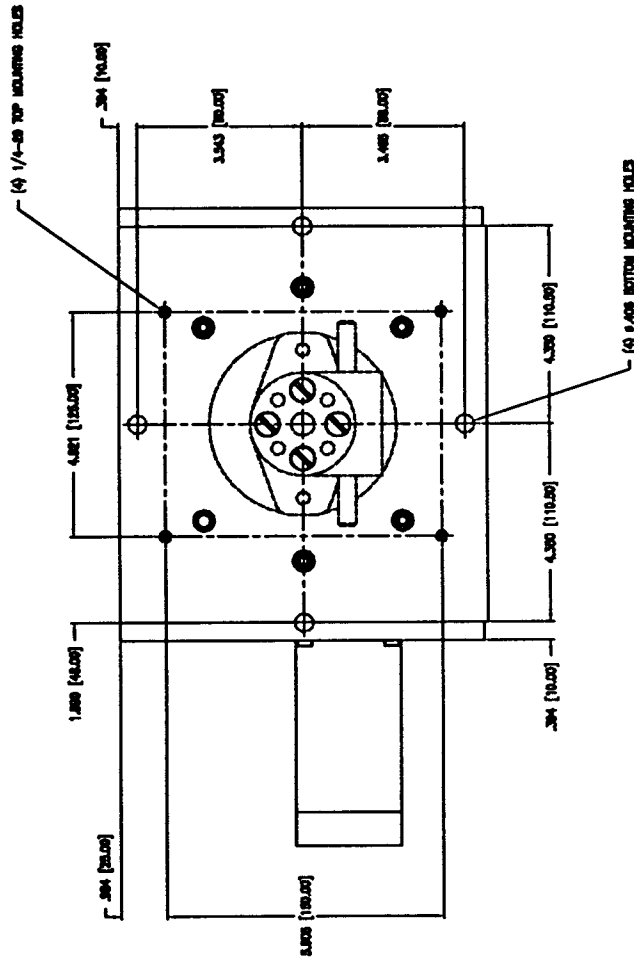
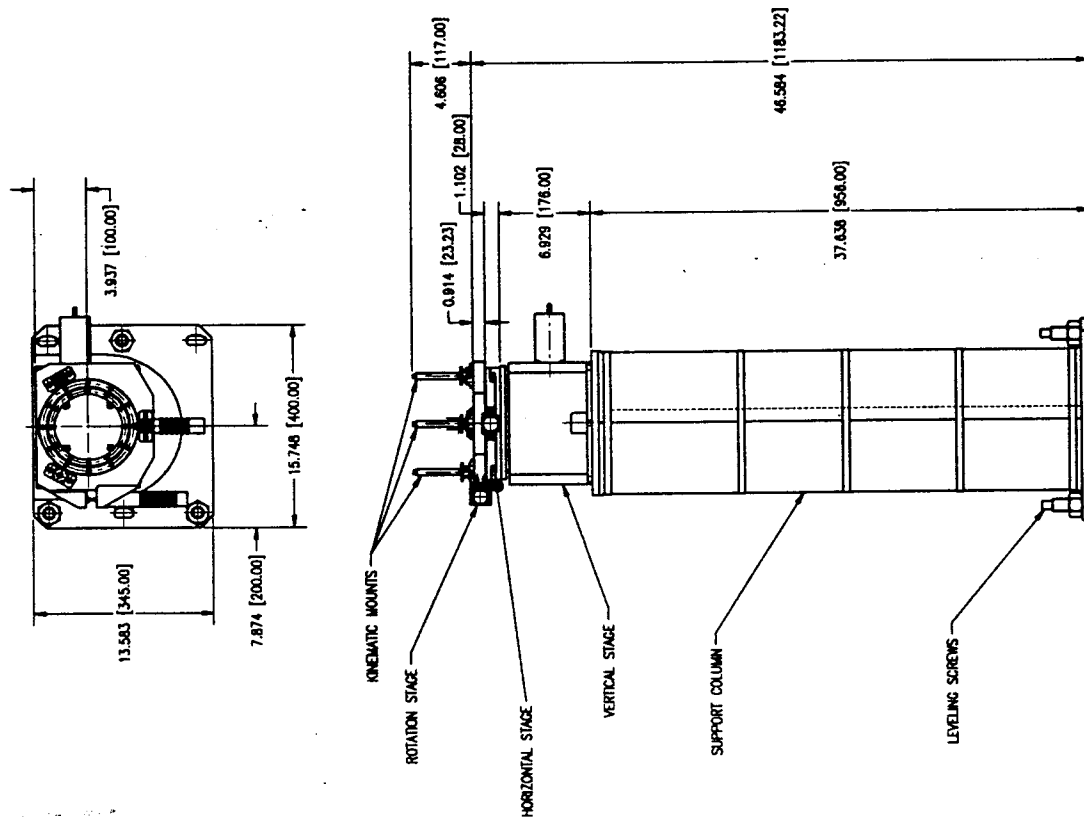


Figure 41 PBPM VERTICAL STAGE ASSEMBLY



SPECIFICATIONS:

1. LOAD CAPACITY: 90 kg
2. TRAVEL RANGE: ± 5 mm
3. RESOLUTION: $0.1 - 0.5 \mu\text{m}$
4. REPEATABILITY: VERTICAL: $\pm 2 \mu\text{m}$
HORIZONTAL: $\pm 5 \mu\text{m}$
5. ANGULAR RESOLUTION: 5 ARCSECONDS
6. STRAIGHTNESS OF TRAJECTORY: 1×10^{-5} RAD/25 mm

Figure 42 PBPM SUPPORT TABLE ASSEMBLY

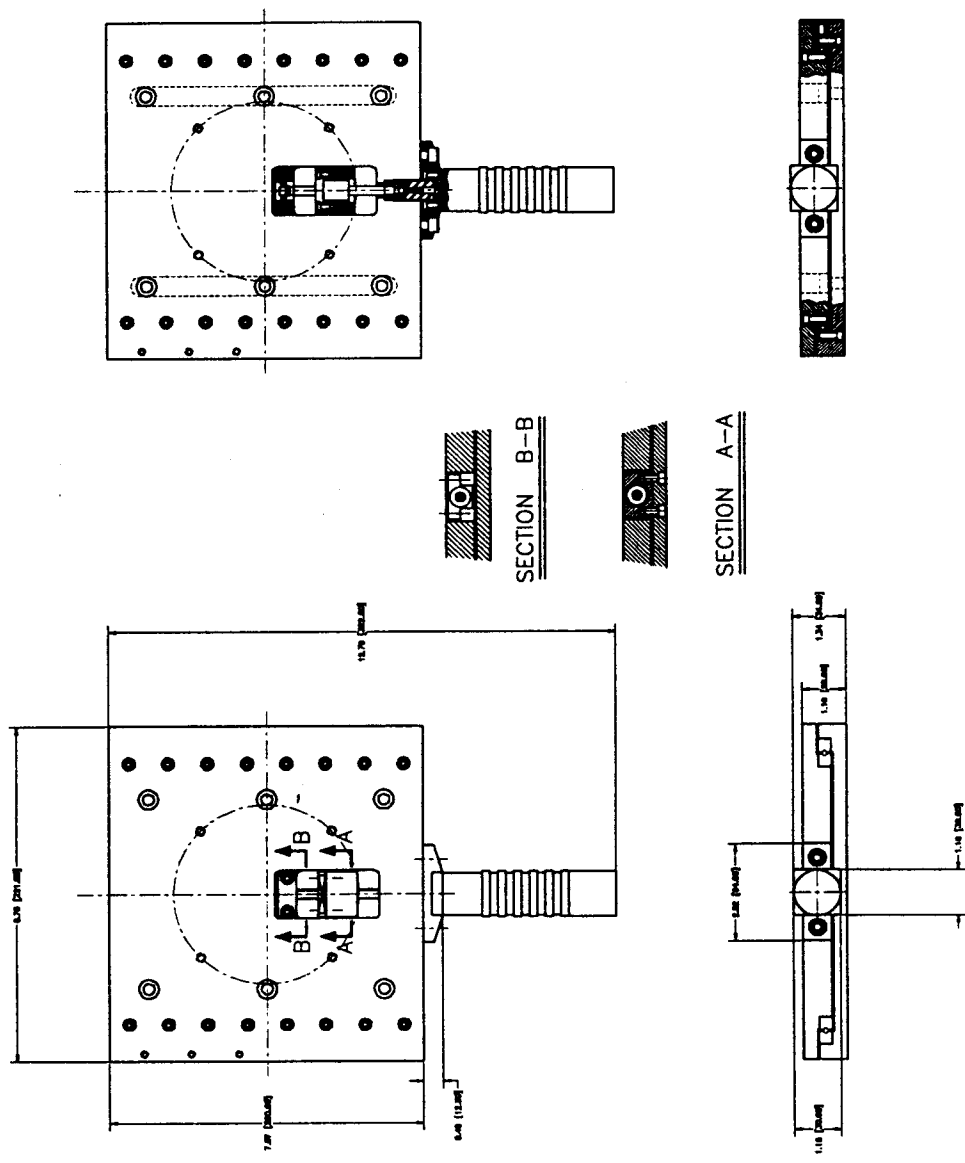


Figure 43 PBPM HORIZONTAL STAGE ASSEMBLY

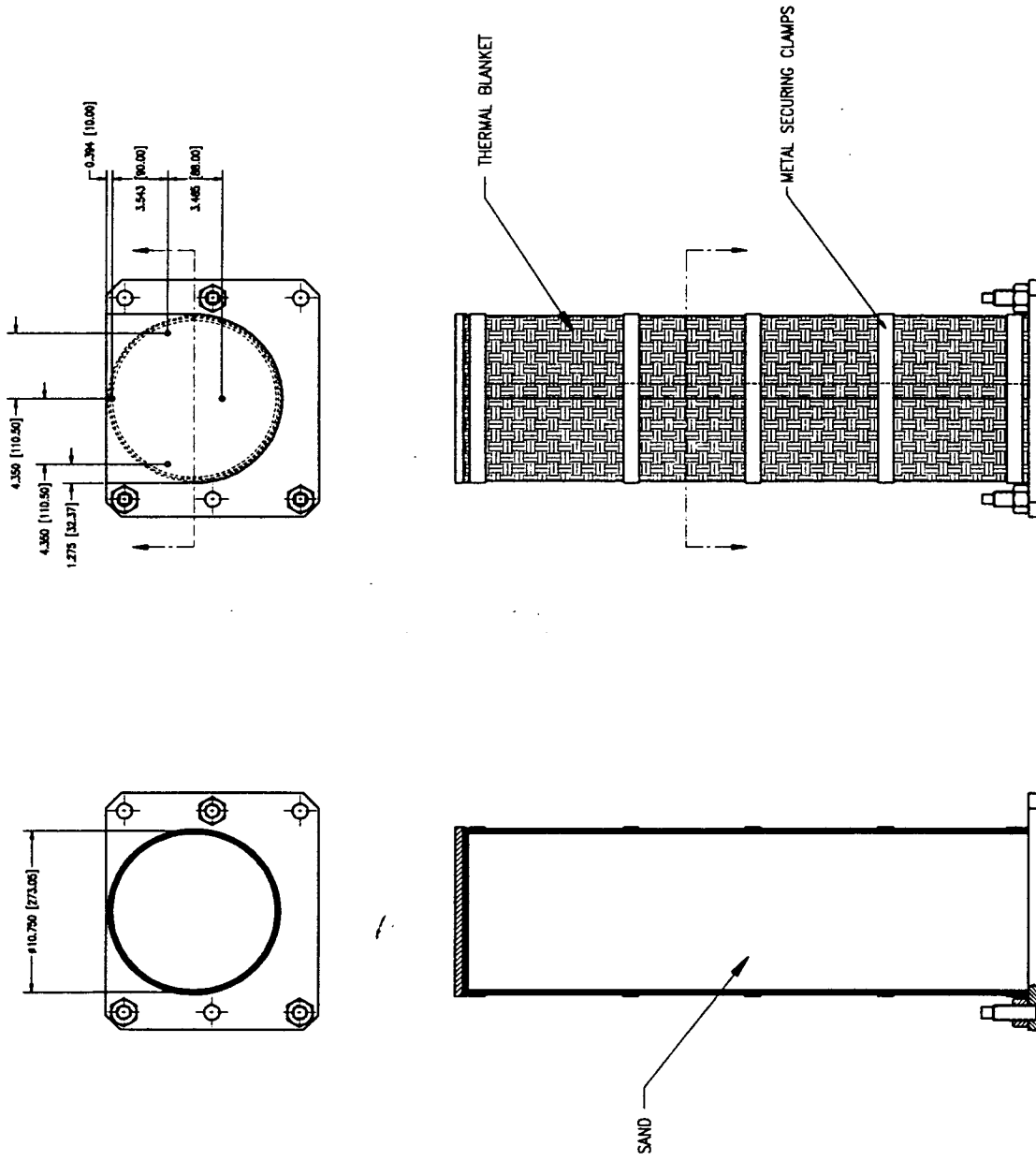
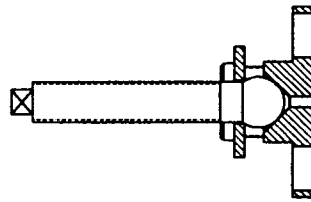
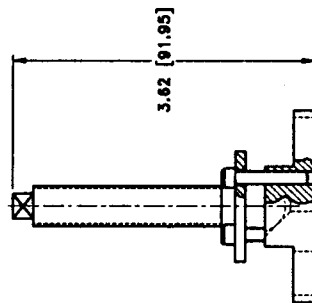
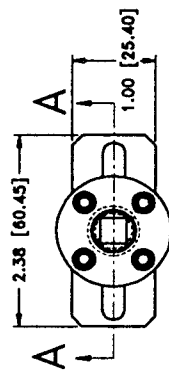


Figure 45 PBPM SUPPORT COLUMN ASSEMBLY



SECTION A-A

Figure 46 PBPM KINEMATIC MOUNT CONE ASSEMBLY

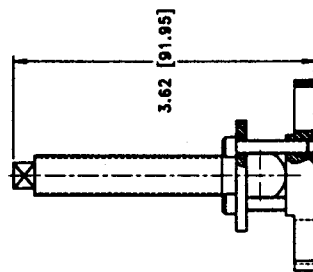
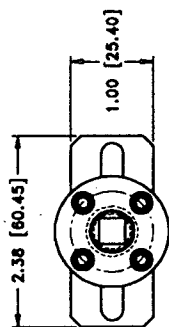


Figure 47 PBPM KINEMATIC MOUNT FLAT ASSEMBLY

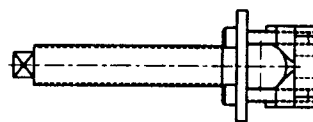
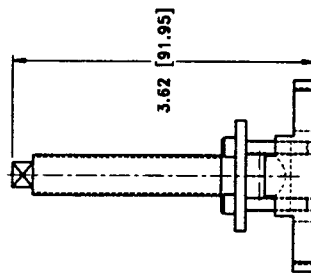
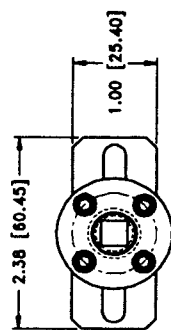


Figure 48 PBPM KINEMATIC MOUNT V ASSEMBLY

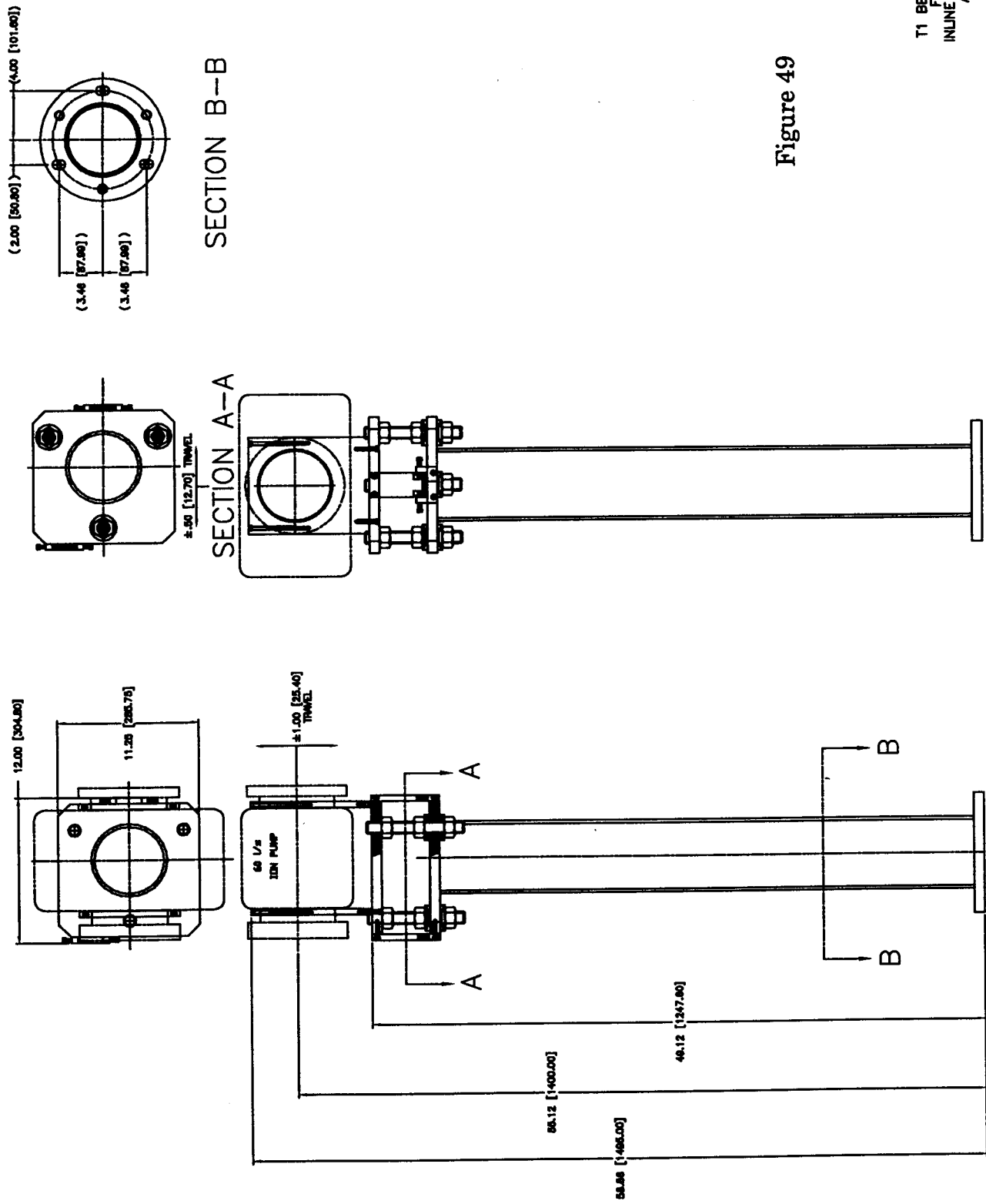


Figure 49

T1 BENDING MAGNET
FRONT END
INLINE ION PUMP SUPP
ASSEMBLY

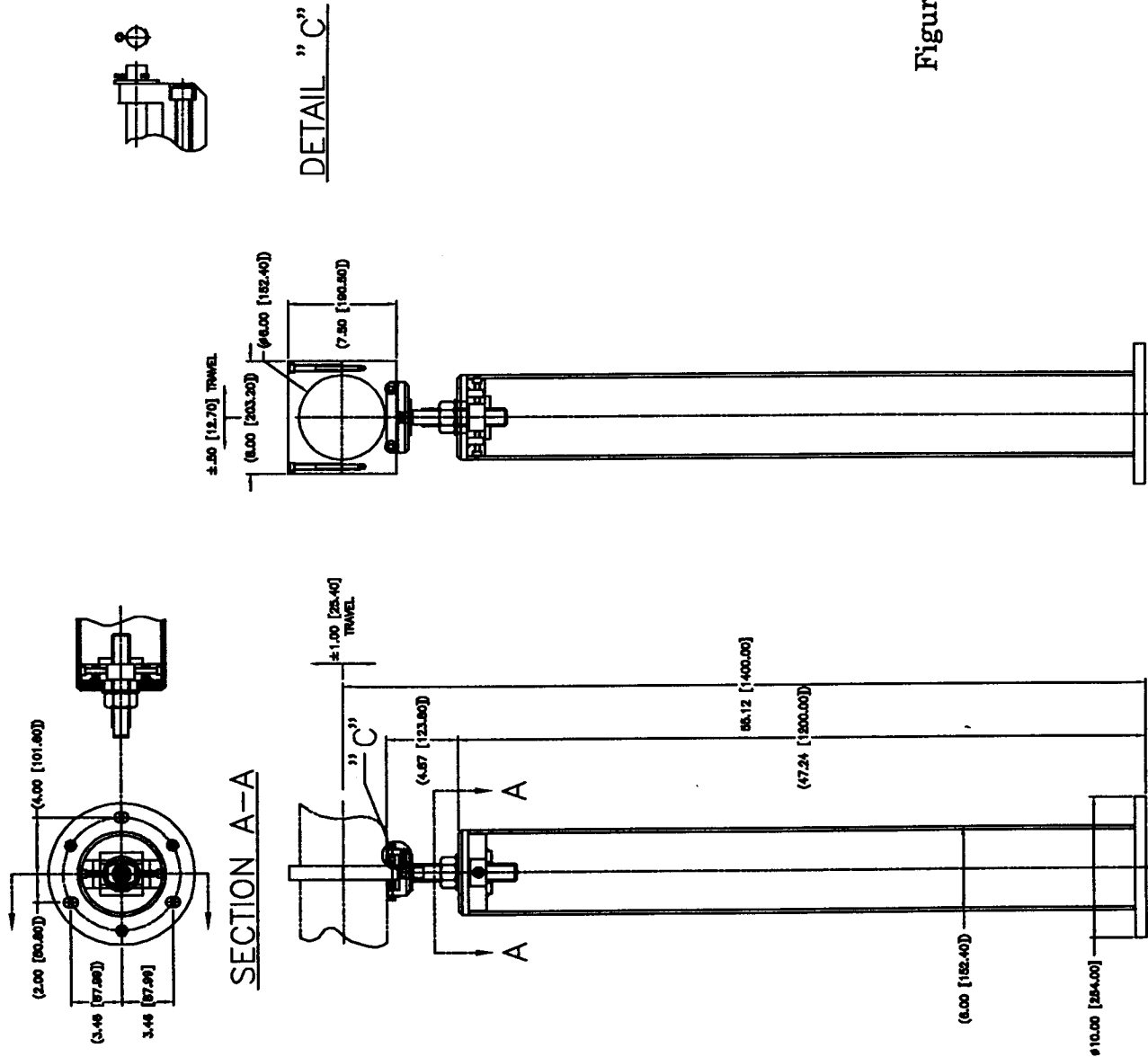


Figure 50

T1 BENDING MAGNET
FRONT END
BEAM PIPE SUPPORT
ASSEMBLY

10. Stepping Motor Drives

- 10.1. Stepping motors (being developed)
- 10.2. Drivers/Controllers (being developed)

Design Status

The APS user organization has appointed a subcommittee to advise the APS in developing standard recommendations for stepping motors, drivers, and controllers. It is expected that the committee will provide their recommendation before the end of 1993 by working closely with the APS. The standardisation is also closely linked to anew software development work at the APS that uses Experimental Physics Interface Control System (EPICS).

As a starting point, the APS has used the stepping motor/drivers specified in section 10.1 - 10.2, which are used in all standard supports (section 9).

10.1. - 10.2. Stepping Motors - Drivers/Controllers

- Standardize stepping motor drives and controllers
- Control for multi-motor driven systems
- Open and/or closed loop control
- Acceleration and deceleration control
- Power fail-safe control with battery backup coordinate memory

The APS stepping motor driver/controller is designed to provide a user friendly control environment for multi-motor driven systems such as kinematic mounting tables or beamline slits. Control is to be either manual or through computer control.

Specifications:

- Stepping motor: four phase, 400 half steps/rev, 3% accuracy
M063-LE06-E: 3.36 V DC, 2.9 A
M093-FD8107-E: 4.3V, 3.5A
- Maximum stepping rate: 40000 half steps/sec
- Able to interface with computer
- Position display: seven digit and sign with computer conversion
- Feedback: open and/or closed loop with TTL incremental encoder signals
- Memory backup: battery backup nonvolatile memory of control data
- Power fail safe
- Switch status information to host: open or closed of limits or home
- Connectors (to be standardized)
- Cables (to be standardized)

11. Interlock - Interfaces

11.1. Switches

11.2. Solenoids

11.3. Interfaces - cables and connectors

11.3.1. Ion pumps with power supplies

11.3.2. Ion gauges with power supplies

11.3.3. Vacuum valves

Design Status

Work will be completed by the end of 1993.

12. Actuators

- 12.1. Heavy load with stepping motor drive
- 12.2. Heavy load with pneumatic drive
- 12.3. Light load with stepping motor drive
- 12.4. Light load with pneumatic drive

Design Status

The design work on all the actuators is in advanced stage, and prototypes will be built and tested in 1993. The following sections include various design specifications.

12.1. APS Heavy Load Actuator with Stepping Motor Drive

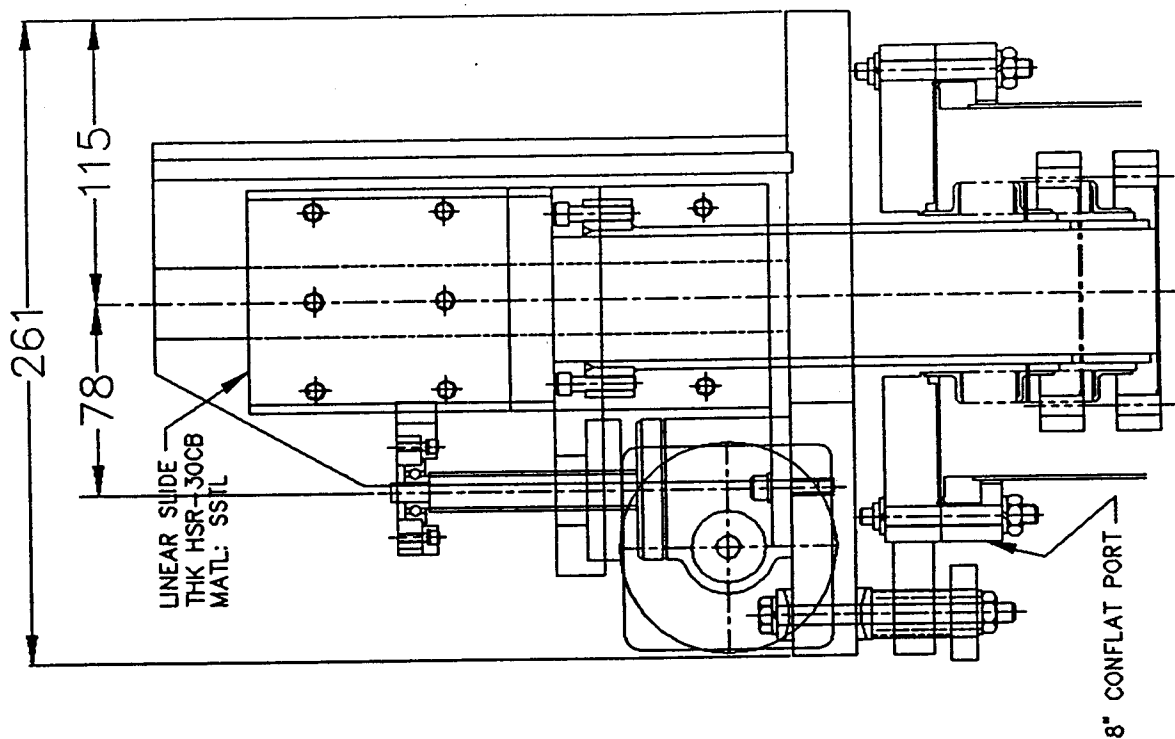
**SLAH-30-8, SLAH-75-8
(A2-81) (A2-82)**

- Heavy load actuators
- For use with APS ID white beam slits
- Stepping motor driven with shaft encoder

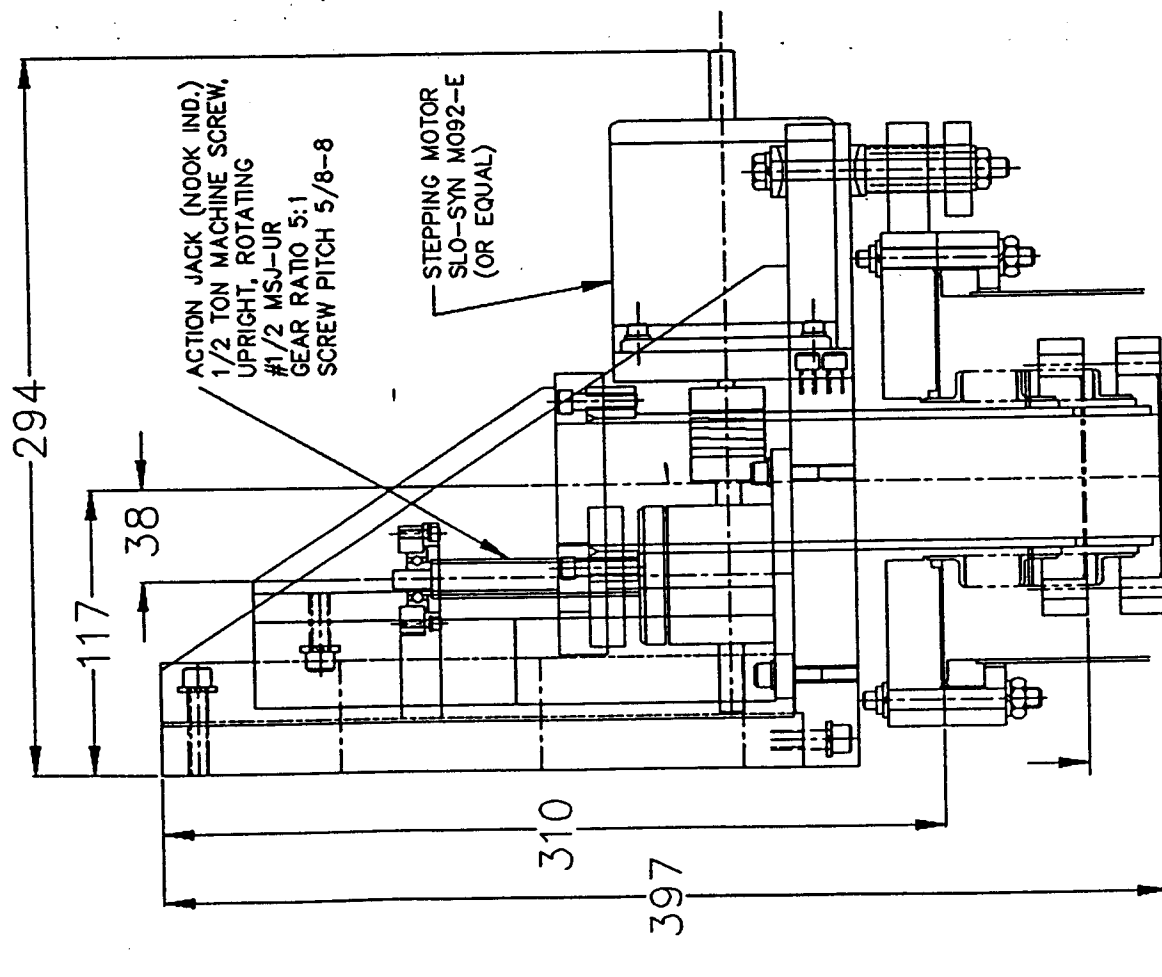
A typical application for these actuators is to drive APS ID white beam slits. There are three different ranges of travel designed.

Specifications:

- Slide type:	Linear rolling
- Travel ranges:	30 & 75 mm
- Motion resolution:	2 μ m
- Motion reproducibility:	5 μ m
- Straightness:	2×10^{-4} rad/25 mm
- Vacuum load:	38 kg
- Maximum useful axial load:	100 kg
- Stepping motor:	Slo-Syn M092-LE06
- Actuator flange O. D.:	8 inch
- Feedthrough flange O. D.:	4.5 inch
- Maximum feedthrough diameter:	50 mm
- Redundant limit switches	
-Encoder:	Optical on motor shaft and/or linear on slide
-Maximum speed:	20 mm/min
-Vacuum:	UHV compatible



APS HEAVY LOAD STEPPING LINEAR ACTUATOR
SLAH-30-8
SIDE VIEW
1/20/93
C. BRITE



APS HEAVY LOAD STEPPING LINEAR ACTUATOR
SLAH-30-8
ELEVATION
1/20/93
C. BRITE

Figure 51

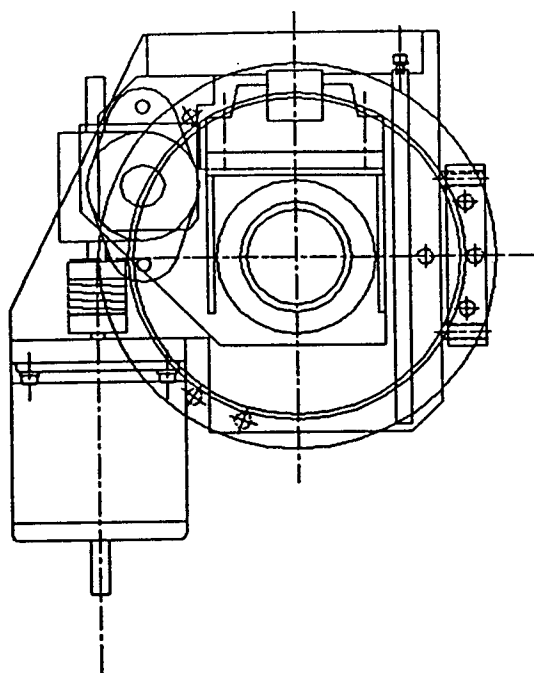
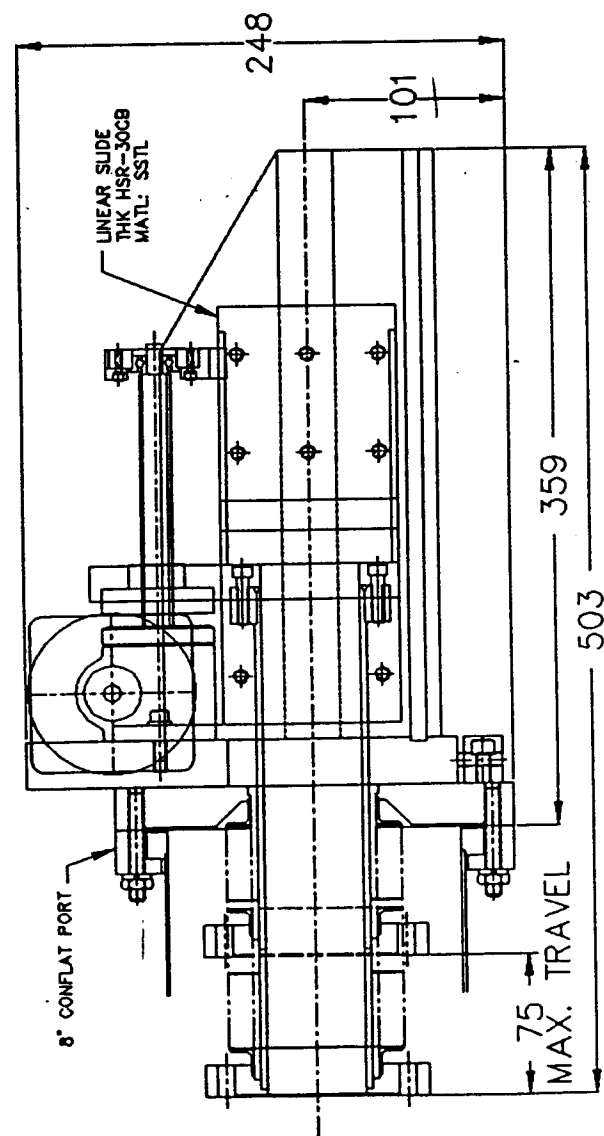
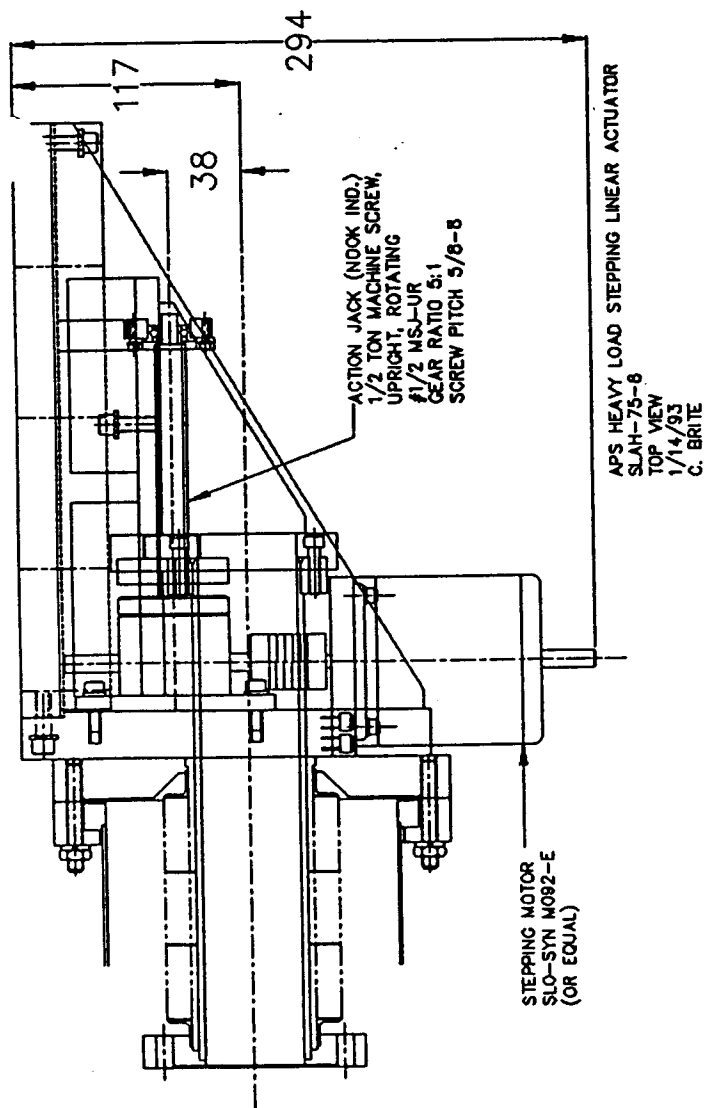


Figure 52

12.2. APS Heavy Load Actuator with Pneumatic Drive

PLAH-33-10

- Heavy load actuators
- For use with APS ID and BM front end and beamline safety shutters

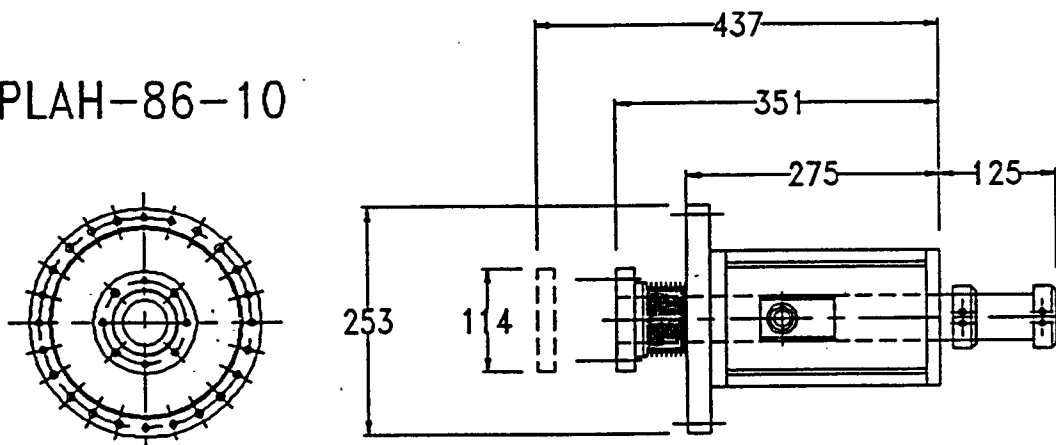
A typical application for the heavy load pneumatic actuators is to drive APS safety shutters.

Specifications:

- Stroke:	33 mm \pm 0.25 mm
- Motion repeatability:	0.5 mm \pm 0.1 mm
- Total axial load:	190 kg
- Vacuum load:	40 kg
- Maximum useful axial load:	70 kg
- Chamber flange O. D.:	8 inch
- Rod flange O. D.:	4.5 inch
- Redundant limit switches in each end position	Micro switch BZZRQ2X-A2
- Pneumatic power supply:	90 - 120 psi
- Maximum closing time:	0.5 - 1 sec
- Pneumatic damping:	in each end position
- Life time:	500k cycles
- Vacuum:	UHV compatible

APS HEAVY LOAD PNEUMATIC LINEAR ACTUATOR

PLAH-86-10

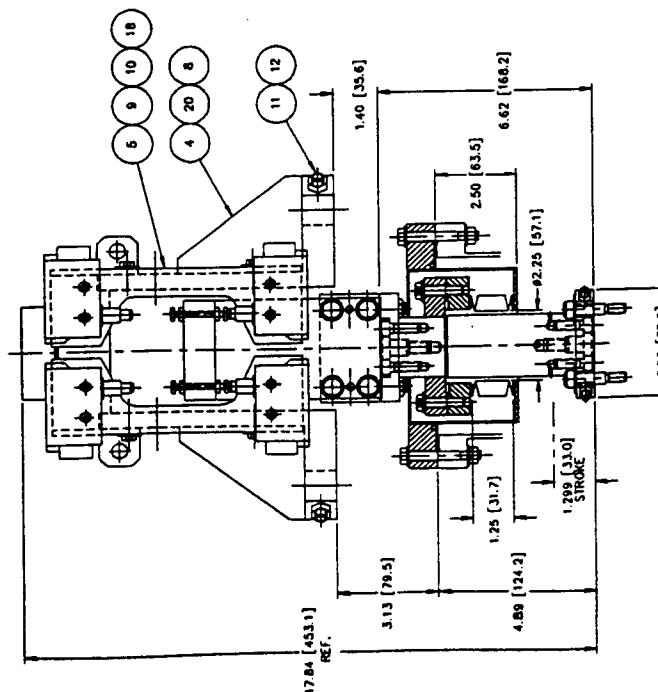
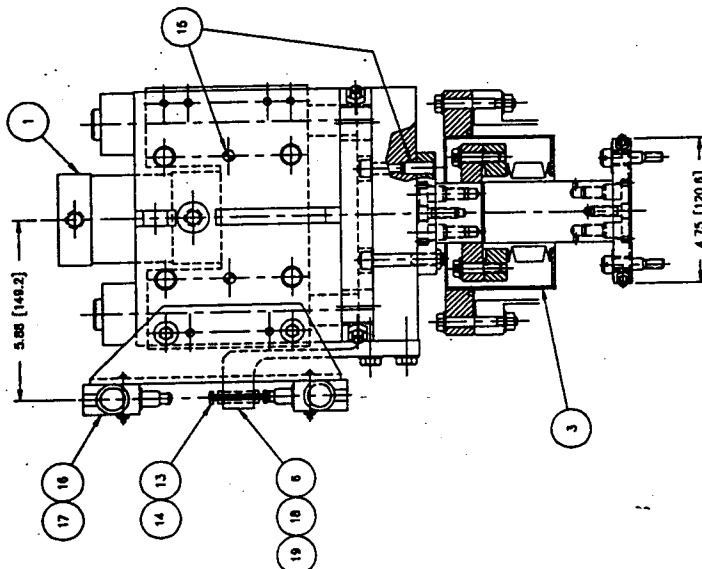
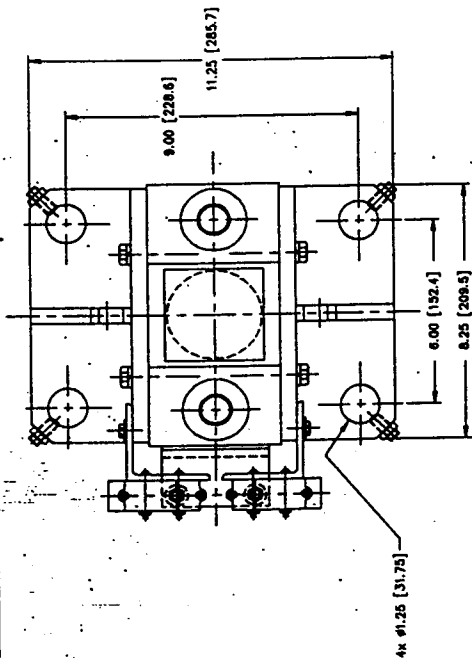


PLAH.DWG 01-18-92

Figure 53

SPECIFICATIONS

STROKE: 33 mm
 MOTION REPEATABILITY: 0.5 mm
 TOTAL AXIAL LOAD: 220 kg
 VACUUM LOAD: 40 kg
 MINIMUM USEFUL AXIAL LOAD: 150 kg
 CHAMBER FLANGE O.D.: 9 in.
 ROD FLANGE O.D.: 4.5 in.
 REDUNDANT LIMIT SWITCHES: 20 EACH END POSITION
 PNEUMATIC LOWER SUPPLY: 80-120 psi
 PNEUMATIC COILS: 0.5 - 1 in.
 PNEUMATIC DAMPING: 500K cycles
 LIFE TIME: UNV COMPATIBLE
 VACUUM: UNV COMPATIBLE



- NOTES:
- THIS IS A UNV ASSEMBLY. KEEP THE UNV PARTS CLEAN DURING ASSEMBLY AND WRAP UP FOR UNV PACKING WITH ALUMINUM FOIL.
 - DEVICE SHALL BE LEAK TESTED USING A MASS SPECTROMETER WITH MINIMUM SENSITIVITY FOR HELIUM OF 2X 10⁻¹⁰ STANDARD CC/SEC PER LEAK METER DIVISION, SUCH AS:
 - ALCATEL ASM-110TCL
 - VARIAN NGR 925 OR 936
 - VEECO MS-8, MS-90 OR MS-18
 - DU PONT CEC 24-1208
- CALIBRATION OF THE LEAK DETECTOR SENSITIVITY SHALL BE PERFORMED JUST PRIOR TO TESTING.
- FINAL TEST WILL CONSIST OF SURROUNDING THE CHAMBER (BAGGING) WITH HELIUM. THE CHAMBER WILL BE REJECTED IF A 2X DEFLECTION IN THE MOST SENSITIVE RANGE OF THE LEAK DETECTOR IS SENSED WITHIN 1 MIN.
3. ALL DIMENSIONS WITH [] ARE MILLIMETERS

REFERENCE SOURCE:
 1. MICRO SWITCH
 821 - ROUTE 83
 BENSenville, IL 60106
 PHONE: 860-3968

QTY	DESCRIPTION	QTY	DESCRIPTION	QTY	DESCRIPTION
20	3/8-16 UNC-1/2 LG HHCS DRILLED HD	8	SST		
18	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
17	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
16	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
15	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
14	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
13	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
12	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
11	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
10	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
9	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
8	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
7	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
6	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
5	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
4	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
3	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
2	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
1	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		

QTY	DESCRIPTION	QTY	DESCRIPTION	QTY	DESCRIPTION
20	3/8-16 UNC-1/2 LG HHCS DRILLED HD	8	SST		
18	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
17	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
16	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
15	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
14	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
13	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
12	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
11	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
10	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
9	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
8	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
7	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
6	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
5	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
4	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
3	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
2	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		
1	3/8-16 UNC-1/2 LG HHCS DRILLED HD	4	SST		

Figure 54

12.3. APS Light Load Actuator with Stepping Motor Drive

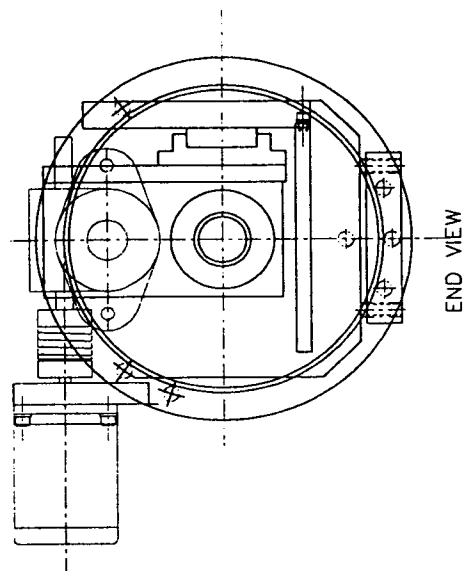
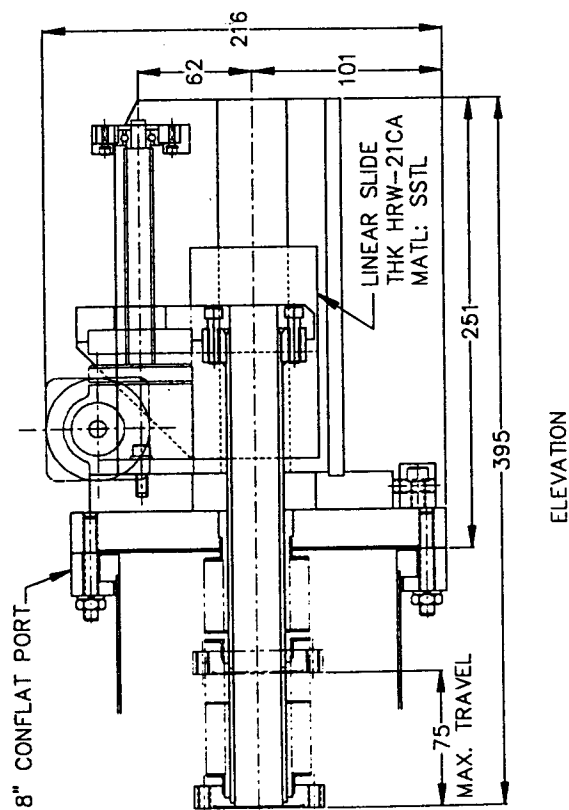
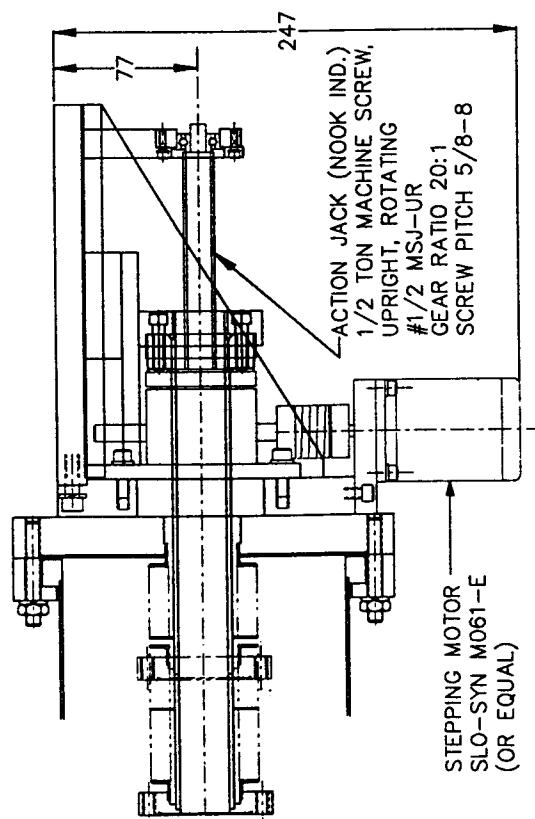
SLAL-30-8, SLAL-75-8, SLAL-150-8
(A1-81) (A1-82) (A1-83)

- Light load actuators
- For use with APS ID and BM monochromatic slits and BM white slits
- Stepping-motor driven with shaft encoder

A typical application for these actuators is to drive the APS monochromatic beam slits and BM white beam slits. There are three different ranges of travel designed.

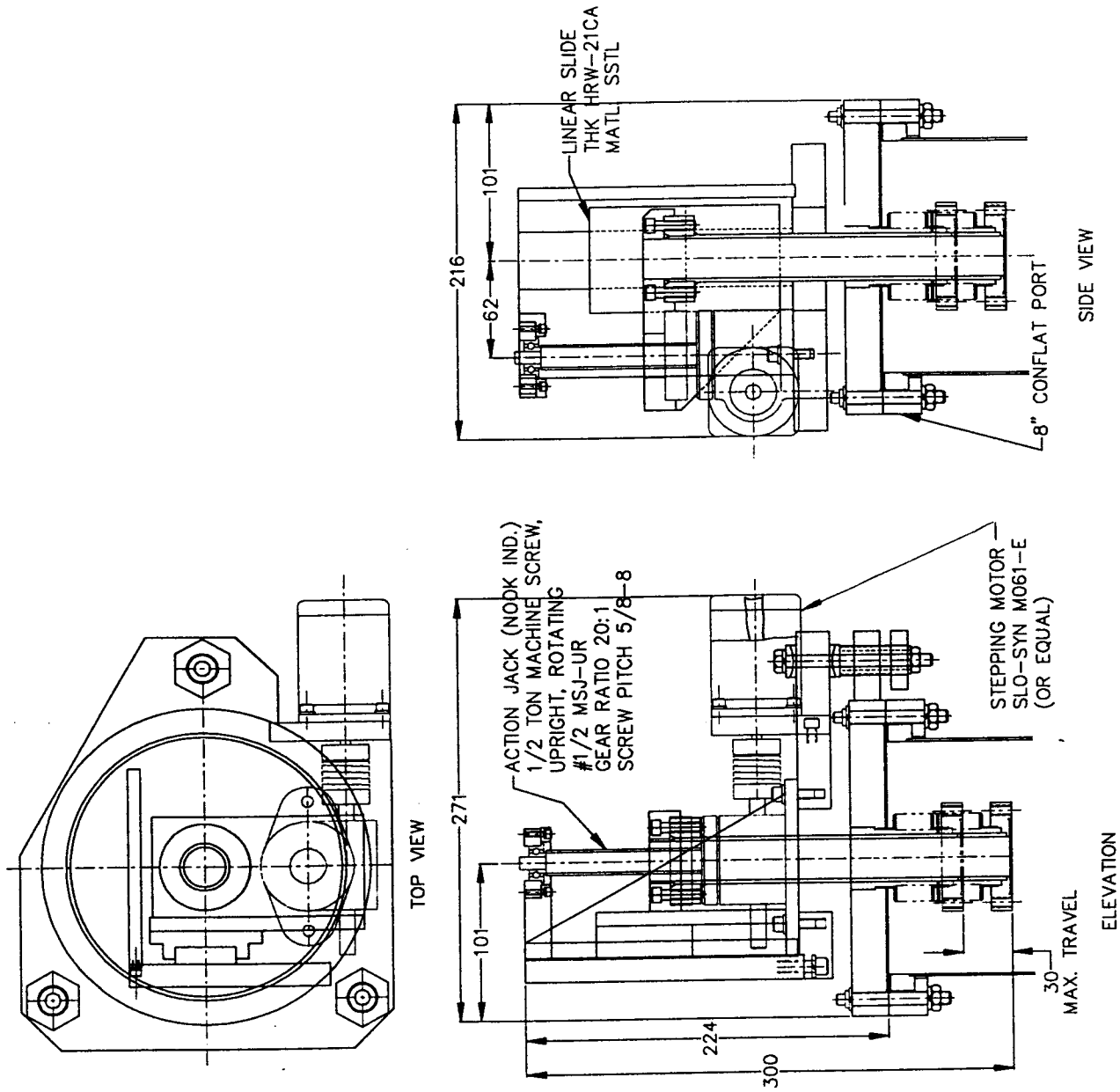
Specifications:

- Slide type:	Linear rolling
- Travel ranges:	30, 75, and 150 mm
- Motion resolution:	1 μ m
- Motion reproducibility:	5 μ m
- Straightness:	2×10^{-4} rad/25 mm
- Vacuum load:	19 kg
- Maximum useful axial load:	10 kg
- Stepping motor:	Slo-Syn M061-LE06
- Actuator flange O. D.:	8 inch
- Feedthrough flange O. D.:	2.75 inch
- Maximum feedthrough diameter:	25 mm
- Redundant limit switches	
-Encoder:	Optical on motor shaft and/or linear on slide
-Maximum speed:	50 mm/min
-Vacuum:	UHV compatible



APS LIGHT LOAD STEPPING LINEAR ACTUATOR
SLAL-75-8
1/26/93
C. BRITE

Figure 55



APS LIGHT LOAD STEPPING LINEAR ACTUATOR
 SLAL-30-8
 1/27/93
 C. BRITE

Figure 56

12.4. APS Light Load Pneumatic Actuator with Pneumatic Drive

A3-81, A3-83

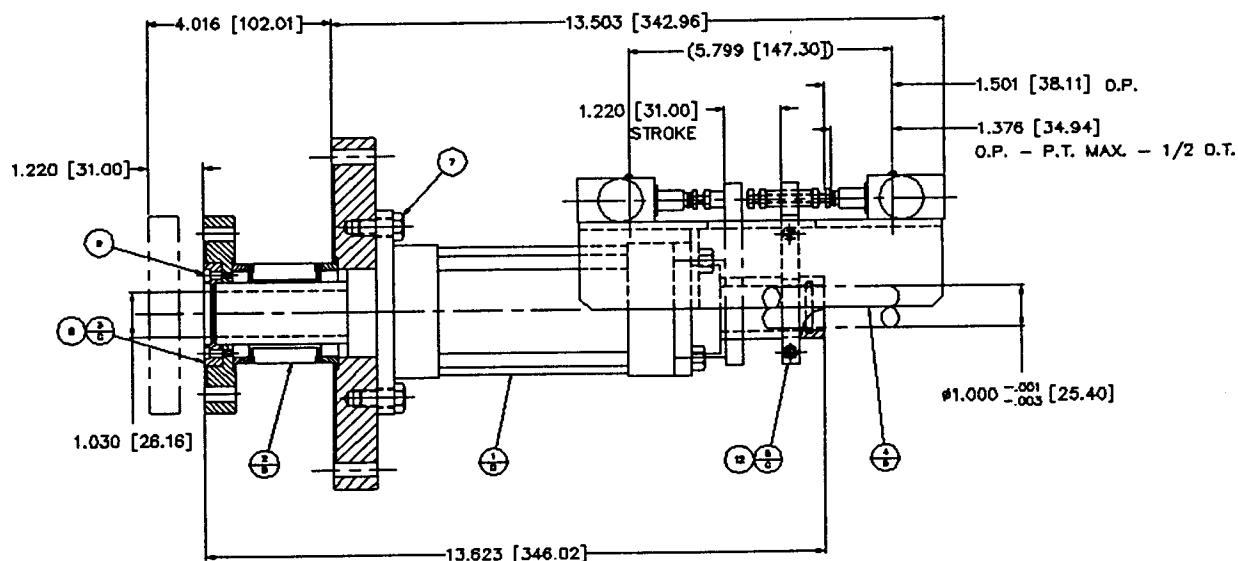
- Light load actuator
- For use with APS monochromatic beam shutters and BM white beam shutters

A typical application for the light load pneumatic actuators is to drive APS monochromatic beam shutters and BM white beam shutters.

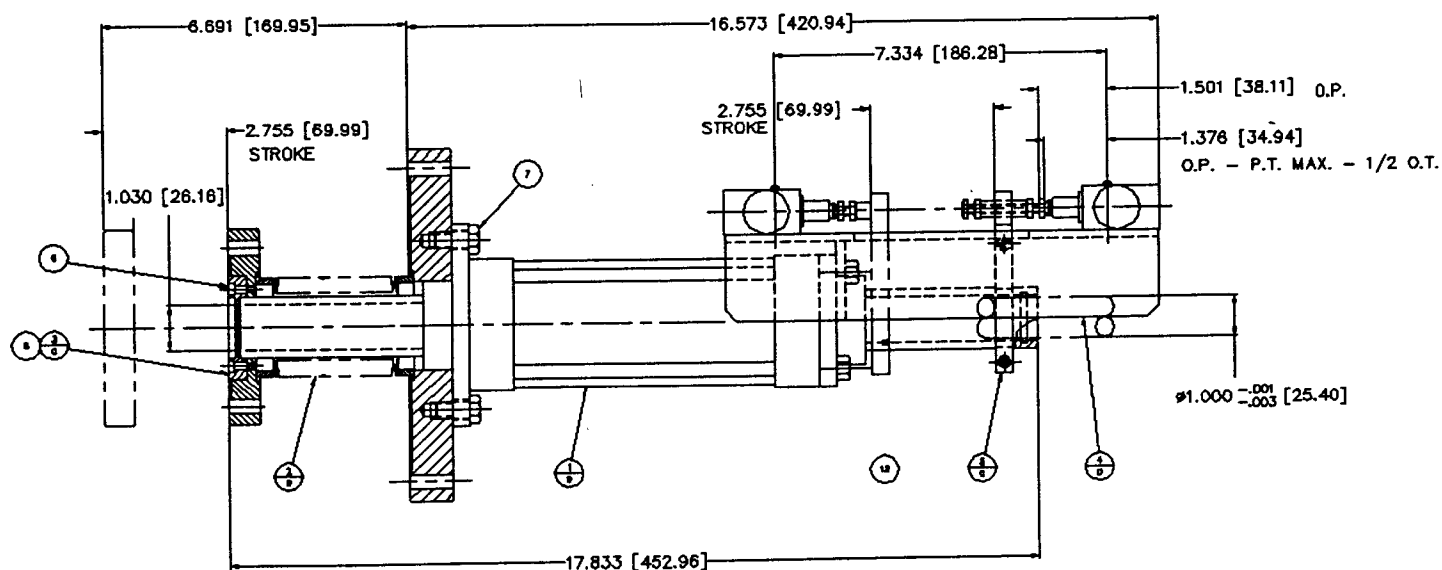
Specifications:

- Stroke:	31 mm \pm 0.25 mm & 70 mm \pm 0.25 mm
- Motion repeatability:	0.1 mm
- Total axial load	90 kg
- Vacuum load:	17 kg
- Maximum useful axial load:	30 kg
- Actuator flange O. D.:	8 inch
- Feedthrough flange:	4.5 inch
- Maximum feedthrough diameter:	25 mm
- Bore size:	2.5 inch
- Rod size:	1.375 inch
- Bellows O. D.:	56 mm
- Bellows I. D.:	35.6 mm
- Redundant limit switches in each end position:	Micro switch BZZRQ2X-A2
- Pneumatic power supply:	60 - 100 psi
- Maximum closing time:	1 sec
- Pneumatic damping:	in each end position
- Solenoid:	24 V DC (power failure safe design)
- Life time:	500 k cycles
- Vacuum:	UHV compatible

A3-81, 31mm STROKE



A3-83, 70 mm STROKE



APS A3 Light Load Pneumatic Linear Actuators

Figure 57 A3S1.DWG 02-22-1993

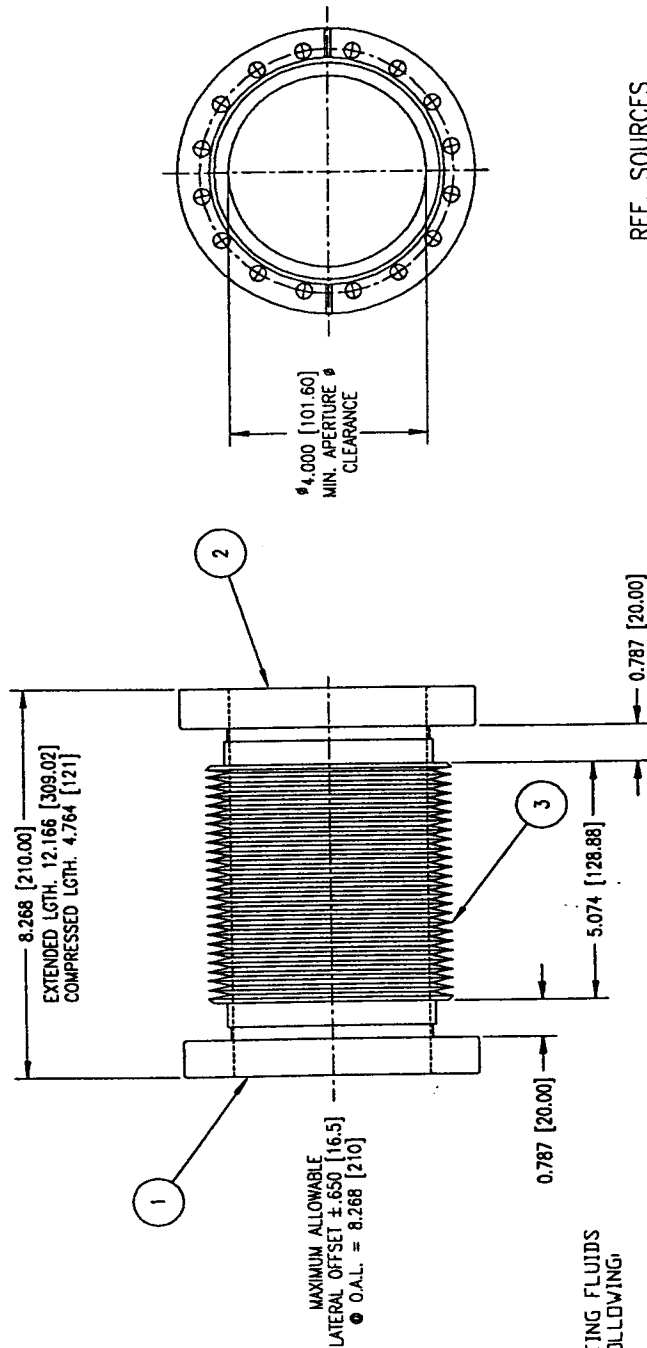
13. Bellows

13.1. Welded bellows

13.2. Formed bellows

Design Status

The design work for welded bellows is complete, while that for formed bellows will be completed before May 1993. With the completion of the designs, these bellows can be procured from vendors. They will also be available from the APS stockroom.



REF. SOURCES

- STANDARD BELLOWS CO.
375 TUNPIKE AVE.
WINDSOR LOCKS, CONN. 06096
- MDC VACUUM PRODUCTS CORP.
23842 CABOT BLVD.
HAYWARD, CA. 94545-1651

NOTES:

- WHEN MACHINING VACUUM PARTS, USE OF SILICONE AND SULPHUR-BASED CUTTING FLUIDS IS PROHIBITED. USE ONE OF THE FOLLOWING:
A) CIMCOOL 5 STAR 49
B) TRIM SOL
- ALL WELDS JOINING BELLOWS AND FLANGES ARE TO BE INTERNAL
- BELLOWS ASSEMBLY SHALL BE LEAK TESTED USING A MASS SPECTROMETER WITH MINIMUM SENSITIVITY FOR HELIUM OF 2 X 10⁻¹⁰ STANDARD CC/SEC PER LEAK METER DIVISION, SUCH AS ALCATEL SAM-110TCL
Du PONT CEC 24-1208
VARIAN MS-9, MS-90 OR MS-18
CALIBRATION OF THE LEAK DETECTOR SENSITIVITY SHALL BE PERFORMED JUST PRIOR TO TRESTING.
FINAL TEST WILL CONSIST OF SURROUNDING THE ASSEMBLY (BAGGING) WITH HELIUM. THE ASSEMBLY WILL BE REJECTED IF A 2% DEFLECTION ON THE MOST SENSITIVE RANGE OF THE LEAK DETECTOR IS SENSED WITHIN 1 MIN.
4. KEEP THE PART CLEAN, AND WRAP FOR UHV PACKING WITH ALUMINUM FOIL.
5. DIMENSIONS IN [] ARE MILLIMETERS

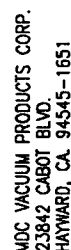
Figure 58

3		STD. BELLOWS CAT. #497 - 400 - 7 - EE	WITH EXTENDED ENDS	1
2		MDC'S CAT. #100026 16" CF. ROTATABLE FLANGE		1
1		MDC'S CAT. #110026 16" CF. NONROTATABLE FLANGE		1
ITEM	DWG/PART NUMBER	NOMENCLATURE OR DESCRIPTION		MATERIAL / SPEC
PARTS LIST				
UNLESS OTHERWISE SPECIFIED: ALL DIMENSIONS ARE IN INCHES				
TOLERANCES				
DECIMALS				
FRACTIONS				
SURFACE FINISHES				
REMOVE ALL BURRS AND BREAK SHARP EDGES TO MAX SURFACE TEXTURE TO BE IN ACCORDANCE WITH LATEST AND BELL SURFACE FINISHES TO BE IN ACCORDANCE WITH LATEST AND BELL ACCORDANCE WITH LATEST AND BELL				
DESIGNED BY MUSCIA				
CHECKED BY D. SHU				
DATE 7/17/83				
PROJECT NO.				
APPROVED/RELEASED				
SCALE HALF				
SHEET 1 of 1				
DRAWING NUMBER 4105090702-820000-00				

ARGONNE NATIONAL LABORATORY

ADVANCED PHOTON SOURCE
V2 - 82 WELDED BELLOWS ASSY.
6" - 6" CF. 4" I.D. X 210mm

A09231		LOG NUMBER
DESIGNED BY	MUSCIA	DATE
CHECKED BY	D. SHU	DATE
SEE PARTS LIST		
DO NOT SCALE DRAWING		

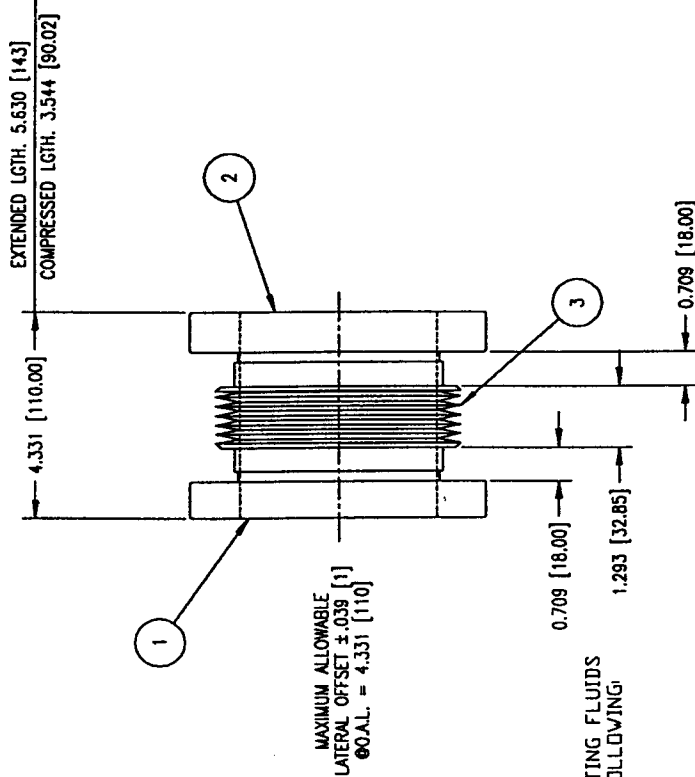


UNLESS OTHERWISE SPECIFIED: ALL DIMENSIONS ARE IN INCHES TOLERANCES	DECIMALS		FRACTIONS		SURFACE ROUGHNESS $\sqrt{32}$	DESIGNER MUSCIA	DATE 2/1/81	CHECKED BY MUSCIA	DATE 2/1/81	CHIEF DESIGN ENGINEER D. SHU	PROJECT MGR T. M. KERRY	APPROVED/RELEASED	SCALE 1/2"=1'	SIZE HALF SHEET 1 of 1	DRAWING NUMBER 4105090702-830000-00
	.X 1/16 1/8 1/4 1/2 3/4 1	.001 1/32 1/16 1/8 1/4 1/2 3/4 1													
PARTS LIST															
SEE PARTS LIST															
MATERIAL D. SHU															
REMOVE ALL BURRS AND BREAK SHARP EDGES AT MAX. SURFACE TEXTURE TO BE IN ACCORDANCE WITH LATEST AND B-41 DIMENSIONS & TOLERANCING IN ACCORDANCE WITH LATEST AND T-15															
THIS DRAWING IS THE PROPERTY OF ARGONNE NATIONAL LABORATORY															
ADVANCED PHOTON SOURCE V2 - 83 WELDED BELLOW ASSY. 6" - 6" CF. 4" I.D. X 175mm															
DATE 2/2/81															
DATE 2/2/81															

[illegible]

Figure 59

1. WHEN MACHINING VACUUM PARTS, USE OF SILICONE AND SULPHUR-BASED CUTTING FLUIDS IS PROHIBITED. USE ONE OF THE FOLLOWING:
A) CIMCOOL 5 STAR 49
B) TRIM SOL
2. ALL WELDS JOINING BELLOWS AND FLANGES ARE TO BE INTERNAL
3. BELLOWS ASSEMBLY SHALL BE LEAK TESTED USING A MASS SPECTROMETER WITH MINIMUM SENSITIVITY FOR HELIUM OF 2×10^{-10} STANDARD CC/SEC PER LEAK METER DIVISION, SUCH AS
ALCATEL SAM-110TCL
Du PONT CEC 24-120B
VARIAN MS-9, MS-90 OR MS-18
- CALIBRATION OF THE LEAK DETECTOR SENSITIVITY SHALL BE PERFORMED JUST PRIOR TO TRESTING.
- FINAL TEST WILL CONSIST OF SURROUNDING THE ASSEMBLY (BAGGING) WITH HELIUM. THE ASSEMBLY WILL BE REJECTED IF A 2% DEFLECTION ON THE MOST SENSITIVE RANGE OF THE LEAK DETECTOR IS SENSED WITHIN 1 MIN.
4. KEEP THE PART CLEAN, AND WRAP FOR UHV PACKING WITH ALUMINUM FOIL.
5. DIMENSIONS IN [] ARE MILLIMETERS



NOTES:

1. WHEN MACHINING VACUUM PARTS, USE OF SILICONE AND SULPHUR-BASED CUTTING FLUIDS IS PROHIBITED. USE ONE OF THE FOLLOWING:
A) CIMCOOL 5 STAR 49
B) TRIM SOL

2. ALL WELDS JOINING BELLOWS AND FLANGES ARE TO BE INTERNAL

3. BELLWAS ASSEMBLY SHALL BE LEAK TESTED USING A MASS SPECTROMETER WITH MINIMUM SENSITIVITY FOR HELIUM OF 2 X 10⁻¹⁰ STANDARD CC/SEC PER LEAK METER DIVISION, SUCH AS
ALCATEL SAM-110TCL
DU PONT CEC 24-120B
VARIAN MS-9, MS-90 OR MS-18

CALIBRATION OF THE LEAK DETECTOR SENSITIVITY SHALL BE PERFORMED JUST PRIOR TO TRESTING.

FINAL TEST WILL CONSIST OF SURROUNDING THE ASSEMBLY (BAGGING) WITH HELIUM. THE ASSEMBLY WILL BE REJECTED IF A 2% DEFLECTION ON THE MOST SENSITIVE RANGE OF THE LEAK DETECTOR IS SENSED WITHIN 1 MIN.

4. KEEP THE PART CLEAN, AND WRAP FOR UVH PACKING WITH ALUMINUM FOIL.

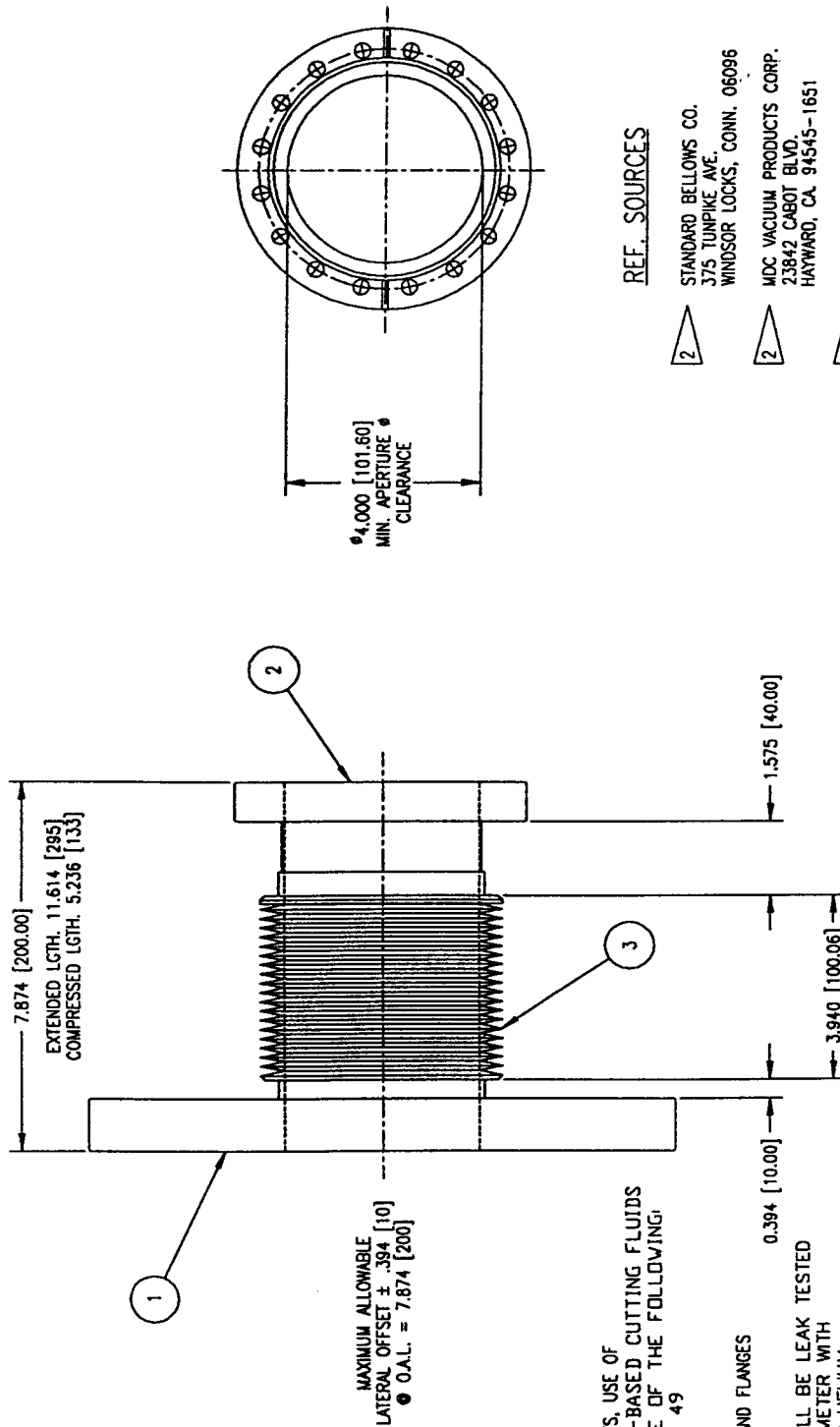
5. DIMENSIONS IN [] ARE MILLIMETERS

REF. SOURCES

1. STANDARD BELLWOS CO.
375 TUNPIKE AVE.
WINDSOR LOCKS, CONN. 06096
2. MDC VACUUM PRODUCTS CORP.
23842 CABOT BLVD.
HAYWARD, CA. 94545-1651

3		ST'D. BELLWOS CAT. #497 - 400 - 2 - EE		WITH EXTENDED ENDS		1	
2		MDC'S CAT. #100026		6" CF. ROTATABLE FLANGE		1	
1		MDC'S CAT. #110026		6" CF. NONROTATABLE FLANGE		1	
ITEM		QTY/PART NUMBER		NOMENCLATURE OR DESCRIPTION		MATERIAL / SPEC	
PARTS LIST							
UNLESS OTHERWISE SPECIFIED: ALL DIMENSIONS ARE IN INCHES				THIS DRAWING IS THE PROPERTY OF			
TOLERANCES				ARGONNE NATIONAL LABORATORY			
DECIMALS ANGULAR				DATE			
X .03 (.7500) 4.31				D. SHU			
XX .01 (.25) 4.25				DATE			
XXX .006 (.157)				1/1/73			
SURFACE ROUGHNESS 125				T. M. ZACHARY			
REWORK ALL DIMS AND				PROJECT MGR.			
BREAK SHARP EDGES, ALL SHAL				APPROVED/RELEASED			
SURFACE TEXTURE TO BE IN				DATE			
ACCORDANCE WITH LATEST AND 84-1				1/1/73			
ENCLOSING & TELEPHONS IN				MATERIAL			
ACCORDANCE WITH LATEST AND THIS				D. SHU			
DO NOT SCALE DRAWING				SEE PARTS LIST			
SYN				CHANGE DESCRIPTION			
BY				CHKD			
DATE				DATE			
REVISIONS				SCALE			
SIZE				HALF			
SHEET				1 of 1			
DRAWING NUMBER				4105090702-840000-00			

Figure 60



NOTES:

1. WHEN MACHINING VACUUM PARTS, USE OF SILICONE AND SULPHUR-BASED CUTTING FLUIDS IS PROHIBITED. USE ONE OF THE FOLLOWING:
A) CIMCOOL 5 STAR 49
B) TRIM SOL

2. ALL WELDS JOINING BELLOWS AND FLANGES ARE TO BE INTERNAL

3. BELLOWS ASSEMBLY SHALL BE LEAK TESTED USING A MASS SPECTROMETER WITH MINIMUM SENSITIVITY FOR HELIUM OF 2 X 10⁻¹⁰ STANDARD CC/SEC PER LEAK METER DIVISION, SUCH AS

ALCATEL SAM-110TCL
Du PONT CEC 24-120B
VARIAN MS-9, MS-90 OR MS-18
CALIBRATION OF THE LEAK DETECTOR SENSITIVITY SHALL BE PERFORMED JUST PRIOR TO TRESTING.

FINAL TEST WILL CONSIST OF SURROUNDING THE ASSEMBLY (BAGGING) WITH HELIUM. THE ASSEMBLY WILL BE REJECTED IF A 2% DEFLECTION ON THE MOST SENSITIVE RANGE OF THE LEAK DETECTOR IS SENSED WITHIN 1 MIN.

4. KEEP THE PART CLEAN, AND WRAP FOR UHV PACKING WITH ALUMINUM FOIL.

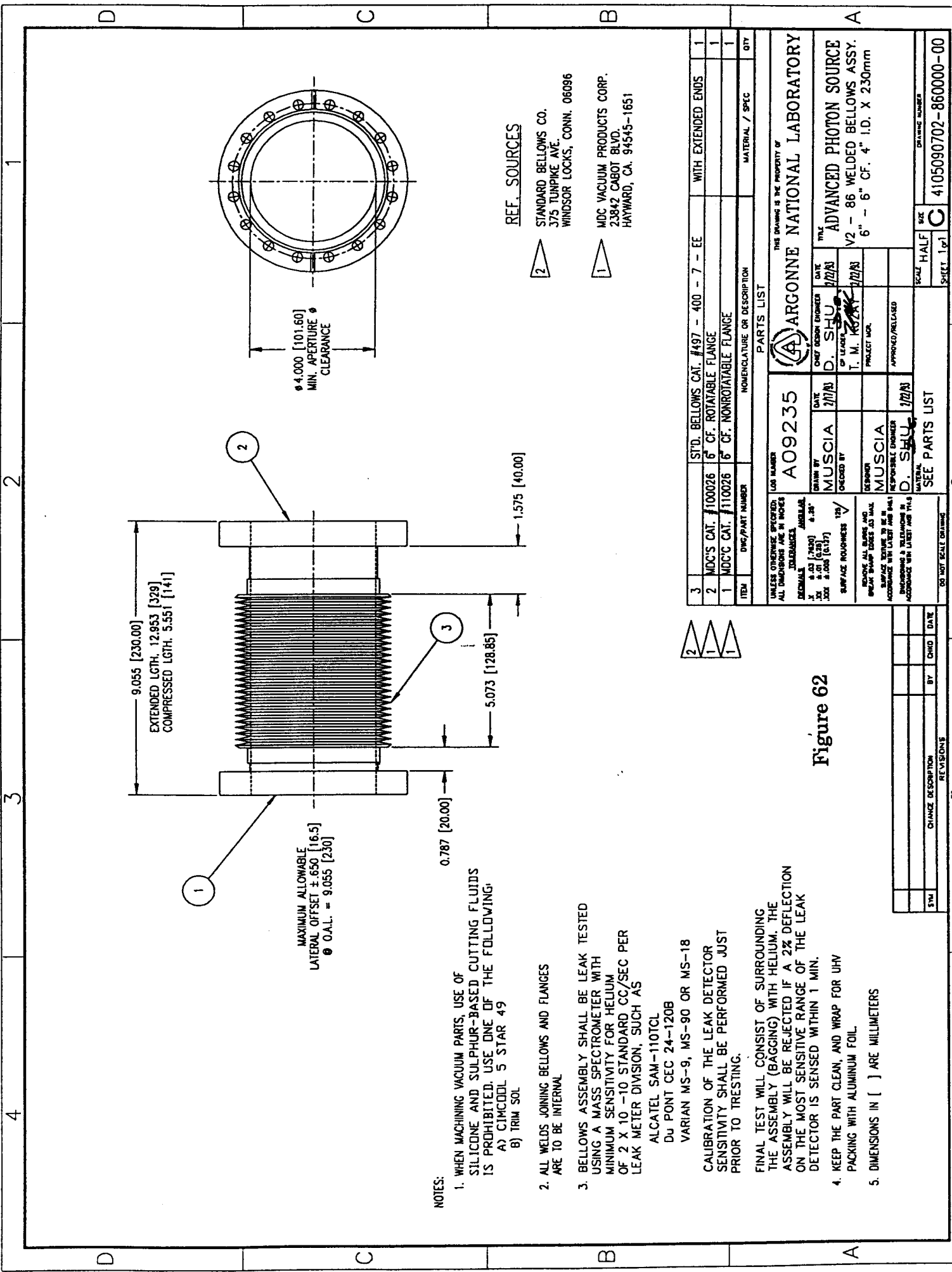
5. DIMENSIONS IN [] ARE MILLIMETERS

REF. SOURCES

- 2 STANDARD BELLOWS CO.
375 TUNPIKE AVE.
WINDSOR LOCKS, CONN. 06096
- 2 MDC VACUUM PRODUCTS CORP.
23842 CABOT BLVD.
HAYWARD, CA 94545-1651
- 1 NOR-CAL PRODUCTS, INC.
1967 S. OREGON ST.
P.O. BOX 518
YREKA, CA 96097

3	STD. BELLOWS CAT. #497 - 400 - 6 - EE	WITH EXTENDED ENDS	1
2	MDC'S CAT. #100028 6" CF. ROTATABLE FLANGE		1
1	N.C. #1200-000N 12" CF. NONROTATABLE FLANGE 4" I.D.		1
ITEM	QTY/PART NUMBER	NOMENCLATURE OR DESCRIPTION	MATERIAL / SPEC

UNLESS OTHERWISE SPECIFIED: ALL DIMENSIONS ARE IN INCHES			
DECIMALS	FRACTIONS	TOLERANCES	FINISHES
1/16	1/32	±.005	125
1/32	1/64	±.003	125
1/64	1/128	±.002	125
1/128	1/256	±.001	125
1/256	1/512	±.0005	125
1/512	1/1024	±.0002	125
1/1024	1/2048	±.0001	125
1/2048	1/4096	±.00005	125
1/4096	1/8192	±.00002	125
1/8192	1/16384	±.00001	125
1/16384	1/32768	±.000005	125
1/32768	1/65536	±.000002	125
1/65536	1/131072	±.000001	125
1/131072	1/262144	±.0000005	125
1/262144	1/524288	±.0000002	125
1/524288	1/1048576	±.0000001	125
1/1048576	1/2097152	±.00000005	125
1/2097152	1/4194304	±.00000002	125
1/4194304	1/8388608	±.00000001	125
1/8388608	1/16777216	±.000000005	125
1/16777216	1/33554432	±.000000002	125
1/33554432	1/67108864	±.000000001	125
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1/134217728	1/268435456	±.0000000002	125
1/268435456	1/536870912	±.0000000001	125
1/536870912	1/1073741824	±.00000000005	125
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1/2147483648	1/4294967296	±.00000000001	125
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1/8589934592	1/17179869184	±.000000000002	125
1/17179869184	1/34359738368	±.000000000001	125
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1/2199023255552	1/4398046511104	±.000000000000005	125
1/4398046511104	1/8796093022208	±.000000000000002	125
1/8796093022208	1/17592186044416	±.000000000000001	125
1/17592186044416	1/35184372088832	±.0000000000000005	125
1/35184372088832	1/70368744177664	±.0000000000000002	125
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1/1125899906842624	1/2251799813685248	±.000000000000000005	125
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1/4503599627370496	1/9007199254740992	±.000000000000000001	125
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NOTES:

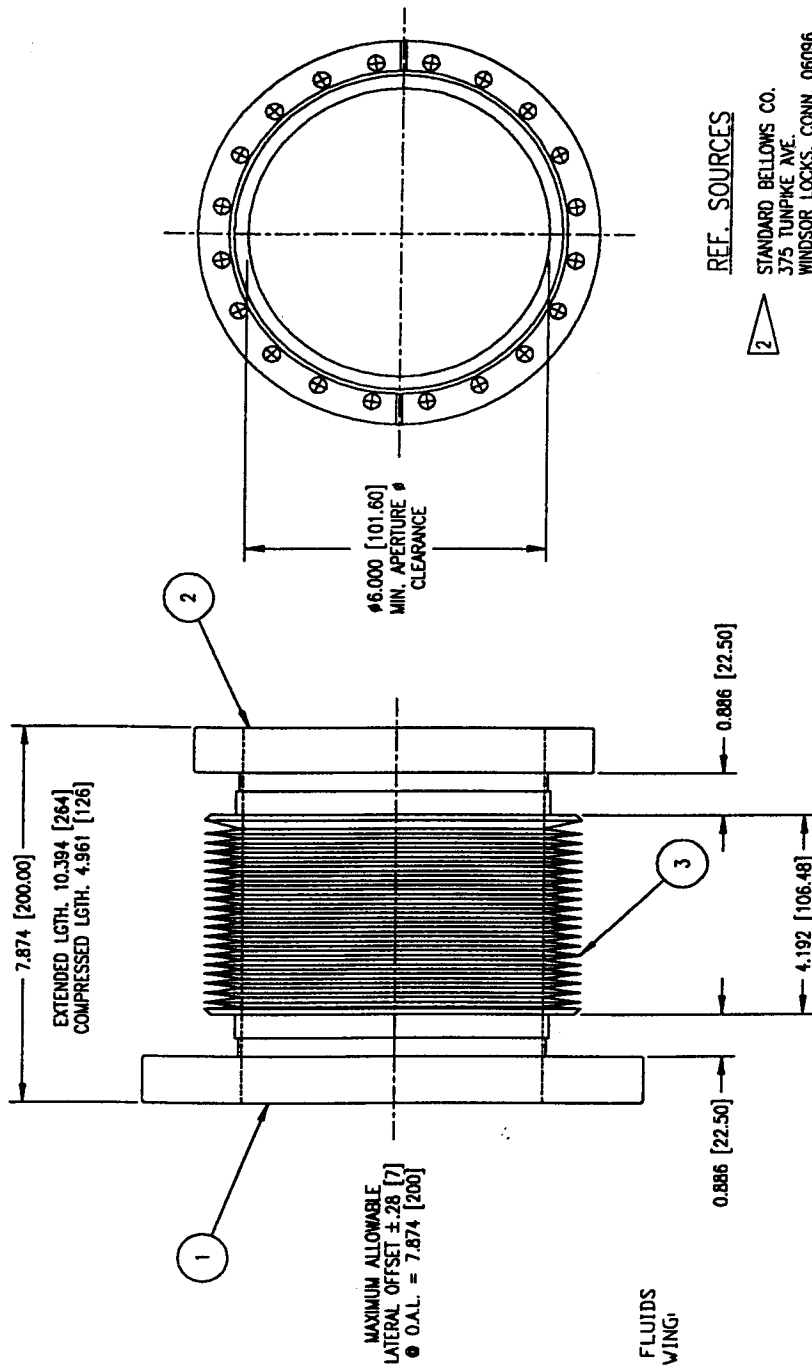
1. WHEN MACHINING VACUUM PARTS, USE OF SILICONE AND SULPHUR-BASED CUTTING FLUIDS IS PROHIBITED. USE ONE OF THE FOLLOWING:
A) CIMCOOL 5 STAR 49
B) TRIM SOL
2. ALL WELDS JOINING BELLOWS AND FLANGES ARE TO BE INTERNAL
3. BELLOWS ASSEMBLY SHALL BE LEAK TESTED USING A MASS SPECTROMETER WITH MINIMUM SENSITIVITY FOR HELIUM OF 2 X 10⁻¹⁰ STANDARD CC/SEC PER LEAK METER DIVISION, SUCH AS ALCATEL SAM-110TCL
DU PONT CEC 24-120B
VARIAN MS-9, MS-90 OR MS-18
CALIBRATION OF THE LEAK DETECTOR SENSITIVITY SHALL BE PERFORMED JUST PRIOR TO TESTING.
4. FINAL TEST WILL CONSIST OF SURROUNDING THE ASSEMBLY (BAGGING) WITH HELIUM. THE ASSEMBLY WILL BE REJECTED IF A 2% DEFLECTION ON THE MOST SENSITIVE RANGE OF THE LEAK DETECTOR IS SENSED WITHIN 1 MIN.
5. KEEP THE PART CLEAN, AND WRAP FOR UHV PACKING WITH ALUMINUM FOIL.
6. DIMENSIONS IN [] ARE MILLIMETERS

REF. SOURCES

- 2 STANDARD BELLOWS CO.
375 TUNPIKE AVE.
WINDSOR LOCKS, CONN. 06096
- 1 MDC VACUUM PRODUCTS CORP.
23842 CABOT BLVD.
HAYWARD, CA. 94545-1651

Figure 62

UNLESS OTHERWISE SPECIFIED: ALL DIMENSIONS ARE IN INCHES			THIS DRAWING IS THE PROPERTY OF		
ITEM	DWG/PART NUMBER	NOMENCLATURE OR DESCRIPTION	LOG NUMBER	DATE	BY
3		STD. BELLOWS CAT. #497 - 400 - 7 - EE	A09235	DATE	BY
2	MDC'S CAT. #100026	6" CF. ROTATABLE FLANGE		DATE	BY
1	MDC'S CAT. #110026	6" CF. NONROTATABLE FLANGE		DATE	BY
PARTS LIST			ARGONNE NATIONAL LABORATORY		
ITEM	DWG/PART NUMBER	NOMENCLATURE OR DESCRIPTION	LOG NUMBER	DATE	BY
1		ADVANCED PHOTON SOURCE	A09235	DATE	BY
2		V2 - 86 WELDED BELLOWS ASSY.		DATE	BY
3		6" - 8" CF. 4" I.D. X 230mm		DATE	BY
PARTS LIST			ARGONNE NATIONAL LABORATORY		
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3		6" - 8" CF. 4" I.D. X 230mm		DATE	BY
PARTS LIST			ARGONNE NATIONAL LABORATORY		
ITEM	DWG/PART NUMBER	NOMENCLATURE OR DESCRIPTION	LOG NUMBER	DATE	BY
1		ADVANCED PHOTON SOURCE	A09235	DATE	BY
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PARTS LIST			ARGONNE NATIONAL LABOR		



REF. SOURCES

- 2 STANDARD BELLOWS CO.
375 TUNPKE AVE.
WINDSOR LOCKS, CONN. 06096
- 1 MDC VACUUM PRODUCTS CORP.
23842 CABOT BLVD.
HAYWARD, CA. 94545-1651

NOTES:

1. WHEN MACHINING VACUUM PARTS, USE OF SILICONE AND SULPHUR-BASED CUTTING FLUIDS IS PROHIBITED. USE ONE OF THE FOLLOWING:
A) CIMCOOL 5 STAR 49
B) TRIM SOL
2. ALL WELDS JOINING BELLOWS AND FLANGES ARE TO BE INTERNAL
3. BELLOWS ASSEMBLY SHALL BE LEAK TESTED USING A MASS SPECTROMETER WITH MINIMUM SENSITIVITY FOR HELIUM OF 2 X 10⁻¹⁰ STANDARD CC/SEC PER LEAK METER DIVISION, SUCH AS ALCATEL SAM-110TCL
DU PONT CEC 24-120B
VARIAN MS-9, MS-90 OR MS-18
CALIBRATION OF THE LEAK DETECTOR SENSITIVITY SHALL BE PERFORMED JUST PRIOR TO TRESTING.
FINAL TEST WILL CONSIST OF SURROUNDING THE ASSEMBLY (BAGGING) WITH HELIUM. THE ASSEMBLY WILL BE REJECTED IF A 2% DEFLECTION ON THE MOST SENSITIVE RANGE OF THE LEAK DETECTOR IS SENSED WITHIN 1 MIN.
4. KEEP THE PART CLEAN, AND WRAP FOR UHV PACKING WITH ALUMINUM FOIL.
5. DIMENSIONS IN [] ARE MILLIMETERS

Figure 63



ITEM	QTY	DESCRIPTION	MATERIAL / SPEC
3	1	STD. BELLOWS CAT. #750 - 600 - 5 - EE	WITH EXTENDED ENDS
2	1	MDC'S CAT. #100031	8" CF. ROTATABLE FLANGE
1	1	MDC'S CAT. #110033	10" CF. NONROTATABLE FLANGE
1	1	ITEM	

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UNLESS OTHERWISE SPECIFIED	ALL DIMENSIONS ARE IN INCHES	DECIMALS	FRACTIONS	ANGULAR	SURFACE FINISH	WELDING	THREADS	KEYWAYS	SPACINGS	STRAIGHTENING	REWORK	REVISIONS	DATE
		0.001	1/32	0.001	0.001	0.001	0.001	0.001	0.001	0.001	0.001	0.001	0.001

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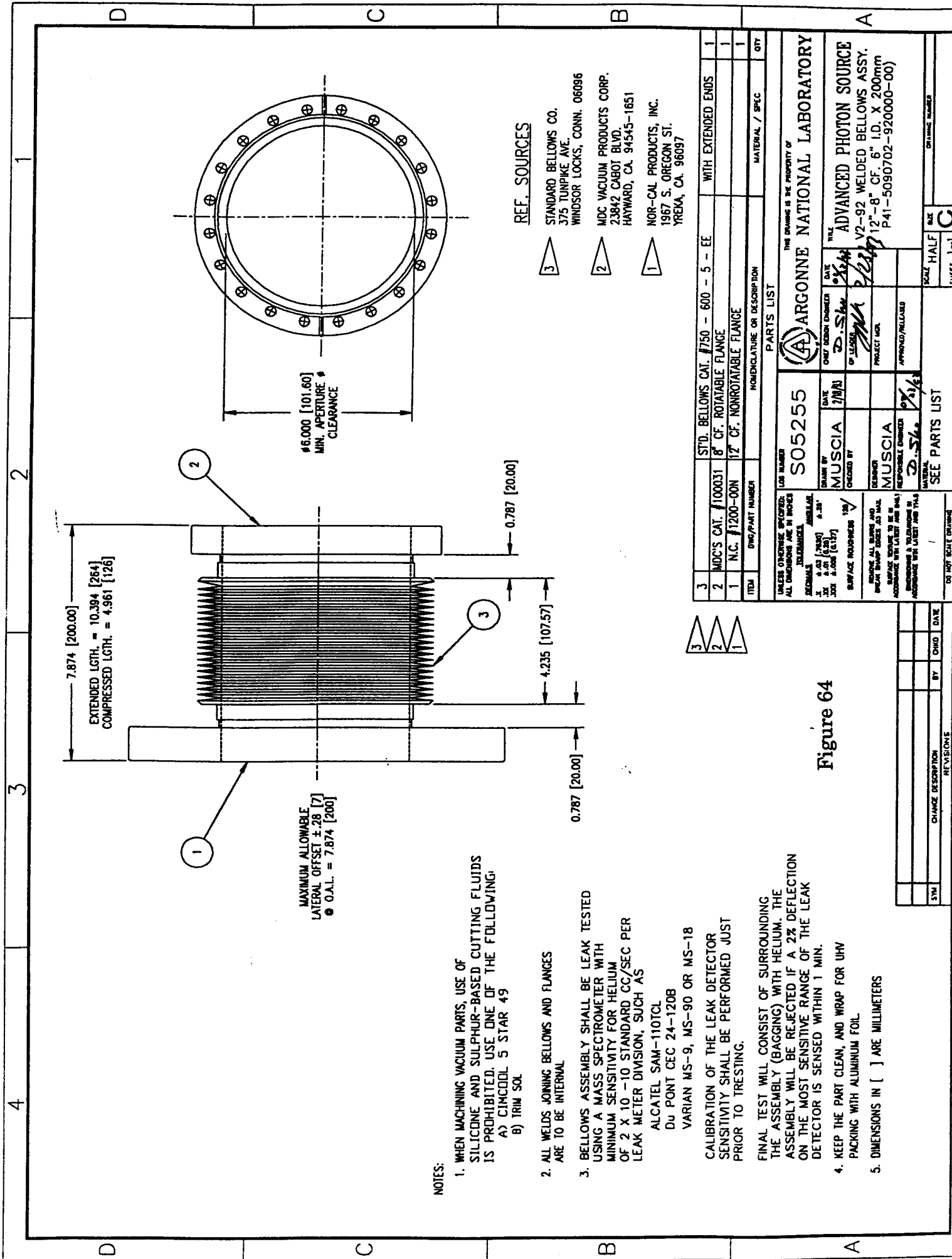
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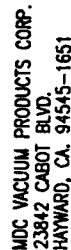
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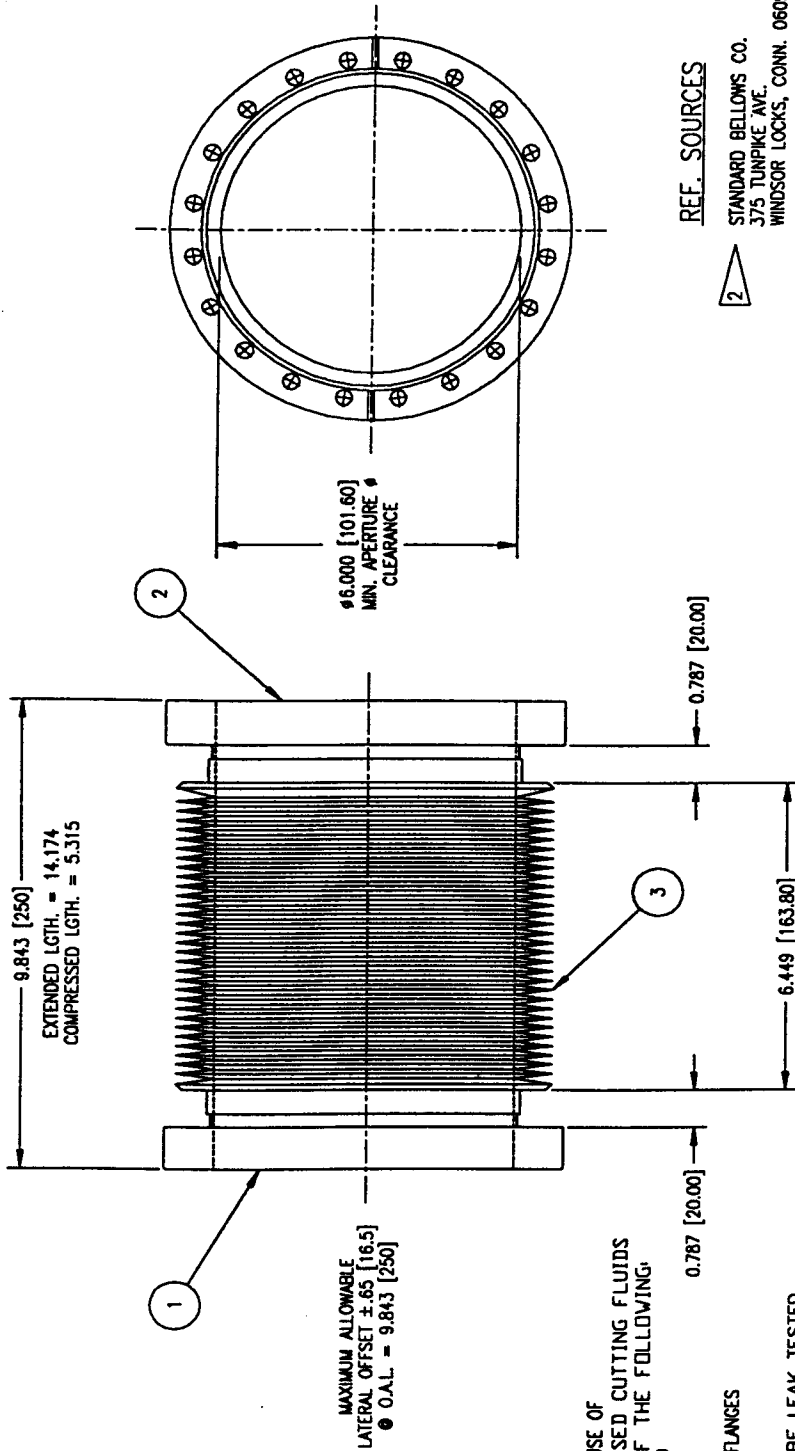
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375 TUNPIKE AVE.
WINDSOR LOCKS, CONN. 06096

MDC VACUUM PRODUCTS CORP.
23842 CABOT BLVD.
HAYWARD, CA. 94545-1651

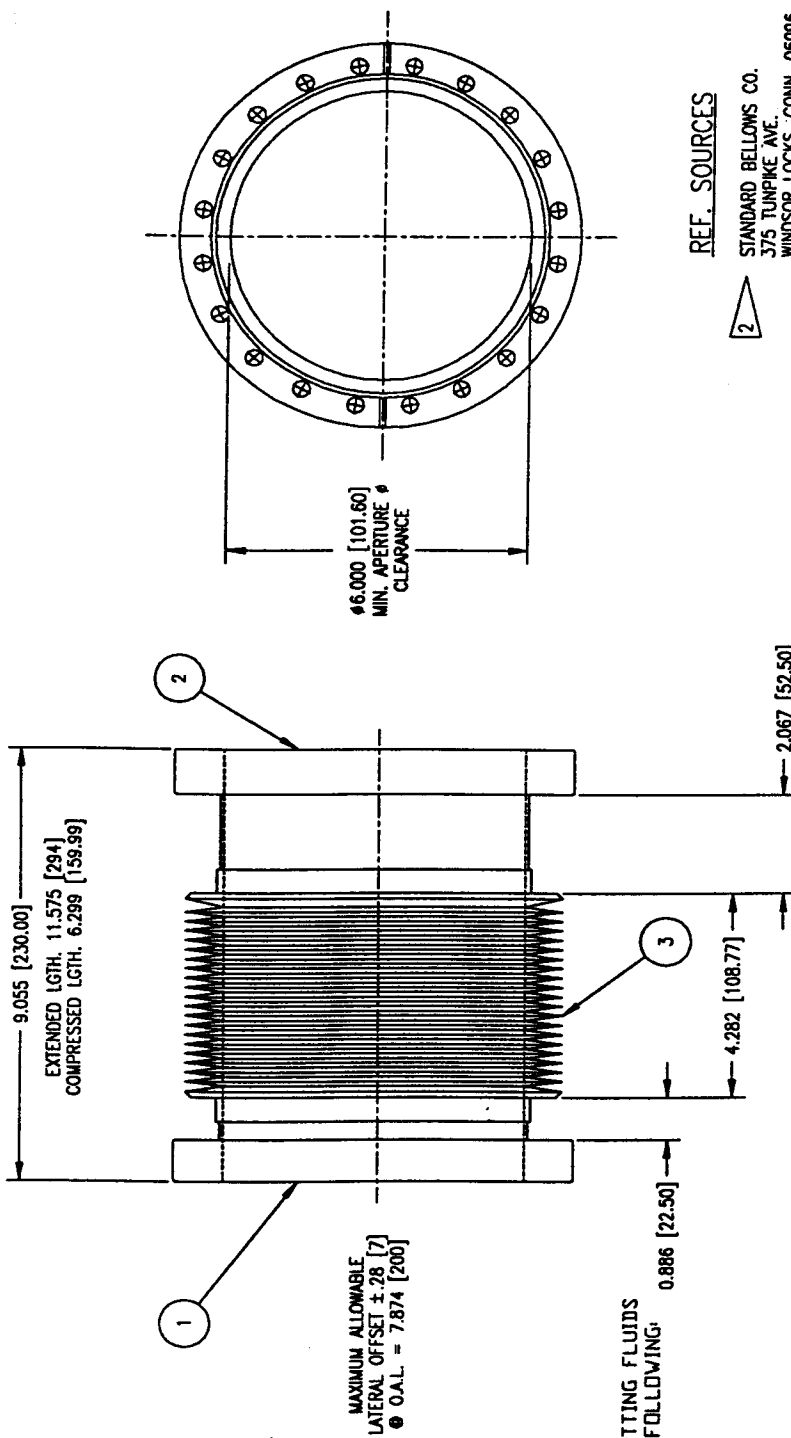


ITEM	DWG/PART NUMBER	NOMENCLATURE OR DESCRIPTION	MATERIAL / SPEC	QTY
3	MDC'S CAT. #100031	STD. BELLOWS CAT. #750 - 600 - 8 - EE	WITH EXTENDED ENDS	1
2	MDC'S CAT. #110031	8" CF. ROTATABLE FLANGE		1
1	MDC'S CAT. #110031	8" CF. NONROTATABLE FLANGE		1

PARTS LIST

UNLESS OTHERWISE SPECIFIED, ALL DIMENSIONS ARE IN INCHES		LOG NUMBER		S05257		THE DRAWING IS THE PROPERTY OF	
TOLERANCES		DRAWN BY		MUSCIA		DATE	
FRACTIONS		CHECKED BY		MUSCIA		DATE	
DECIMALS		APPROVED BY		MUSCIA		DATE	
ANGLES		PROJECT NO.		0.500		DATE	
HOLE DIA.		APPROVED/RELEASED		0.500		DATE	
TAP DIA.		SEE PARTS LIST		0.500		DATE	
THREADS		SCALE		HALF		DATE	
SURFACE FINISHES		SHEET		1 of 1		DATE	

Figure 66



REF. SOURCES

- STANDARD BELLOWS CO.
375 TUNPIKE AVE.
WINDSOR LOCKS, CONN. 06096
- MDC VACUUM PRODUCTS CORP.
23842 CABOT BLVD.
HAYWARD, CA. 94545-1651

NOTES:

- WHEN MACHINING VACUUM PARTS, USE OF SILICONE AND SULPHUR-BASED CUTTING FLUIDS IS PROHIBITED. USE ONE OF THE FOLLOWING:
A) CIMCOOL 5 STAR 49
B) TRIM SOL
- ALL WELDS JOINING BELLOWS AND FLANGES ARE TO BE INTERNAL
- BELLOWS ASSEMBLY SHALL BE LEAK TESTED USING A MASS SPECTROMETER WITH MINIMUM SENSITIVITY FOR HELIUM OF 2 X 10⁻¹⁰ STANDARD CC/SEC PER LEAK METER DIVISION, SUCH AS
ALCATEL SAM-110TCL
DU PONT CEC 24-120B
VARIAN MS-9, MS-90 OR MS-18
CALIBRATION OF THE LEAK DETECTOR SENSITIVITY SHALL BE PERFORMED JUST PRIOR TO TRESTING.

FINAL TEST WILL CONSIST OF SURROUNDING THE ASSEMBLY (BAGGING) WITH HELIUM. THE ASSEMBLY WILL BE REJECTED IF A 2% DEFLECTION ON THE MOST SENSITIVE RANGE OF THE LEAK DETECTOR IS SENSED WITHIN 1 MIN.

4. KEEP THE PART CLEAN, AND WRAP FOR UHV PACKING WITH ALUMINUM FOIL

5. DIMENSIONS IN [] ARE MILLIMETERS

Figure 67

3		STD. BELLOWS CAT. #750 - 600 - 5 - EE		WITH EXTENDED ENDS		1
2		MDC'S CAT. #100031		8" CF. ROTATABLE FLANGE		1
1		MDC'S CAT. #110031		8" CF. NONROTATABLE FLANGE		1
ITEM	ENG/PART NUMBER	NOMENCLATURE OR DESCRIPTION			MATERIAL / SPEC	QTY
PARTS LIST						
UNLESS OTHERWISE SPECIFIED, ALL DIMENSIONS ARE IN INCHES						
TOLERANCES						
DECIMALS	FRACTIONS	ANGLES				
.X	4/100 (.004)	1/16"				
.XX	1/50 (.02)	1/32"				
.XXX	1/100 (.01)	1/64"				
SURFACE FINISHES						
125						
REMOVE ALL BURRS AND						
SHARP EDGES TO BE RADIUS						
SURFACE TOLERANCE TO BE IN						
CONFORMANCE WITH LATEST AND BEST						
PRACTICES & TOLERANCES IN						
CONFORMANCE WITH LATEST AND BEST						
DO NOT SCALE DRAWING						
LOT NUMBER		S05256		THIS DRAWING IS THE PROPERTY OF		
DRAWN BY		MUSCIA		ARGONNE NATIONAL LABORATORY		
CHECKED BY		MUSCIA		DATE		
DESIGNED BY		MUSCIA		DATE		
APPROVED/RELEASED		DATE		DATE		
MATERIAL		SEE PARTS LIST		DATE		
SCALE		HALF		DATE		
SHEET		191		DATE		